Introduction Representations for systems with independents components Representations for systems with dependent components References

> Mixture representations based on signatures for coherent systems with heterogeneous components

J. Navarro^{a1}, F. J. Samaniego^b and N. Balakrishnan^c ^{a,}Universidad de Murcia, Spain, ^bUniversity of California, Davis, USA, ^cMcMaster University, Canada.



¹Supported by Ministerio de Ciencia y Tecnología under grant MTM2009-08311 and Fundación Séneca under grant 0.8627 ∯1/08: → < ≥ → ≥ ∽ ○

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1, \ldots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X_1,\ldots,X_n IID.
- X_{1:n},..., X_{n:n} the associated OS.
- X_{k:n} represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1, \ldots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X_1,\ldots,X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- X_{k:n} represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1,\ldots,X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X_1, \ldots, X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- X_{k:n} represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1,\ldots,X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X_1, \ldots, X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- X_{k:n} represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1,\ldots,X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X_1, \ldots, X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- X_{k:n} represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1,\ldots,X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X₁,..., X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- $X_{k:n}$ represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

・ロト ・ 一下・ ・ ヨト ・ ヨト

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Coherent systems and order statistics

- X_1, \ldots, X_n (positive) random variables.
- $\overline{F}_i(t) = \Pr(X_i > t)$ reliability (survival) function.
- X_1,\ldots,X_n exchangeable (EXC), i.e., for any σ

$$(X_1,\ldots,X_n) =_{ST} (X_{\sigma(1)},\ldots,X_{\sigma(n)}).$$

- X₁,..., X_n IID.
- $X_{1:n}, \ldots, X_{n:n}$ the associated OS.
- $X_{k:n}$ represents the lifetime of the k-out-of-n:F system.
- $T = \phi(X_1, \ldots, X_n)$ lifetime of a coherent system.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixture representations

• Samaniego (IEEE TR, 1985), IID and \overline{F}_1 continuous, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \overline{F}_{i:n}(t), \qquad (1.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \ldots, p_n)$ is the signature of the system.
- p_i does not depend on \overline{F}_1 and

$$p_i = \frac{\left| \{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)} \} \right|}{n!}$$

- Navarro and Rychlik (JMVA, 2007), (1.1) holds for EXC r.v. with absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhathacharya (NRL, 2008), (1.1) holds for EXC r.v. when p is given by (1.2).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixture representations

• Samaniego (IEEE TR, 1985), IID and \overline{F}_1 continuous, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \overline{F}_{i:n}(t), \qquad (1.1)$$

where $p_i = \Pr(T = X_{i:n})$.

• $\mathbf{p} = (p_1, \ldots, p_n)$ is the signature of the system.

• p_i does not depend on \overline{F}_1 and

$$p_i = \frac{\left|\{\sigma : \phi(x_1, \ldots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \ldots < x_{\sigma(n)}\}\right|}{n!}$$

- Navarro and Rychlik (JMVA, 2007), (1.1) holds for EXC r.v. with absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhathacharya (NRL, 2008), (1.1) holds for EXC r.v. when p is given by (1.2).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixture representations

• Samaniego (IEEE TR, 1985), IID and \overline{F}_1 continuous, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \overline{F}_{i:n}(t), \qquad (1.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \overline{F}_1 and

$$p_i = \frac{\left|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}\right|}{n!}$$
(1.2)

- Navarro and Rychlik (JMVA, 2007), (1.1) holds for EXC r.v. with absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhathacharya (NRL, 2008), (1.1) holds for EXC r.v. when p is given by (1.2).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixture representations

• Samaniego (IEEE TR, 1985), IID and \overline{F}_1 continuous, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \overline{F}_{i:n}(t), \qquad (1.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \ldots, p_n)$ is the signature of the system.
- p_i does not depend on \overline{F}_1 and

$$p_i = \frac{\left|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}\right|}{n!}$$
(1.2)

- Navarro and Rychlik (JMVA, 2007), (1.1) holds for EXC r.v. with absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhathacharya (NRL, 2008), (1.1) holds for EXC r.v. when p is given by (1.2).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixture representations

• Samaniego (IEEE TR, 1985), IID and \overline{F}_1 continuous, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \overline{F}_{i:n}(t), \qquad (1.1)$$

where $p_i = \Pr(T = X_{i:n})$.

• $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.

• p_i does not depend on \overline{F}_1 and

$$p_i = \frac{\left|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}\right|}{n!}$$
(1.2)

- Navarro and Rychlik (JMVA, 2007), (1.1) holds for EXC r.v. with absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhathacharya (NRL, 2008), (1.1) holds for EXC r.v. when **p** is given by (1.2).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixed systems

- A **mixed system** of order *n* is a stochastic mixture of coherent systems of order *n* (Boland and Samaniego, 2004).
- From (1.1), in the EXC case, all the mixed systems of order *n* can be written as mixtures of $X_{1:n}, \ldots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0,1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\overline{F}_T(t) = \sum_{i=1}^n c_i \overline{F}_{i:n}(t).$$

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixed systems

- A **mixed system** of order *n* is a stochastic mixture of coherent systems of order *n* (Boland and Samaniego, 2004).
- From (1.1), in the EXC case, all the mixed systems of order *n* can be written as mixtures of $X_{1:n}, \ldots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0,1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\overline{F}_T(t) = \sum_{i=1}^n c_i \overline{F}_{i:n}(t).$$

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixed systems

- A **mixed system** of order *n* is a stochastic mixture of coherent systems of order *n* (Boland and Samaniego, 2004).
- From (1.1), in the EXC case, all the mixed systems of order *n* can be written as mixtures of $X_{1:n}, \ldots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0, 1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\overline{F}_T(t) = \sum_{i=1}^n c_i \overline{F}_{i:n}(t).$$

