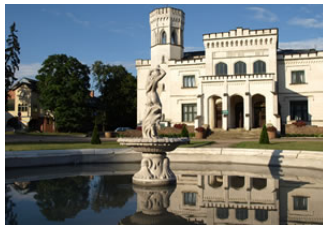


Stochastic comparisons of coherent systems and order statistics

J. Navarro¹, Universidad de Murcia (Spain)



¹Supported by Ministerio de Economía y Competitividad under Grant MTM2012-34023-FEDER.

Outline

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 - Proportional hazard rate model
 - Order statistics
 - Coherent systems
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 - Comparison results
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 - Representations
 - Comparison results
 - Examples

Distortion functions

- The distorted distributions were introduced in Yaari's dual theory of choice under risk (Econometrica 55 (1987):95–115).
- The **distorted distribution** (DD) associated to a distribution function (DF) F and to an increasing continuous **distortion function** $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (1.1)$$

- For the reliability functions (RF) $\bar{F} = 1 - F$, $\bar{F}_q = 1 - F_q$, we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (1.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the **dual distortion function**; see Hürlimann (2004, N Am Actuarial J).

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Multivariate distortion functions

- The **generalized distorted distribution** (GDD) associated to n DF F_1, \dots, F_n and to an increasing continuous **multivariate distortion function** $Q : [0, 1]^n \rightarrow [0, 1]$ such that $Q(0, \dots, 0) = 0$ and $Q(1, \dots, 1) = 1$, is

$$F_Q(t) = Q(F_1(t), \dots, F_n(t)). \quad (1.3)$$

- For the RF we have

$$\bar{F}_Q(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t)), \quad (1.4)$$

where $\bar{F} = 1 - F$, $\bar{F}_Q = 1 - F_Q$ and $\bar{Q}(u_1, \dots, u_n) = 1 - Q(1 - u_1, \dots, 1 - u_n)$ is the **multivariate dual distortion function**; see Navarro et al. (JAP, 2011).

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Proportional hazard rate (PHR) model

- The PHR (Cox) model associated to a RF \bar{F} is

$$\bar{F}_\alpha(t) = (\bar{F}(t))^\alpha = \bar{q}(\bar{F}(t))$$

for $\alpha > 0$. F_α is a DD with $\bar{q}(u) = u^\alpha$ and $q(u) = 1 - (1 - u)^\alpha$.

- The proportional reversed hazard rate (PRHR) model is

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Order statistics (OS)

- X_1, \dots, X_n IID $\sim F$ random variables.
- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the DF, then

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.5)$$

(see David and Nagaraja 2003, p. 46) where

$$F_{j:j}(t) = \Pr(X_{j:j} \leq t) = \Pr(\max(X_1, \dots, X_j) \leq t) = F^j(t)$$

and

$$q_{i:n}(u) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} u^j$$

is a strictly increasing polynomial in $[0, 1]$.

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Coherent systems- IID case

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n s_i \bar{F}_{i:n}(t), \quad (1.6)$$

where $s_i = \Pr(T = X_{i:n})$.

- $\mathbf{s} = (s_1, \dots, s_n)$ is the signature of the system.
- Then T has a DD from F with

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Coherent systems- INID case

- Consider an n -component system with components of r different types. Suppose that the system has m_k components of type k , where $k = 1, \dots, r$. Assume that the lifetimes of components of the same type are exchangeable and that the lifetimes of components of different types are independent. Then the *survival signature* of the system is a nonnegative function ϕ of r variables, where $\phi(i_1, \dots, i_r)$ for $i_k = 0, \dots, m_k$ and $k = 1, \dots, r$, represents the probability that the system works when precisely i_k components of type k are working for $k = 1, \dots, r$.
- Coolen and Coolen-Maturi (2012), IND components:

$$\bar{F}_T(t) = \sum_{i_1=0}^{m_1} \cdots \sum_{i_r=0}^{m_r} \phi(i_1, \dots, i_r) \prod_{k=1}^r \binom{m_k}{i_k} F_k^{m_k - i_k}(t) \bar{F}_k^{i_k}(t). \quad (1.8)$$

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- Then

$$\bar{F}_T(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_r(t)) \quad (1.9)$$

where \bar{Q} is a multinomial.

