

Molecular Dynamics simulations of Biomolecules

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Modelado Molecular

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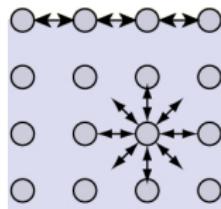
Solvents

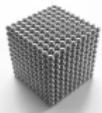
- Most of chemical reactions take place in solution
- Good solvent {
 - Inert
 - Able to solve all reactants
 - Adequate ebullition point
 - Easy to separate
- Inert \neq neutral \Rightarrow {
 - Energy fluxes
 - Intermolecular interactions
- Quantum-mechanical simulations \Rightarrow computationally forbidden.
- Molecular Dynamics



Periodic boundary conditions

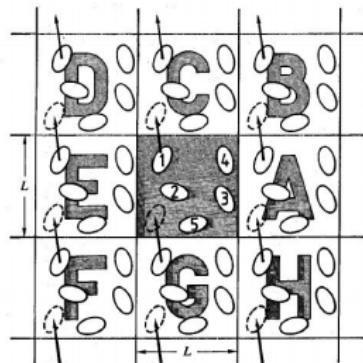
- Cubic box \Rightarrow Surface effects \Rightarrow Surface tension



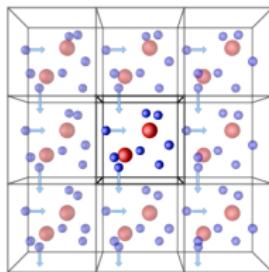
-  $5^3 = 125$ molecules $\left\{ \begin{array}{ll} \text{Surface} & 25 + (25 - 5) + (25 - 9) + (25 - 9) \\ & + (25 - 13) + (25 - 16) = 98 \quad (78.4\%) \\ \text{Bulk} & 125 - 98 = 27 \quad (21.6\%) \end{array} \right.$
-  $6^3 = 216$ molecules $\left\{ \begin{array}{ll} \text{Surface} & 36 + (36 - 6) + (36 - 11) + (36 - 11) \\ & + (36 - 16) + (36 - 20) = 152 \quad (70.4\%) \\ \text{Bulk} & 216 - 152 = 64 \quad (29.6\%) \end{array} \right.$
-  $10^3 = 1000$ mol. $\left\{ \begin{array}{ll} \text{Surface} & 100 + (100 - 10) + (100 - 19) + (100 - 19) \\ & + (100 - 28) + (100 - 36) = 488 \quad (48.8\%) \\ \text{Bulk} & 1000 - 488 = 512 \quad (51.2\%) \end{array} \right.$



Periodic boundary conditions

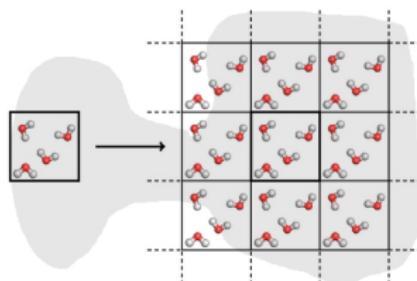


- Central box \Rightarrow infinite lattice
- Periodic image in each box moves in the same way
- If a molecule leaves a box, one of its images will enter through the opposite face
- The number density in all boxes is constant
- Only $(\mathbf{r}_i, \mathbf{p}_i)$ of the molecules in the central box are stored



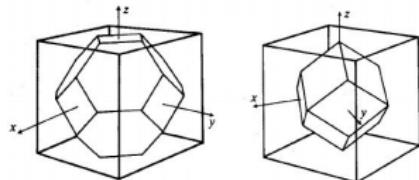


Periodic boundary conditions



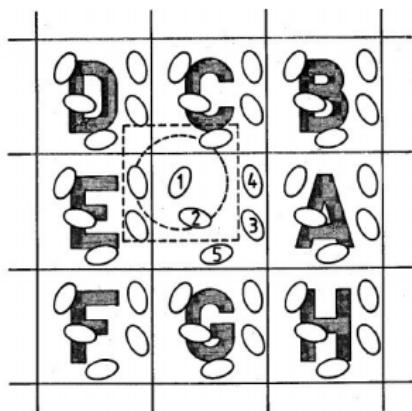
- Special conditions { Phase transitions
Supercritical fluids
- Test ⇒ increase box size
- Other boxes ⇒ space filling polyhedra