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Mixed systems

- A **mixed system** of order *n* is a stochastic mixture of coherent systems of order *n* (Boland and Samaniego, 2004).
- From (1.1), in the EXC case, all the mixed systems of order *n* can be written as mixtures of $X_{1:n}, \ldots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0,1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\overline{F}_T(t) = \sum_{i=1}^n c_i \overline{F}_{i:n}(t).$$

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

The signature of order *n*

- Samaniego's representation was extended in Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008) as follows.
- If $T = \phi(X_1, \dots, X_k)$ and (X_1, \dots, X_n) is an EXC r.v. with $n \ge k$, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i}^{(n)} \overline{F}_{i:n}(t)$$
(1.3)

- $\mathbf{p}^{(n)} = (p_1^{(n)}, \dots, p_n^{(n)})$ is called the signature of order n of T.
- Note that T is equal in law to a mixed system based on (X_1, \ldots, X_n) with signature $\mathbf{p}^{(n)}$.
- If n = k, then $\mathbf{p}^{(k)}$ is the Samaniego's signature of T.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

The signature of order *n*

- Samaniego's representation was extended in Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008) as follows.
- If $T = \phi(X_1, \ldots, X_k)$ and (X_1, \ldots, X_n) is an EXC r.v. with $n \ge k$, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i}^{(n)} \overline{F}_{i:n}(t)$$
(1.3)

- $\mathbf{p}^{(n)} = (p_1^{(n)}, \dots, p_n^{(n)})$ is called the signature of order n of T.
- Note that T is equal in law to a mixed system based on (X_1, \ldots, X_n) with signature $\mathbf{p}^{(n)}$.
- If n = k, then $\mathbf{p}^{(k)}$ is the Samaniego's signature of T.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

The signature of order *n*

- Samaniego's representation was extended in Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008) as follows.
- If $T = \phi(X_1, \ldots, X_k)$ and (X_1, \ldots, X_n) is an EXC r.v. with $n \ge k$, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i}^{(n)} \overline{F}_{i:n}(t)$$
(1.3)

- $\mathbf{p}^{(n)} = (p_1^{(n)}, \dots, p_n^{(n)})$ is called the signature of order n of T.
- Note that T is equal in law to a mixed system based on (X_1, \ldots, X_n) with signature $\mathbf{p}^{(n)}$.
- If n = k, then $\mathbf{p}^{(k)}$ is the Samaniego's signature of T.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

The signature of order *n*

- Samaniego's representation was extended in Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008) as follows.
- If $T = \phi(X_1, \ldots, X_k)$ and (X_1, \ldots, X_n) is an EXC r.v. with $n \ge k$, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i}^{(n)} \overline{F}_{i:n}(t)$$
(1.3)

- $\mathbf{p}^{(n)} = (p_1^{(n)}, \dots, p_n^{(n)})$ is called the signature of order n of T.
- Note that T is equal in law to a mixed system based on (X_1, \ldots, X_n) with signature $\mathbf{p}^{(n)}$.
- If n = k, then $\mathbf{p}^{(k)}$ is the Samaniego's signature of T.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

The signature of order *n*

- Samaniego's representation was extended in Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008) as follows.
- If $T = \phi(X_1, \ldots, X_k)$ and (X_1, \ldots, X_n) is an EXC r.v. with $n \ge k$, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i}^{(n)} \overline{F}_{i:n}(t)$$
(1.3)

- $\mathbf{p}^{(n)} = (p_1^{(n)}, \dots, p_n^{(n)})$ is called the signature of order n of T.
- Note that T is equal in law to a mixed system based on (X_1, \ldots, X_n) with signature $\mathbf{p}^{(n)}$.
- If n = k, then $\mathbf{p}^{(k)}$ is the Samaniego's signature of T.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Generalized mixture representations

• Navarro, Ruiz and Sandoval (CSTM, 2007), if *T* has EXC components, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}_{1:i}(t).$$
(1.4)

- $\mathbf{a} = (a_1, \ldots, a_n)$ is the minimal signature of T.
- a_i only depends on φ but can be negative and so (1.4) is a generalized mixture.
- A similar representation holds in terms of parallel systems.
- In particular, in the IID case:

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}^{i}(t) = h(\overline{F}(t)), \qquad (1.5)$$

where $h(x) = \sum_{i=1}^{n} a_i x^i$ is the domination or reliability polynomial

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Generalized mixture representations

• Navarro, Ruiz and Sandoval (CSTM, 2007), if *T* has EXC components, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}_{1:i}(t).$$
(1.4)

- $\mathbf{a} = (a_1, \ldots, a_n)$ is the minimal signature of T.
- a_i only depends on φ but can be negative and so (1.4) is a generalized mixture.
- A similar representation holds in terms of parallel systems.
- In particular, in the IID case:

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}^{i}(t) = h(\overline{F}(t)), \qquad (1.5)$$

where $h(x) = \sum_{i=1}^{n} a_i x^i$ is the domination or reliability polynomial

Sac

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Generalized mixture representations

• Navarro, Ruiz and Sandoval (CSTM, 2007), if *T* has EXC components, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}_{1:i}(t).$$
(1.4)

- $\mathbf{a} = (a_1, \ldots, a_n)$ is the minimal signature of T.
- *a_i* only depends on φ but can be negative and so (1.4) is a generalized mixture.
- A similar representation holds in terms of parallel systems.
- In particular, in the IID case:

$$\overline{F}_{\mathcal{T}}(t) = \sum_{i=1}^{n} a_i \overline{F}^i(t) = h(\overline{F}(t)), \qquad (1.5)$$

where $h(x) = \sum_{i=1}^{n} a_i x^i$ is the domination or reliability polynomial