- If $r = 1$, \bar{Q} is the domination polynomial.
- If $r = n$, then \bar{Q} is the **reliability function of the structure**; see Barlow and Proschan (1975, p. 21).

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Coherent systems-GENERAL case

- A **path set** of T is a set $P \subseteq \{1, \dots, n\}$ such that if all the components in P work, then the system works.
- A **minimal path set** of T is a path set which does not contain other path sets.
- If P_1, \dots, P_m are the minimal path sets of T , then $T = \max_{j=1, \dots, m} X_{P_j}$, where $X_P = \min_{i \in P} X_i$ and

$$\begin{aligned} \bar{F}_T(t) &= \Pr \left(\max_{j=1, \dots, m} X_{P_j} > t \right) = \Pr \left(\bigcup_{j=1}^m \{X_{P_j} > t\} \right) \\ &= \sum_{i=1}^m \bar{F}_{P_i}(t) - \sum_{i \neq j} \bar{F}_{P_i \cup P_j}(t) + \dots \pm \bar{F}_{P_1 \cup \dots \cup P_m}(t) \end{aligned}$$

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Coherent systems-GENERAL case

- The copula representation for the RF of (X_1, \dots, X_n) is

$$\bar{\mathbf{F}}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$ and K is the survival copula.

- Then

$$\bar{F}_P(t) = \bar{Q}_{P,K}(\bar{F}_1(t), \dots, \bar{F}_n(t)),$$

where $\bar{Q}_{P,K}(u_1, \dots, u_n) = K(u_1^P, \dots, u_n^P)$ and $u_i^P = u_i$ for $i \in P$ and $u_i^P = 1$ for $i \notin P$.

- Therefore, from the minimal path set repres., we get

$$\bar{F}_T(t) = \bar{Q}_{\phi,K}(\bar{F}_1(t), \dots, \bar{F}_n(t)).$$

- In the ID case $\bar{F}_T(t) = \bar{q}_{\phi,K}(\bar{F}(t))$.

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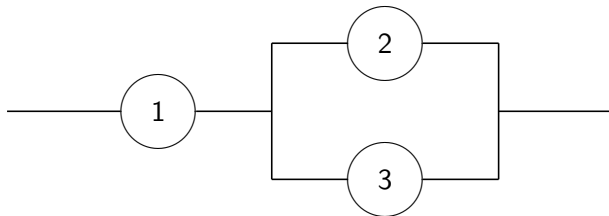
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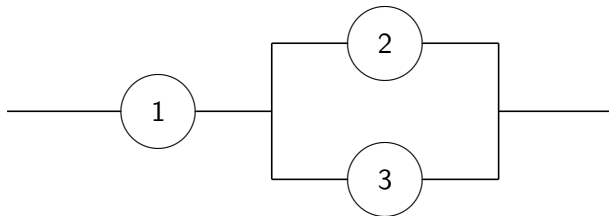


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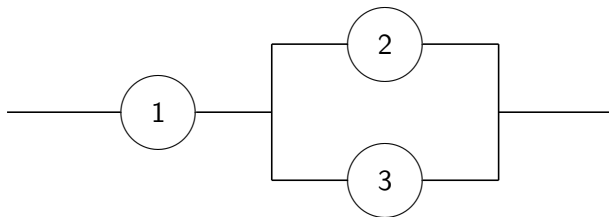
Coherent system lifetime $T = \min(X_1, \max(X_2, X_3))$.

Example



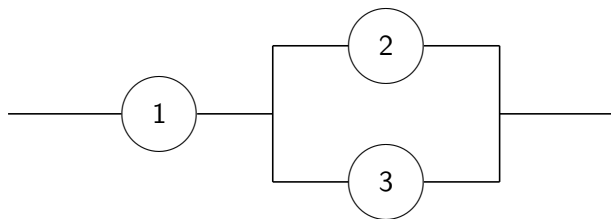
IID \bar{F} cont.: $\mathbf{s} = (2/6, 4/6, 0) = (1/3, 2/3, 0)$.