{ Rombic dodecahedron
Truncated octahedron





Periodic boundary conditions

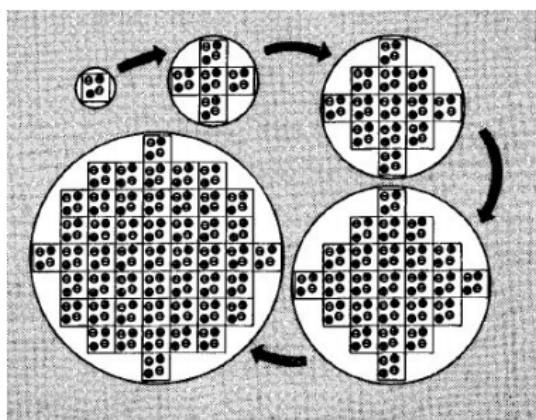


- Infinite number of interactions (potential energy and forces)
- Minimum Image Convention \Rightarrow each molecule interacts with the closest periodic image of the other $N - 1$ molecules
- Define a box centered in molecule 1 \Rightarrow interacts with $2, 3_E, 4_E$, and 5_C
- Pairwise-additive interactions $\Rightarrow \frac{1}{2} N(N - 1)$ terms



Long-range interactions

Ewald summation



X. Quian and T. Schlick, Journal of Chemical Physics 116, 5971 (2002)

$$V = \frac{1}{2} \sum_{\mathbf{n}} \sum'_{i,j} \frac{q_i q_j}{|\mathbf{r}_{ij} + \mathbf{n}|}$$

$$\mathbf{n} = (n_x L, n_y L, n_z L)$$

$$\sum' \Rightarrow \underline{i=j}, \underline{\mathbf{n}=0}$$

$$\begin{aligned} \gamma^{zz}(\varepsilon_s = 1) = & \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \left(\sum_{|\mathbf{n}|=0}^{\infty} z_i z_j \frac{\operatorname{erfc}(\kappa |\mathbf{r}_{ij} + \mathbf{n}|)}{|\mathbf{r}_{ij} + \mathbf{n}|} \right. \\ & + (1/\pi L^3) \sum_{\mathbf{k} \neq 0} z_i z_j (4\pi^2/k^2) \exp(-k^2/4\kappa^2) \cos(\mathbf{k} \cdot \mathbf{r}_{ij}) \Big) \\ & - (\kappa/\pi^{1/2}) \sum_{i=1}^N z_i^2 + (2\pi/3L^3) \left| \sum_{i=1}^N z_i \mathbf{r}_i \right|^2. \end{aligned}$$



Hamilton's equations

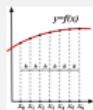
- Newton's second law

$$\mathbf{F}_i = m_i \mathbf{a}_i = m_i \frac{d^2 \mathbf{r}_i}{dt^2} \Rightarrow \text{Second order differential equation}$$

- Hamilton's equations

$$\begin{aligned} \dot{\mathbf{r}}_i &= \mathbf{p}_i / m_i \\ \dot{\mathbf{p}}_i &= \mathbf{F}_i \end{aligned} \quad \left. \right\} \Rightarrow \text{Coupled first order differential equations}$$

- Equivalent formulations $\Rightarrow \mathbf{F}_i = \dot{\mathbf{p}}_i = m_i \ddot{\mathbf{r}}_i = m_i \mathbf{a}_i$
- Forces $\Rightarrow \mathbf{F}_i = -\nabla_{\mathbf{r}_i} V = -\left(\frac{\partial V}{\partial x_i}, \frac{\partial V}{\partial y_i}, \frac{\partial V}{\partial z_i}\right)$