Sac

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Generalized mixture representations

• Navarro, Ruiz and Sandoval (CSTM, 2007), if *T* has EXC components, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}_{1:i}(t).$$
(1.4)

- $\mathbf{a} = (a_1, \ldots, a_n)$ is the minimal signature of T.
- a_i only depends on \u03c6 but can be negative and so (1.4) is a generalized mixture.
- A similar representation holds in terms of parallel systems.
- In particular, in the IID case:

$$\overline{F}_{\mathcal{T}}(t) = \sum_{i=1}^{n} a_i \overline{F}^i(t) = h(\overline{F}(t)), \qquad (1.5)$$

where $h(x) = \sum_{i=1}^{n} a_i x^i$ is the domination or reliability

Sac

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Generalized mixture representations

• Navarro, Ruiz and Sandoval (CSTM, 2007), if *T* has EXC components, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}_{1:i}(t).$$
(1.4)

- $\mathbf{a} = (a_1, \ldots, a_n)$ is the minimal signature of T.
- a_i only depends on \u03c6 but can be negative and so (1.4) is a generalized mixture.
- A similar representation holds in terms of parallel systems.
- In particular, in the IID case:

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} a_{i} \overline{F}^{i}(t) = h(\overline{F}(t)), \qquad (1.5)$$

where $h(x) = \sum_{i=1}^{n} a_i x^i$ is the domination or reliability polynomial ISI Dublin 2011 Representations of systems with heterogeneous components

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \overline{F}_X(t) \leq \overline{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X t | X > t) \leq_{ST} (Y t | Y > t)$ for all t.
- $X \leq_{MRL} Y \Leftrightarrow E(X t | X > t) \leq E(Y t | Y > t)$, mean residual life order.
- X ≤_{LR} Y ⇔ f_Y(t)/f_X(t) is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for s < t.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Stochastic orderings relationships

$$\begin{array}{ccccccc} E(X_{s,t}) \leq E(Y_{s,t}) & \Rightarrow & E(X_t) \leq E(Y_t) & \Rightarrow & E(X) \leq E(Y) \\ & \uparrow & & \uparrow & & \uparrow \\ X \leq_{DTM} Y & \Rightarrow & X \leq_{MRL} Y & \Rightarrow & X \leq_{M} Y \\ & \uparrow & & \uparrow & & \uparrow \\ X \leq_{LR} Y & \Rightarrow & X \leq_{HR} Y & \Rightarrow & X \leq_{ST} Y \\ & \uparrow & & \uparrow & & \uparrow \\ X_{s,t} \leq_{ST} Y_{s,t} & \Rightarrow & X_t \leq_{ST} Y_t & \Rightarrow & \overline{F}_X \leq \overline{F}_Y \end{array}$$

where $Z_t = (Z - t | Z > t)$ and $Z_{s,t} = (Z | s < Z < t)$ (see Navarro, Belzunce and Ruiz, PEIS, 1997).

A D A A B A A B A A B A

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Ordering results for systems-IID case

Theorem (Kochar, Mukerjee and Samaniego, NRL 1999)

Let \mathbf{p}_1 and \mathbf{p}_2 be the signatures of the two coherent systems of order n, both based on components with IID lifetimes with common continuous reliability \overline{F} . Let T_1 and T_2 be their respective lifetimes.

(i) If
$$\mathbf{p}_1 \leq_{ST} \mathbf{p}_2$$
, then $T_1 \leq_{ST} T_2$.
(ii) If $\mathbf{p}_1 \leq_{HR} \mathbf{p}_2$, then $T_1 \leq_{HR} T_2$.
(iii) If $\mathbf{p}_1 \leq_{LR} \mathbf{p}_2$, then $T_1 \leq_{LR} T_2$.

Introduction Representations for systems with independents components References

Ordering results

Ordering results for k-out-of systems

• For any
$$X_1, \ldots, X_n$$
, we have

Representations for systems with dependent components

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}. \tag{1.6}$$

However,

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n} \tag{1.7}$$

Analogously

$$X_{1:n} \leq_{MRL} \cdots \leq_{MRL} X_{n:n}, \tag{1.8}$$

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n} \tag{1.9}$$
Mixture representations Ordering results Outline

Representations for systems with independents components Representations for systems with dependent components References

Ordering results for k-out-ofn systems

• For any
$$X_1, \ldots, X_n$$
, we have

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}. \tag{1.6}$$

• However,

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n} \tag{1.7}$$

does not necessarily hold (see Navarro and Shaked, JAP, 2006)

Analogously

$$X_{1:n} \leq_{MRL} \cdots \leq_{MRL} X_{n:n}, \tag{1.8}$$

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n} \tag{1.9}$$

do not necessarily hold (see Navarro and Hernandez, Metrika, 2008, and Navarro, JSPI, 2008).

Mixture representations Ordering results Outline

Representations for systems with independents components Representations for systems with dependent components References

Ordering results for k-out-ofn systems

• For any
$$X_1, \ldots, X_n$$
, we have

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}. \tag{1.6}$$

• However,

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n} \tag{1.7}$$

does not necessarily hold (see Navarro and Shaked, JAP, 2006)

Analogously

$$X_{1:n} \leq_{MRL} \cdots \leq_{MRL} X_{n:n}, \qquad (1.8)$$

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n} \tag{1.9}$$

do not necessarily hold (see Navarro and Hernandez, Metrika, 2008, and Navarro, JSPI, 2008).