Example



$$\text{IID } \bar{F} \text{ cont.: } \bar{F}_T(t) = \frac{1}{3}\bar{F}_{1:3}(t) + \frac{2}{3}\bar{F}_{2:3}(t).$$

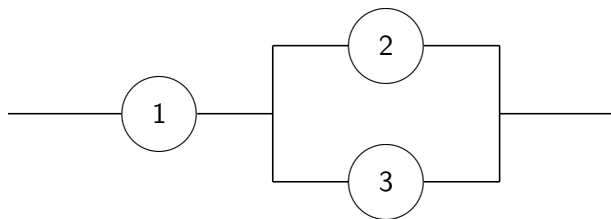
Example-general case



Coherent system lifetime $T = \max(\min(X_1, X_2), \min(X_1, X_3))$

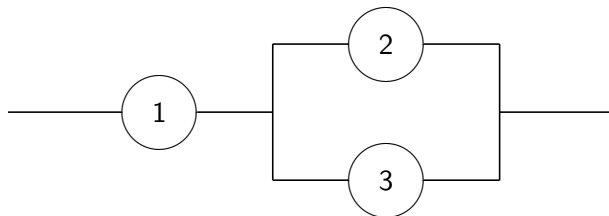
Minimal path sets $P_1 = \{1, 2\}$ and $P_2 = \{1, 3\}$.

Example-general case



$$\begin{aligned}\bar{F}_T(t) &= \Pr(\{X_{\{1,2\}} > t\} \cup \{X_{\{1,3\}} > t\}) \\ &= \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) - \bar{F}_{\{1,2,3\}}(t).\end{aligned}$$

Example-general case

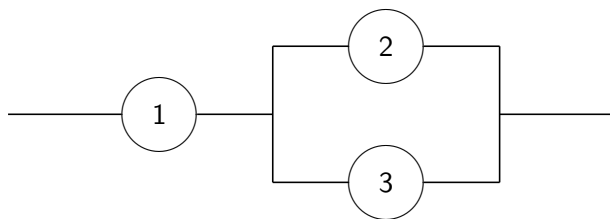


$$\bar{F}_{\{1,2\}}(t) = \bar{F}(t, t, 0) = K(\bar{F}_1(t), \bar{F}_2(t), 1), \dots$$

$$\bar{F}_T(t) = \bar{Q}_{\phi, K}(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)) \text{ where}$$

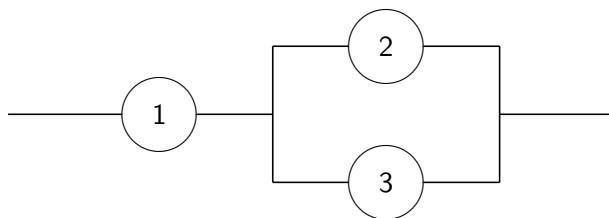
$$\bar{Q}_{\phi, K}(u_1, u_2, u_3) = K(u_1, u_2, 1) + K(u_1, 1, u_3) - K(u_1, u_2, u_3).$$

Example-general case



ID: $\bar{F}_T(t) = \bar{q}_{\phi, \kappa}(\bar{F}(t))$,
where $\bar{q}_{\phi, \kappa}(u) = K(u, u, 1) + K(u, 1, u) - K(u, u, u)$.

Example-general case



IID: $\bar{F}_T(t) = 2\bar{F}^2(t) - \bar{F}^3(t) = q_\phi(\bar{F}(t))$,
where $\bar{q}_\phi(u) = 2u^2 - u^3$ and $\mathbf{a} = (0, 2, -1)$.