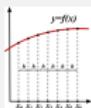
Verlet algorithm

$$\mathbf{r}(t) = \mathbf{r}(t_0) + \underbrace{\dot{\mathbf{r}}(t_0)}_{\mathbf{v}(t_0)}(t - t_0) + \frac{1}{2} \underbrace{\ddot{\mathbf{r}}(t_0)}_{\mathbf{a}(t_0)}(t - t_0)^2 + \mathcal{O}((t - t_0)^3)$$

$$= \mathbf{r}(t_0) + \mathbf{v}(t_0)(t - t_0) + \frac{1}{2} \mathbf{a}(t_0)(t - t_0)^2 \quad (1)$$

$$\mathbf{r}(t \pm \delta) = \mathbf{r}(t_0) + \mathbf{v}(t_0)(t \pm \delta - t_0) + \frac{1}{2} \mathbf{a}(t_0)(t \pm \delta - t_0)^2 \quad (2)$$

$$\begin{aligned}
 (1), (2) \Rightarrow & \mathbf{r}(t+\delta) + \mathbf{r}(t-\delta) - 2\mathbf{r}(t) = \cancel{\mathbf{r}(t_0)} + \cancel{\mathbf{v}(t_0)(t+\delta-t_0)} + \frac{1}{2} \mathbf{a}(t_0)(t+\delta-t_0)^2 \\
 & + \cancel{\mathbf{r}(t_0)} + \cancel{\mathbf{v}(t_0)(t-\delta-t_0)} + \frac{1}{2} \mathbf{a}(t_0)(t-\delta-t_0)^2 \\
 & - 2\cancel{\mathbf{r}(t_0)} - 2\cancel{\mathbf{v}(t_0)(t-t_0)} - \mathbf{a}(t_0)(t-t_0)^2 \\
 & = \frac{1}{2} \mathbf{a}(t_0)((t-t_0)^2 + \delta^2 + 2(t-t_0)\delta) \\
 & + \frac{1}{2} \mathbf{a}(t_0)((t-t_0)^2 + \delta^2 - 2(t-t_0)\delta) \\
 & - \cancel{\mathbf{a}(t_0)(t-t_0)^2} = \mathbf{a}(t_0)\delta^2
 \end{aligned}$$



Verlet algorithm

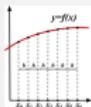
$$\mathbf{r}(t + \delta) = 2\mathbf{r}(t) - \mathbf{r}(t - \delta) + \mathbf{a}(t_0)\delta^2$$

$$\boxed{\mathbf{r}(t_0 + \delta) = 2\mathbf{r}(t_0) - \mathbf{r}(t_0 - \delta) + \mathbf{a}(t_0)\delta^2} \Leftarrow \text{Verlet}$$

$$(1) \Rightarrow \dot{\mathbf{r}}(t) = \mathbf{v}(t) = \mathbf{v}(t_0) + \mathbf{a}(t_0)(t - t_0) \quad (3)$$

$$\begin{aligned}
 \mathbf{r}(t+\delta) - \mathbf{r}(t-\delta) &= \cancel{\mathbf{r}(t_0)} + \mathbf{v}(t_0)(t+\delta-t_0) + \frac{1}{2}\mathbf{a}(t_0)(t+\delta-t_0)^2 \\
 &\quad - \cancel{\mathbf{r}(t_0)} - \mathbf{v}(t_0)(t-\delta-t_0) - \frac{1}{2}\mathbf{a}(t_0)(t-\delta-t_0)^2 \\
 &= 2\mathbf{v}(t_0)\delta + \frac{1}{2}\mathbf{a}(t_0)\left(\cancel{(t-t_0)^2} + \cancel{\delta^2} + 2(t-t_0)\delta - \cancel{(t-t_0)^2} - \cancel{\delta^2} + 2(t-t_0)\delta\right) \\
 &= 2\mathbf{v}(t_0)\delta + 2\mathbf{a}(t_0)(t-t_0)\delta = 2\mathbf{v}(t)\delta \\
 \mathbf{v}(t) &= \frac{\mathbf{r}(t+\delta) - \mathbf{r}(t-\delta)}{2\delta}
 \end{aligned}$$

$$\boxed{\mathbf{v}(t_0) = \frac{\mathbf{r}(t_0+\delta) - \mathbf{r}(t_0-\delta)}{2\delta}} \Leftarrow \text{Verlet}$$