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

Ordering results for systems-EXC case

Theorem (Navarro et al., NRL 2008)

If
$$T_1 = \phi_1(Y_1, \ldots, Y_{n_1})$$
 and $T_2 = \phi_2(Z_1, \ldots, Z_{n_2})$ have signatures
of order $n \mathbf{p}^{(n)} = (p_1, \ldots, p_n)$ and $\mathbf{q}^{(n)} = (q_1, \ldots, q_n)$,
 $\{Y_1, \ldots, Y_{n_1}\}$ and $\{Z_1, \ldots, Z_{n_2}\}$ are contained in $\{X_1, \ldots, X_n\}$
and (X_1, \ldots, X_n) is EXC, then:
(i) If $\mathbf{p}^{(n)} \leq_{ST} \mathbf{q}^{(n)}$, then $T_1 \leq_{ST} T_2$.
(ii) If $\mathbf{p}^{(n)} \leq_{HR} \mathbf{q}^{(n)}$ and (1.7) holds, then $T_1 \leq_{HR} T_2$.
(iii) If $\mathbf{p}^{(n)} \leq_{HR} \mathbf{q}^{(n)}$ and (1.8) holds, then $T_1 \leq_{MRL} T_2$.
(iv) If $\mathbf{p}^{(n)} \leq_{LR} \mathbf{q}^{(n)}$ and (1.9) holds, then $T_1 \leq_{LR} T_2$.

イロト イポト イヨト イヨト

nac

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

New results included in this talk

- Representations for systems with INID components.
- Representations for systems with DNID components.
- Ordering properties based on signatures.
- The results are included in the paper: J. Navarro, F.J. Samaniego, and N. Balakrishnan. Signature-based representations for the reliability of systems with heterogeneous components. To appear in Journal of Applied Probability 48 (3), 2011.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

New results included in this talk

- Representations for systems with INID components.
- Representations for systems with DNID components.
- Ordering properties based on signatures.
- The results are included in the paper: J. Navarro, F.J. Samaniego, and N. Balakrishnan. Signature-based representations for the reliability of systems with heterogeneous components. To appear in Journal of Applied Probability 48 (3), 2011.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

New results included in this talk

- Representations for systems with INID components.
- Representations for systems with DNID components.
- Ordering properties based on signatures.
- The results are included in the paper: J. Navarro, F.J. Samaniego, and N. Balakrishnan. Signature-based representations for the reliability of systems with heterogeneous components. To appear in Journal of Applied Probability 48 (3), 2011.

Representations for systems with independents components Representations for systems with dependent components References Mixture representations Ordering results Outline

New results included in this talk

- Representations for systems with INID components.
- Representations for systems with DNID components.
- Ordering properties based on signatures.
- The results are included in the paper: J. Navarro, F.J. Samaniego, and N. Balakrishnan. Signature-based representations for the reliability of systems with heterogeneous components. To appear in Journal of Applied Probability 48 (3), 2011.

Mixture representation Ordering results Example

General mixture representation

• If
$$X_{1:n} < \cdots < X_{n:n}$$
, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \operatorname{Pr}(X_{i:n} > t | T = X_{i:n}), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$ and $\Pr(X_{i:n} > t | T = X_{i:n}) \neq \overline{F}_{i:n}(t).$

• We can define two signatures: $\mathbf{p} = (p_1, \dots, p_n)$ with $p_i = \Pr(T = X_{i:n})$ (called probability signature) and $\mathbf{s} = (s_1, \dots, s_n)$ with s_i given by (1.2) (called structure signature).

References

• Example 5.1 in Navarro, Samaniego, Balakrishnan and Bhathacharya NRL,2008) proves that

$$\overline{F}_{T}(t) \neq \sum_{i=1}^{n} c_{i} \overline{F}_{i:n}(t),$$

Representations for systems with independents components

Representations for systems with dependent components References Mixture representation Ordering results Example

General mixture representation

• If
$$X_{1:n} < \cdots < X_{n:n}$$
, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \operatorname{Pr}(X_{i:n} > t | T = X_{i:n}), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$ and $\Pr(X_{i:n} > t | T = X_{i:n}) \neq \overline{F}_{i:n}(t).$

- We can define two signatures: $\mathbf{p} = (p_1, \ldots, p_n)$ with $p_i = \Pr(T = X_{i:n})$ (called probability signature) and $\mathbf{s} = (s_1, \ldots, s_n)$ with s_i given by (1.2) (called structure signature).
- Example 5.1 in Navarro, Samaniego, Balakrishnan and Bhathacharya NRL,2008) proves that

$$\overline{F}_{T}(t) \neq \sum_{i=1}^{n} c_{i} \overline{F}_{i:n}(t),$$

Representations for systems with independents components

Representations for systems with dependent components References Mixture representation Ordering results Example

General mixture representation

• If
$$X_{1:n} < \cdots < X_{n:n}$$
, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} p_{i} \operatorname{Pr}(X_{i:n} > t | T = X_{i:n}), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$ and $\Pr(X_{i:n} > t | T = X_{i:n}) \neq \overline{F}_{i:n}(t).$

- We can define two signatures: $\mathbf{p} = (p_1, \ldots, p_n)$ with $p_i = \Pr(T = X_{i:n})$ (called probability signature) and $\mathbf{s} = (s_1, \ldots, s_n)$ with s_i given by (1.2) (called structure signature).
- Example 5.1 in Navarro, Samaniego, Balakrishnan and Bhathacharya NRL,2008) proves that

$$\overline{F}_{T}(t) \neq \sum_{i=1}^{n} c_{i} \overline{F}_{i:n}(t),$$

Mixture representation

Generalized mixture representation using path sets

- A set $P \subseteq \{1, \ldots, n\}$ is a *path set* of a coherent system if the system works when all the components in P work.
- A path set P is a *minimal path set* if it does not contain other
- If T has minimal path sets P_1, \ldots, P_k , then

$$T = \max_{j=1,\dots,k} X_{P_j}, \tag{2.2}$$

where $X_{P_i} = \min_{i \in P_i} X_i$, for $j = 1, \dots, k$ (see Barlow and

• From the inclusion-exclusion formula we have

$$\overline{F}_{T}(t) = \sum_{j=1}^{k} \overline{F}_{P_{j}}(t) - \sum_{i < j} \overline{F}_{P_{i} \cup P_{j}}(t) + \dots + (-1)^{k+1} \overline{F}_{P_{1} \cup \dots \cup P_{k}}(t),$$

where $\overline{F}_{P}(t) = \Pr(X_{P} > t)$ and $X_{P} = \min_{t \in \mathcal{B}} \mathcal{K}_{t}, \forall \geq \forall \neq \geq \bullet$ nan ISI Dublin 2011