Example IND components

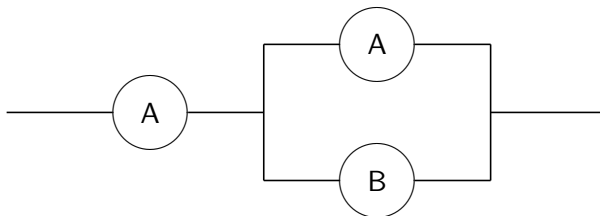


Figure: System 1.

$$\phi(0, 0) = \phi(1, 0) = \phi(0, 1) = 0$$

Example IND components

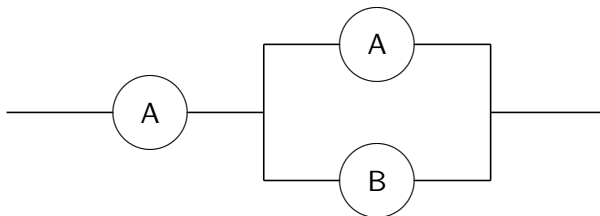


Figure: System 1.

$$\phi(1, 1) = 1/2$$

Example IND components

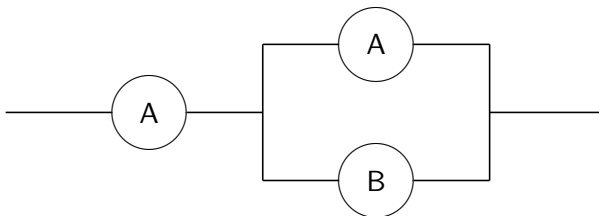


Figure: System 1.

$$\phi(2, 0) = \phi(2, 1) = 1$$

Example IND components

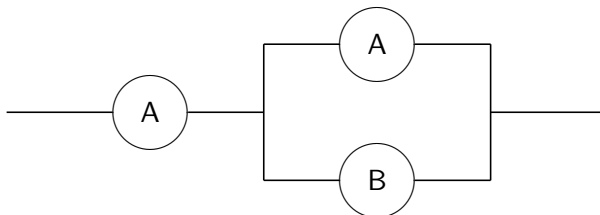


Figure: System 1.

$$\bar{F}_{T_1}(t) = \phi(1, 1) \binom{2}{1} F_A^{2-1}(t) \bar{F}_A^1(t) \binom{1}{1} F_B^{1-1}(t) \bar{F}_B^1(t) + \dots$$

Example IND components

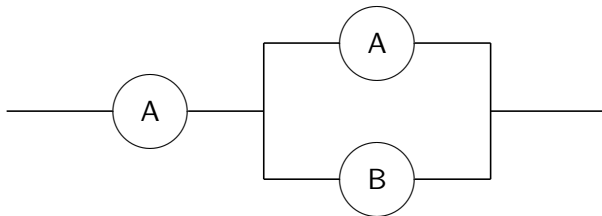


Figure: System 1.

$$\bar{F}_{T_1}(t) = F_A(t)\bar{F}_A(t)\bar{F}_B(t) + \bar{F}_A^2(t)F_B(t) + \bar{F}_A^2(t)\bar{F}_B(t), \text{ i.e.,}$$

$$\bar{F}_{T_1}(t) = \bar{F}_A^2(t) + \bar{F}_A(t)\bar{F}_B(t) - \bar{F}_A^2(t)\bar{F}_B(t)$$

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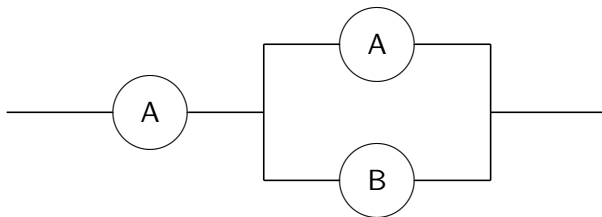


Figure: System 1.

$\bar{F}_{T_1}(t) = \bar{Q}_{\phi, K}(\bar{F}_A(t), \bar{F}_A(t), \bar{F}_B(t))$, where

$$\bar{Q}_{\phi, K}(u_1, u_2, u_3) = K(u_1, u_2, 1) + K(u_1, 1, u_3) - K(u_1, u_2, u_3).$$

Example IND components

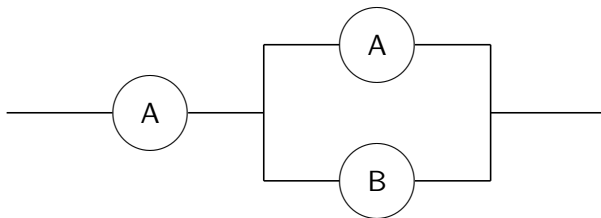


Figure: System 1.