Leap-frog algorithm

$$(3) \text{ with } t \rightarrow t_0 + \frac{\delta}{2} \Rightarrow \mathbf{v}(t_0 + \frac{\delta}{2}) = \mathbf{v}(t_0) + \mathbf{a}(t_0)(t_0 + \frac{\delta}{2} - t_0) = \mathbf{v}(t_0) + \frac{1}{2} \mathbf{a}(t_0) \delta \quad (4)$$

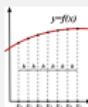
$$\begin{aligned} (2) \text{ with } t \rightarrow t_0 \Rightarrow \mathbf{r}(t_0 + \delta) &= \mathbf{r}(t_0) + \mathbf{v}(t_0) \delta + \frac{1}{2} \mathbf{a}(t_0) \delta^2 \\ &= \mathbf{r}(t_0) + \delta \left(\mathbf{v}(t_0) + \frac{1}{2} \mathbf{a}(t_0) \delta \right) \\ &= \mathbf{r}(t_0) + \mathbf{v}(t_0 + \frac{\delta}{2}) \delta \end{aligned}$$

(4)

$$\boxed{\mathbf{r}(t_0 + \delta) = \mathbf{r}(t_0) + \mathbf{v}(t_0 + \frac{\delta}{2}) \delta} \Leftarrow \text{Leap-frog}$$

$$\left. \begin{array}{l} (4) \Rightarrow \mathbf{v}(t_0 + \frac{\delta}{2}) = \mathbf{v}(t_0) + \frac{1}{2} \mathbf{a}(t_0) \delta \\ (4) \text{ with } \delta \rightarrow -\delta \Rightarrow \mathbf{v}(t_0 - \frac{\delta}{2}) = \mathbf{v}(t_0) - \frac{1}{2} \mathbf{a}(t_0) \delta \end{array} \right\} \mathbf{v}(t_0 + \frac{\delta}{2}) - \mathbf{v}(t_0 - \frac{\delta}{2}) = \mathbf{a}(t_0) \delta$$

$$\boxed{\mathbf{v}(t_0 + \frac{\delta}{2}) = \mathbf{v}(t_0 - \frac{\delta}{2}) + \mathbf{a}(t_0) \delta} \Leftarrow \text{Leap-frog}$$



Other algorithms

$$\mathbf{r}(t_0 + \delta) = \mathbf{r}(t_0) + \mathbf{v}(t_0) \delta + \frac{1}{2} \mathbf{a}(t_0) \delta^2$$

$$\mathbf{v}(t_0 + \frac{\delta}{2}) = \mathbf{v}(t_0) + \frac{1}{2} \mathbf{a}(t_0) \delta$$

$$\mathbf{v}(t_0 + \delta) = \mathbf{v}(t_0 + \frac{\delta}{2}) + \frac{1}{2} \mathbf{a}(t_0 + \delta) \delta$$

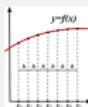
⇐ Velocity Verlet

$$\mathbf{r}(t_0 + \delta) = \mathbf{r}(t_0) + \mathbf{v}(t_0) \delta + \frac{2}{3} \mathbf{a}(t_0) \delta^2 - \frac{1}{6} \mathbf{a}(t_0 - \delta) \delta^2$$

$$\mathbf{v}(t_0 + \delta) = \mathbf{v}(t_0) + \frac{1}{3} \mathbf{a}(t_0 + \delta) \delta + \frac{5}{6} \mathbf{a}(t_0) \delta - \frac{1}{6} \mathbf{a}(t_0 - \delta) \delta$$