Mixture representation Ordering results

Generalized mixture representation using path sets

- A set $P \subseteq \{1, \ldots, n\}$ is a *path set* of a coherent system if the system works when all the components in P work.
- A path set P is a *minimal path set* if it does not contain other path sets.
- If T has minimal path sets P_1, \ldots, P_k , then

$$T = \max_{j=1,\dots,k} X_{P_j}, \tag{2.2}$$

where $X_{P_i} = \min_{i \in P_i} X_i$, for $j = 1, \dots, k$ (see Barlow and

From the inclusion-exclusion formula we have

$$\overline{F}_{T}(t) = \sum_{j=1}^{k} \overline{F}_{P_{j}}(t) - \sum_{i < j} \overline{F}_{P_{i} \cup P_{j}}(t) + \dots + (-1)^{k+1} \overline{F}_{P_{1} \cup \dots \cup P_{k}}(t),$$

where $\overline{F}_{P}(t) = \Pr(X_{P} > t)$ and $X_{P} = \min_{t \in \mathcal{B}} \mathcal{K}_{t}, \forall \geq \forall \neq \geq \bullet$ nan ISI Dublin 2011

Mixture representation Ordering results

Generalized mixture representation using path sets

- A set $P \subseteq \{1, \ldots, n\}$ is a *path set* of a coherent system if the system works when all the components in P work.
- A path set P is a *minimal path set* if it does not contain other path sets.
- If T has minimal path sets P_1, \ldots, P_k , then

$$T = \max_{j=1,\dots,k} X_{P_j}, \tag{2.2}$$

where $X_{P_i} = \min_{i \in P_i} X_i$, for j = 1, ..., k (see Barlow and Proschan, 1975).

From the inclusion-exclusion formula we have

$$\overline{F}_{T}(t) = \sum_{j=1}^{\kappa} \overline{F}_{P_{j}}(t) - \sum_{i < j} \overline{F}_{P_{i} \cup P_{j}}(t) + \dots + (-1)^{k+1} \overline{F}_{P_{1} \cup \dots \cup P_{k}}(t),$$

where $\overline{F}_{P}(t) = \Pr(X_{P} > t)$ and $X_{P} = \min_{t \in P} \mathscr{K}_{P}, \forall z \to \forall z$ nan ISI Dublin 2011

Mixture representation Ordering results Example

Generalized mixture representation using path sets

- A set P ⊆ {1,..., n} is a path set of a coherent system if the system works when all the components in P work.
- A path set *P* is a *minimal path set* if it does not contain other path sets.
- If T has minimal path sets P_1, \ldots, P_k , then

$$T = \max_{j=1,\dots,k} X_{P_j}, \tag{2.2}$$

where $X_{P_j} = \min_{i \in P_j} X_i$, for j = 1, ..., k (see Barlow and Proschan, 1975).

• From the inclusion-exclusion formula we have

$$\overline{F}_{\mathcal{T}}(t) = \sum_{j=1}^{k} \overline{F}_{P_{j}}(t) - \sum_{i < j} \overline{F}_{P_{i} \cup P_{j}}(t) + \dots + (-1)^{k+1} \overline{F}_{P_{1} \cup \dots \cup P_{k}}(t),$$
(2.3)

where $\overline{F}_P(t) = \Pr(X_P > t)$ and $X_P = \min_{i \in P} \mathbb{X}_i \quad \exists \to \exists \to \exists \to \forall q \in \mathbb{N}$ ISI Dublin 2011 Representations of systems with heterogeneous components

Mixture representation Ordering results Example

Reliability representations for the INID case

• If $X_1, ..., X_n$ are independent, then

$$\overline{F}_P(t) = \prod_{i \in P} \overline{F}_i(t).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = H(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (2.4)$$

- *H* is called *reliability structure function* in Esary and Proschan (Tech, 1963).
- *H* is strictly increasing in (0, 1) in each variable and H(x, ..., x) = h(x).

Mixture representation Ordering results Example

Reliability representations for the INID case

• If $X_1, ..., X_n$ are independent, then

$$\overline{F}_P(t) = \prod_{i \in P} \overline{F}_i(t).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = H(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (2.4)$$

- *H* is called *reliability structure function* in Esary and Proschan (Tech, 1963).
- *H* is strictly increasing in (0, 1) in each variable and H(x, ..., x) = h(x).

Mixture representation Ordering results Example

Reliability representations for the INID case

• If $X_1, ..., X_n$ are independent, then

$$\overline{F}_P(t) = \prod_{i \in P} \overline{F}_i(t).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = H(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (2.4)$$

- *H* is called *reliability structure function* in Esary and Proschan (Tech, 1963).
- *H* is strictly increasing in (0, 1) in each variable and H(x, ..., x) = h(x).

Mixture representation Ordering results Example

Reliability representations for the INID case

• If $X_1, ..., X_n$ are independent, then

$$\overline{F}_P(t) = \prod_{i \in P} \overline{F}_i(t).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = H(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (2.4)$$

- *H* is called *reliability structure function* in Esary and Proschan (Tech, 1963).
- *H* is strictly increasing in (0, 1) in each variable and H(x, ..., x) = h(x).

Mixture representation Ordering results Example

Reliability representations for the independent case

Theorem

Let $T = \phi(X_1, ..., X_n)$ be the lifetime of a system with independent components, signature vector $\mathbf{s} = (s_1, ..., s_n)$ and reliability polynomial and reliability structure function h and H, respectively. Then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} s_{i} \overline{G}_{i:n}(t), \qquad (2.5)$$

where $\overline{G}_{i:n}(t) = P(Y_{i:n} > t)$ and Y_1, \ldots, Y_n are IID with a common reliability function

$$\overline{G}(t) = h^{-1}(H(\overline{F}_1(t), \dots, \overline{F}_n(t))).$$
(2.6)

・ロト ・ 同ト ・ ヨト ・ ヨト

Mixture representation Ordering results Example

Reliability representations for the independent case

• T is equal in law to a system with the same structure and IID components with reliability \overline{G} .

Definition

If $\psi : S \subseteq \mathbb{R}^n \to \mathbb{R}$ is a real valued function, a *mean function* of ψ in S is a function $m_{\psi} : \mathbb{R}^n \to \mathbb{R}$ such that

$$\psi(x_1,\ldots,x_n)=\psi(z,\ldots,z)$$

for all $(x_1, \ldots, x_n) \in S$, where $z = m_{\psi}(x_1, \ldots, x_n)$.

۲

• If m_H is the mean function of H, then

$$\overline{G}(t) = m_H(\overline{F}_1(t), \ldots, \overline{F}_n(t)).$$

・ロト ・回ト ・ヨト ・ヨト

Mixture representation Ordering results Example

Reliability representations for the independent case

• T is equal in law to a system with the same structure and IID components with reliability \overline{G} .

Definition

If $\psi : S \subseteq \mathbb{R}^n \to \mathbb{R}$ is a real valued function, a *mean function* of ψ in S is a function $m_{\psi} : \mathbb{R}^n \to \mathbb{R}$ such that

$$\psi(x_1,\ldots,x_n)=\psi(z,\ldots,z)$$

for all $(x_1, \ldots, x_n) \in S$, where $z = m_{\psi}(x_1, \ldots, x_n)$.

• If m_H is the mean function of H, then

$$\overline{G}(t) = m_H(\overline{F}_1(t), \ldots, \overline{F}_n(t)).$$

Mixture representation Ordering results Example

Reliability representations for the independent case

• T is equal in law to a system with the same structure and IID components with reliability \overline{G} .

Definition

If $\psi: S \subseteq \mathbb{R}^n \to \mathbb{R}$ is a real valued function, a *mean function* of ψ in S is a function $m_{\psi}: \mathbb{R}^n \to \mathbb{R}$ such that

$$\psi(x_1,\ldots,x_n)=\psi(z,\ldots,z)$$

for all $(x_1, \ldots, x_n) \in S$, where $z = m_{\psi}(x_1, \ldots, x_n)$.

• If m_H is the mean function of H, then

$$\overline{G}(t) = m_H(\overline{F}_1(t), \ldots, \overline{F}_n(t)).$$

Representations for systems with independents components

Representations for systems with dependent components References Mixture representation Ordering results Example

Ordering results INID case

Theorem

Let T and T^* be the lifetimes of two coherent systems with signatures $\mathbf{s} = (s_1, \ldots, s_n)$ and $\mathbf{s}^* = (s_1^*, \ldots, s_n^*)$ and both with independent component lifetimes. Let h and h* be their reliability polynomials and let H and H^{*} be their structure reliability functions. Let \overline{G} and \overline{G}^* be the reliability functions defined in (2.6).(i) If $\overline{G} \leq_{ST} \overline{G}^*$ and $\mathbf{s} \leq_{ST} \mathbf{s}^*$, then $T \leq_{ST} T^*$; (ii) If $\overline{G} <_{HR} \overline{G}^*$, $\mathbf{s} <_{HR} \mathbf{s}^*$ and either xh'(x)/h(x) or $x(h^*)'(x)/h(x)$ is decreasing, then $T \leq_{HR} T^*$; (iii) If $\overline{G} \leq_{RHR} \overline{G}^*$, $\mathbf{s} \leq_{RHR} \mathbf{s}^*$ and either (1-x)h'(x)/(1-h(x))or $(1-x)(h^*)'(x)/(1-h^*(x))$ is increasing, then $T \leq_{RHR} T^*$.

・ロト ・回ト ・ヨト ・ヨト

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $\mathbf{s} = \left(0, \frac{2}{3}, \frac{1}{3}, 0\right)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

 $\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

 $H(p_1, p_2, p_3, p_4) = p_1p_2 + p_3p_4 - p_1p_2p_3p_4.$

- Also, $h(p) = 2p^2 p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.
- Then

$$\overline{G} = \sqrt{1 - \sqrt{1 - \overline{F}_1 \overline{F}_2 - \overline{F}_3 \overline{F}_4 + \overline{F}_1 \overline{F}_2 \overline{F}_3 \overline{F}_4}}.$$
 (2.7)

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $s = (0, \frac{2}{3}, \frac{1}{3}, 0)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

 $\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

 $H(p_1, p_2, p_3, p_4) = p_1 p_2 + p_3 p_4 - p_1 p_2 p_3 p_4.$

- Also, $h(p) = 2p^2 p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.
- Then

$$\overline{G} = \sqrt{1 - \sqrt{1 - \overline{F}_1 \overline{F}_2 - \overline{F}_3 \overline{F}_4 + \overline{F}_1 \overline{F}_2 \overline{F}_3 \overline{F}_4}}.$$
 (2.7)