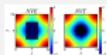
⇐ Beeman

Verlet, Leap-frog, velocity Verlet, Beeman, ... ⇒ Similar global errors



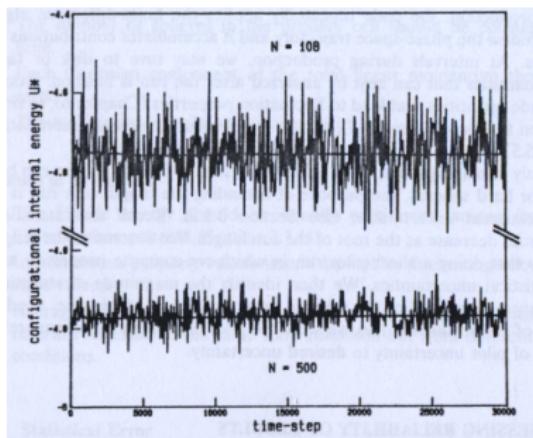
References

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NVE ensemble

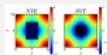
- NVE ensemble $\Rightarrow \begin{cases} N/V \rightarrow \text{density} \\ E \text{ constant} \rightarrow \text{Hamilton's equations} \end{cases}$



$$E = \frac{\mathbf{p}^2}{2m} + V(\mathbf{r})$$

$$\dot{E} = \frac{2\mathbf{p} \cdot \dot{\mathbf{p}}}{2m} + \dot{V}(\mathbf{r}) = \frac{\mathbf{p} \cdot \dot{\mathbf{p}}}{m} + \nabla_{\mathbf{r}} V \cdot \dot{\mathbf{r}}$$

$$= \frac{\mathbf{p}}{m} \cdot (\dot{\mathbf{p}} + \nabla_{\mathbf{r}} V) = 0 \Rightarrow \dot{\mathbf{p}} = -\nabla_{\mathbf{r}} V$$



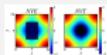
NVT ensemble

- Equilibrium \Rightarrow degree of freedom $\Rightarrow \frac{1}{2} k_{\text{B}} T$
- Temperature $\Rightarrow K = \sum_{i=1}^N \frac{1}{2} m_i \mathbf{v}_i^2 = 3N \left(\frac{1}{2} k_{\text{B}} T \right) \Rightarrow T = \frac{2K}{3Nk_{\text{B}}}$
- Scaling

$$\left. \begin{array}{l} K = \sum_{i=1}^N \frac{1}{2} m_i \mathbf{v}_i^2 = 3N \left(\frac{1}{2} k_{\text{B}} T \right) \\ \sum_{i=1}^N \frac{1}{2} m_i \mathbf{v}'_i^2 = 3N \left(\frac{1}{2} k_{\text{B}} T_f \right) \end{array} \right\} \frac{\sum_i m_i \mathbf{v}_i^2}{\sum_i m_i \mathbf{v}'_i^2} = \frac{T}{T_f} \rightarrow \sum_i m_i \mathbf{v}_i^2 = \sum_i m_i \mathbf{v}'_i^2 \frac{T}{T_f}$$

$$\mathbf{v}_i^2 = \mathbf{v}'_i^2 \frac{T}{T_f}$$

$$\mathbf{v}'_i = \frac{T_f}{T} \mathbf{v}_i$$



NVT ensemble

- Coupling to a external bath [Berendsen 1984]

$$\mathbf{v}'_i = \lambda \mathbf{v}_i \rightarrow \lambda = \sqrt{1 + \frac{\Delta t}{\tau} \left(\frac{T_f}{T} - 1 \right)}$$

- Other thermostats (Nose-Hoover, ...)
- Equilibration (*NVT*) - Production (*NVE*)
- Other emsembles (*NPT*, ...)