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $s = (0, \frac{2}{3}, \frac{1}{3}, 0)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

 $\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

 $H(p_1, p_2, p_3, p_4) = p_1p_2 + p_3p_4 - p_1p_2p_3p_4.$

- Also, $h(p) = 2p^2 p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.
- Then

$$\overline{G} = \sqrt{1 - \overline{F_1}\overline{F_2} - \overline{F_3}\overline{F_4} + \overline{F_1}\overline{F_2}\overline{F_3}\overline{F_4}}.$$
(2.7)

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $s = (0, \frac{2}{3}, \frac{1}{3}, 0)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

$$\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

$$H(p_1, p_2, p_3, p_4) = p_1p_2 + p_3p_4 - p_1p_2p_3p_4.$$

- Also, $h(p) = 2p^2 p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.
- Then

$$\overline{G} = \sqrt{1 - \sqrt{1 - \overline{F}_1 \overline{F}_2 - \overline{F}_3 \overline{F}_4 + \overline{F}_1 \overline{F}_2 \overline{F}_3 \overline{F}_4}}.$$
(2.7)

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $s = (0, \frac{2}{3}, \frac{1}{3}, 0)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

$$\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

$$H(p_1, p_2, p_3, p_4) = p_1p_2 + p_3p_4 - p_1p_2p_3p_4.$$

• Also, $h(p) = 2p^2 - p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.

Then

$$\overline{G} = \sqrt{1 - \overline{F_1}\overline{F_2} - \overline{F_3}\overline{F_4} + \overline{F_1}\overline{F_2}\overline{F_3}\overline{F_4}}.$$
(2.7)

Mixture representation Ordering results Example

Example

- $T = \max(\min(X_1, X_2), \min(X_3, X_4))$
- $s = (0, \frac{2}{3}, \frac{1}{3}, 0)$
- \bullet The minimal path sets are $\{1,2\}$ and $\{3,4\}$ and then

$$\overline{F}_{T}(t) = \overline{F}_{1}(t)\overline{F}_{2}(t) + \overline{F}_{3}(t)\overline{F}_{4}(t) - \overline{F}_{1}(t)\overline{F}_{2}(t)\overline{F}_{3}(t)\overline{F}_{4}(t).$$

• $\overline{F}_T(t) = H(\overline{F}_1(t), \overline{F}_2(t), \overline{F}_3(t), \overline{F}_4(t))$, where

$$H(p_1, p_2, p_3, p_4) = p_1p_2 + p_3p_4 - p_1p_2p_3p_4.$$

• Also, $h(p) = 2p^2 - p^4$ and $\mathbf{a} = (0, 2, 0, -1)$.

Then

$$\overline{G} = \sqrt{1 - \sqrt{1 - \overline{F}_1 \overline{F}_2 - \overline{F}_3 \overline{F}_4 + \overline{F}_1 \overline{F}_2 \overline{F}_3 \overline{F}_4}}.$$
 (2.7)

Introduction Representations for systems with independents components Representations for systems with dependent components References References Mixture representation Ordering results Example



Figure: Mean reliability function \overline{G} (red line) for exponential reliability functions $\overline{F}_i(t) = \exp(-it)$, i = 1, 2, 3, 4.

DQC

Mixture representations Ordering results

Reliability representations for the DNID case

• If
$$(X_1, ..., X_n)$$
 has joint reliability \overline{F} , then
 $\overline{F}_P(t) = \overline{F}(t_P)$,
where $\overline{F}(x_1, ..., x_n) = \Pr(X_1 > x_1, ..., X_n > x_n)$ and
 $t_P = (t_1, ..., t_n)$ with $t_i = t$ for $i \in P$ and $t_i = 0$ for $i \notin P$.
• Using Sklar's representation for \overline{F} , we have
 $\overline{F}(x_1, ..., x_n) = K(\overline{F}_1(x_1), ..., \overline{F}_n(x_n))$, (3.1)
where K is the survival copula. Then
 $\overline{F}_P(t) = K(\overline{F}_1(t_1), ..., \overline{F}_n(t_n))$.

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = W(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (3.2)$$

where W only depends on K and P_1, \ldots, P_k and is called structure-dependence function.

ISI Dublin 2011

Mixture representations Ordering results

Reliability representations for the DNID case

$$\overline{F}_P(t) = K(\overline{F}_1(t_1), \ldots, \overline{F}_n(t_n)).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = W(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (3.2)$$

where W only depends on K and P_1, \ldots, P_k and is called structure-dependence function.

ISI Dublin 2011

Mixture representations Ordering results

Reliability representations for the DNID case

• If
$$(X_1, ..., X_n)$$
 has joint reliability \overline{F} , then
 $\overline{F}_P(t) = \overline{F}(t_P)$,
where $\overline{F}(x_1, ..., x_n) = \Pr(X_1 > x_1, ..., X_n > x_n)$ and
 $t_P = (t_1, ..., t_n)$ with $t_i = t$ for $i \in P$ and $t_i = 0$ for $i \notin P$.
• Using Sklar's representation for \overline{F} , we have
 $\overline{F}(x_1, ..., x_n) = K(\overline{F}_1(x_1), ..., \overline{F}_n(x_n))$, (3.1)

where K is the survival copula. Then

$$\overline{F}_P(t) = K(\overline{F}_1(t_1), \ldots, \overline{F}_n(t_n)).$$

• Therefore (2.3) can be written as

$$\overline{F}_{T}(t) = W(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)), \qquad (3.2)$$

where W only depends on K and P_1, \ldots, P_k and is called structure-dependence function.