Conservation principles

- Mass $\Rightarrow M = \sum_i m_i$
- Energy $\Rightarrow E = \sum_i \frac{\mathbf{p}_i^2}{2m_i} + V(\mathbf{r}_i)$

- Linear momentum $\Rightarrow \sum_i \mathbf{p}_i = 0$

- Angular momentum $\Rightarrow \sum_i \mathbf{r}_i \times \mathbf{p}_i = 0$

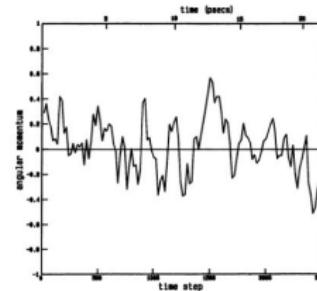


FIGURE 2.15 Fluctuations in the y-component of the angular momentum $\mathcal{J}_y(t) = \sum_i^N (z_i \dot{x}_i - \dot{z}_i x_i)$, computed during a molecular dynamics simulation of 108 Lennard-Jones atoms at $\rho\sigma^3 = 0.7$, $kT/\epsilon = 1$. Units are σ for position and $(m/e)^{1/2}$ for velocity. Values are plotted at intervals of 20 integration time-steps; using potential parameters for argon, 20 time-steps = 0.172 picsec.



Maxwell-Boltzmann distribution

- Velocity distribution

$$\rho(v_x) = \sqrt{\frac{m}{2\pi k_B T}} e^{-\frac{1}{2}mv_x^2/k_B T} \Leftarrow \int_{-\infty}^{\infty} \rho(v_x) dv_x = 1$$

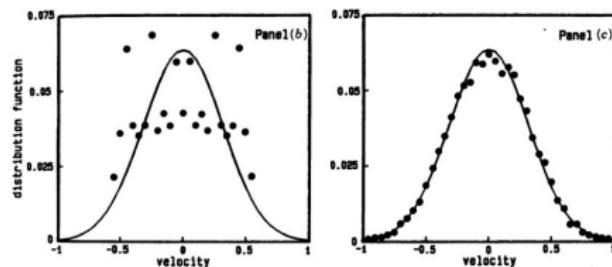


FIGURE 3.9 Approach to equilibrium for the 256-hard-sphere simulation described in Figure 3.7. (a) Same as Figure 3.8(a). (b) The velocity distribution $f(v_x)dv_x$ averaged over the first 5000 collisions of the run (points) compared to the Maxwell distribution (line) at the same kinetic energy. (c) The velocity distribution $f(v_x)dv_x$ averaged over collisions 6000–11,000 of the run (points) compared to the Maxwell distribution (line).



Static properties

- Time average

$$\langle A \rangle = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^\tau A(t) dt \approx \frac{1}{M} \sum_{k=1}^M A(t_k)$$

- Fluctuations

$$\delta A = A - \langle A \rangle$$

$$\begin{aligned}\langle (\delta A)^2 \rangle &= \langle (A - \langle A \rangle)^2 \rangle \\ &= \langle A^2 \rangle - 2 \langle A \rangle \langle A \rangle + \langle A \rangle^2 \\ &= \langle A^2 \rangle - \langle A \rangle^2\end{aligned}$$



Static properties

- Pressure

$$P = \rho k_B T + \frac{\langle W \rangle}{V}$$

$$W = \frac{1}{3} \sum_i^N \mathbf{r}_i \cdot \mathbf{F}_i \rightarrow \text{internal virial}$$

- Heat capacity $\Rightarrow C_V = (\frac{\partial E}{\partial T})_V \rightarrow C_V^* = (1 - \frac{2}{3NT^{*2}} \langle (\delta K^*)^2 \rangle)^{-1}$
- Adiabatic compressibility $\Rightarrow \kappa = -\frac{1}{V} (\frac{\partial V}{\partial P})_S$

$$\kappa^* = (7P^* - \frac{16}{3}\rho^*T^* - 8\rho^*U^* - \frac{N}{\rho^*}T^*\langle(\delta P^*)^2\rangle)^{-1}$$

- Thermal pressure coefficient $\Rightarrow \gamma = (\frac{\partial P}{\partial T})_V$

$$\gamma^* = \frac{2}{3} C_V^* \left(\rho^* - \frac{1}{T^{*2}} \langle \delta K^* \delta P^* \rangle \right)$$