Mixture representations Ordering results

Reliability representations for the general case

Theorem

If $T = \phi(X_1, ..., X_n)$ is the lifetime of a system with structure-dependence function W having right-continuous increasing mean function m_W , then

$$T =_{ST} T^* = \phi(Y_1, \ldots, Y_n)$$

with ID component lifetimes Y_1, \ldots, Y_n with

$$\mathcal{P}(Y_1 > x_1, \dots, Y_n > x_n) = \mathcal{K}(\overline{\mathcal{G}}_W(x_1), \dots, \overline{\mathcal{G}}_W(x_n)), \quad (3.3)$$

where K is the survival copula of (X_1, \ldots, X_n) and

$$\overline{G}_{W}(t) = m_{W}(\overline{F}_{1}(t), \dots, \overline{F}_{n}(t)).$$
(3.4)

nan

Mixture representations Ordering results

Reliability representations for exchangeable copulas

Theorem

If T is the lifetime of a system with signature $\mathbf{s} = (s_1, \ldots, s_n)$, with structure-dependence function W having right-continuous increasing mean function m_W and with components having an exchangeable copula K, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{n} s_{i} \overline{G}_{i:n}(t), \qquad (3.5)$$

where $\overline{G}_{i:n}(t) = P(Y_{i:n} > t)$ and $Y_{1:n} < \cdots < Y_{n:n}$ are the order statistics obtained from the random variables Y_1, \ldots, Y_n with joint reliability function as in (3.3).

Mixture representations Ordering results

Other reliability representation for general copulas

Theorem

If T is the lifetime of a system with signature $\mathbf{s} = (s_1, \ldots, s_n)$ and with component lifetimes X_1, \ldots, X_n having structure-dependence function W, then

$$\overline{F}_{T}(t) = \sum_{i=1}^{\infty} s_{i} \overline{G}_{i:n}(t),$$

where $\overline{G}_{i:n}(t) = P(Y_{i:n} > t)$ and $Y_{1:n} < \cdots < Y_{n:n}$ are the order statistics obtained from IID r.v. Y_1, \ldots, Y_n with common reliability function as

$$\widetilde{G}(t) = h^{-1}(W(\overline{F}_1(t),\ldots,\overline{F}_n(t))),$$

and h is the reliability polynomial.

・ロト ・同ト ・ヨト ・ヨト
Representations for systems with independents components Representations for systems with dependent components References

Mixture representation Ordering results

Ordering results

Theorem

Let T and T^{*} be the lifetimes of two coherent systems with signatures $\mathbf{s} = (s_1, \ldots, s_n)$ and $\mathbf{s}^* = (s_1^*, \ldots, s_n^*)$ and with components having the same exchangeable survival copula K. Let \overline{G}_W and \overline{G}_{W^*} be the reliability functions defined by (3.4). If $\mathbf{s} \leq_{ST} \mathbf{s}^*$ and $\overline{G}_W \leq \overline{G}_{W^*}$, then $T \leq_{ST} T^*$.

Theorem

Let T and T^{*} be the lifetimes of two coherent systems with signatures $\mathbf{s} = (s_1, \ldots, s_n)$ and $\mathbf{s}^* = (s_1^*, \ldots, s_n^*)$ and T^{*} having IID component lifetimes with reliability function \overline{R} . If $\mathbf{s} \leq_{ST} \mathbf{s}^*$, and $\widetilde{G} \leq \overline{R}$, then $T \leq_{ST} T^*$.

イロト イポト イヨト イヨト

Representations for systems with independents components Representations for systems with dependent components References Our references Other references

Our main references

- Navarro, J., Samaniego, F., Balakrishnan, N. and Bhattacharya, D. (2008). On the Application and Extension of System Signatures in Engineering Reliability, Naval Research Logistics 55, 313-327.
- Navarro, J., Balakrishnan, N. and Samaniego, F.J. (2008). Mixture representations of residual lifetimes of used systems, Journal of Applied Probability 45 (4), 1097-1112.
- Navarro, J., Samaniego, F.J. and Balakrishnan, N. (2010). The joint signature of coherent systems with shared components. Journal of Applied Probability 47 (1), 235-253.
- Navarro, J., Samaniego, F.J. and Balakrishnan, N. Signature-based representations for the reliability of systems with heterogeneous components. To appear in Journal of Applied Probability 48 (3), 2011.

Representations for systems with independents components Representations for systems with dependent components References Our references Other references

Other references

- Boland, P. J. and Samaniego, F. (2004). The signature of a coherent system and its applications in reliability. In *Mathematical Reliability: An Expository Perspective* (Eds., R. Soyer, T. Mazzuchi and N.D. Singpurwalla), pp. 1–29. Kluwer Publishers, Boston.
- Esary, J. D. and Proschan, F. (1963). Relationship between system failure rate and component failure rates. Technometrics 5, 183–189.
- Kochar, S., Mukerjee, H., and Samaniego, F. J (1999). The "signature" of a coherent system and its application to comparison among systems. Naval Res. Logist. 46, 507–523.

A D A A B A A B A A B A

Representations for systems with independents components Representations for systems with dependent components References Our references Other references

Other references

- Navarro, J., Ruiz, J.M. and Sandoval, C.J. (2007). Properties of Coherent Systems with Dependent Components. Comm. Stat. Theory and Methods 36 (1), 1-17.
- Navarro, J. and Rychlik, T. (2007). Reliability and expectation bounds for coherent systems with exchangeable components. J. Multivariate Anal. 98, 102-113.
- Navarro, J. and Rychlik, T. (2010). Comparisons and bounds for expected lifetimes of reliability systems. European Journal of Operational Research 207, 309-317.
- Navarro, J. Spizzichino, F. and Balakrishnan, N. (2010). Applications of average and projected systems to the study of coherent systems. J. Multiv. Anal. 101, 1471-1482.