Static properties

- Radial distribution function $g(r)$

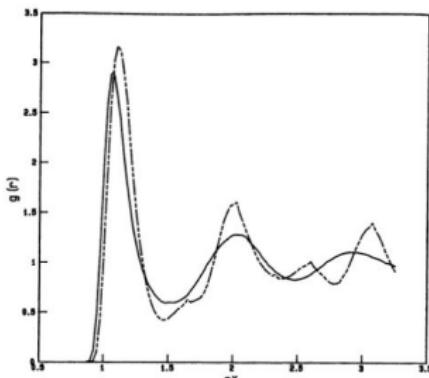


FIGURE 6.22 The radial distribution function $g(r)$ may often be used to distinguish a fluid state (continuous line) from a metastable solidlike state (broken line). These curves are from simulations that used the Lennard-Jones potential with 256 atoms at a density of $\rho\sigma^3 = 0.9$. The fluid state was at $kT/\epsilon = 1.087$, while the metastable state was at $kT/\epsilon = 0.80$. See Figure 5.7 for the location of these states on the Lennard-Jones phase diagram.

$$g(r) = \frac{\rho(r)}{\rho}$$

$$r \in (R, R + \delta) \rightarrow V = \frac{4}{3} \pi ((R + \delta)^3 - R^3)$$

$$\rho(R) = \frac{n(R)}{V}$$



Dynamic properties

- Time correlation functions

$$\begin{aligned}\langle A(t_0) B(t_0 + t) \rangle &= \langle A(0) B(t) \rangle = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_0^{\tau} A(t_0) B(t_0 + t) dt_0 \\ &\simeq \frac{1}{M} \sum_{k=1}^M A(t_k) B(t_k + t)\end{aligned}$$

- Limits $\langle A(0) B(t) \rangle$

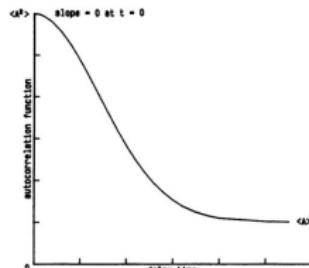


FIGURE 7.2 An autocorrelation function $\langle A(0)A(t) \rangle$ is initially equal to $\langle A^2 \rangle$, but as the delay time grows, it decays, initially with zero slope, to $\langle AB \rangle$.

$$t = 0 \Rightarrow \langle AB \rangle \simeq \frac{1}{M} \sum_{k=1}^M A(t_k) B(t_k)$$

$$t \rightarrow \infty \Rightarrow \langle A \rangle \langle B \rangle \text{ (uncorrelated)}$$



Dynamic properties

- Transport coefficients

$$\text{Flux} = -\text{coefficient} \times \text{gradient}$$

Fick's law $\Rightarrow N\dot{x} = -D \frac{\partial N}{\partial x}$ { $N(x, t) \rightarrow$ number atoms/unit volume
 $\dot{x}(x, t) \rightarrow$ local velocity

TABLE 7.1 Generalized Einstein and Green–Kubo Formulas for Self-Diffusion Coefficient, Shear, and Longitudinal Viscosity

$$K = \lim_{t \rightarrow \infty} \langle [A(t) - A(0)]^2 \rangle / 2t = \int_0^\infty d\tau \langle \dot{A}(\tau) \dot{A}(0) \rangle$$

| K | $A(t)$ | $\dot{A}(t)$ |
|---|----------------------------------|---|
| Self-diffusion coefficient D | $x_i(t)$ | $\dot{x}_i(t)$ |
| Shear viscosity $\eta V kT$ | $m \sum_i^N \dot{x}_i(t) y_i(t)$ | $m \sum_i^N \dot{x}_i(t) \dot{y}_i(t) + \sum_{i < j}^N y_{ij}(t) F_{ijx}(t)$ |
| Longitudinal viscosity ^a $(\frac{4}{3}\eta + \zeta) V kT$ | $m \sum_i^N \dot{x}_i(t) x_i(t)$ | $m \sum_i^N \dot{x}_i(t) \dot{x}_i(t) + \sum_{i < j}^N x_{ij}(t) F_{ijx}(t) - PV$ |

^a ζ is the bulk viscosity.