INID: $\bar{F}_{T_1}(t) = \bar{Q}_1(\bar{F}_A(t), \bar{F}_B(t))$, where

$$\bar{Q}_1(u_1, u_2) = u_1^2 + u_1 u_2 - u_1^2 u_2.$$

Example IND components

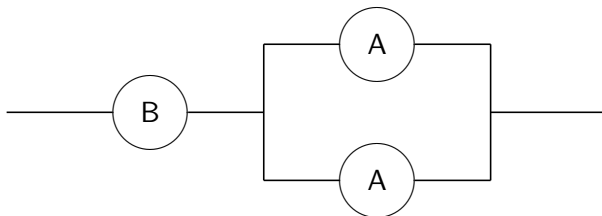


Figure: System 2.

$\bar{F}_{T_2}(t) = \bar{Q}_{\phi, K}(\bar{F}_B(t), \bar{F}_A(t), \bar{F}_A(t))$, where

$$\bar{Q}_{\phi, K}(u_1, u_2, u_3) = K(u_1, u_2, 1) + K(u_1, 1, u_3) - K(u_1, u_2, u_3).$$

Example IND components

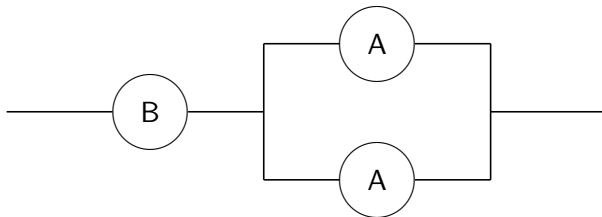


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INID: $\bar{F}_{T_2}(t) = \bar{Q}_2(\bar{F}_A(t), \bar{F}_B(t))$, where

$$\bar{Q}_2(u_1, u_2) = 2u_1u_2 - u_1^2u_2.$$

Comparison results-DD

- If q_1 and q_2 are two DF,

$$q_1(F) \leq_{ord} q_2(F) \text{ for all } F?$$

- If q is a DF,

$$F \leq_{ord} G \Rightarrow q(F) \leq_{ord} q(G)?$$

- If Q_1 and Q_2 are two MDF,

$$Q_1(F_1, \dots, F_n) \leq_{ord} Q_2(F_1, \dots, F_n)?$$

- If Q is a MDF,

$$F_i \leq_{ord} G_i, i = 1, \dots, n, \Rightarrow Q(F_1, \dots, F_n) \leq_{ord} Q(G_1, \dots, G_n)?$$

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Main stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$, stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$ for all t .
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{RHR} Y \Leftrightarrow (t - X|X < t) \geq_{ST} (t - Y|Y < t)$ for all t .
- Then

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Preservation of stochastic orders-DD

- If T_i has the RF $\bar{q}_i(\bar{F}(t))$, $i = 1, 2$, then:
 - $T_1 \leq_{ST} T_2$ for all F if and only if $\bar{q}_2 - \bar{q}_1 \geq 0$ in $(0, 1)$.
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Preservation of stochastic orders-GDD

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Preservation of stochastic orders-GDD

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Open questions

- If T_i has RF $\bar{Q}_i(\bar{F}_1, \dots, \bar{F}_r)$, $i = 1, 2$, then:
- $T_1 \leq_{MRL} T_2$ for all $\bar{F}_1, \dots, \bar{F}_r$ if and only if ??? (also in the case $r = 1$).
- $T_1 \leq_{LR} T_2$ for all $\bar{F}_1, \dots, \bar{F}_r$ if and only if ????
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- Some bounds for mixture representations were obtained in:
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Mixture representation for the case $r = 2$.

- Recently, Serkan Eryilmaz (2015, NAVAL RESEARCH LOGISTICS 62, 388–394) proved that if $r = 2$ and the components are independent, then

$$\bar{F}(t) = \sum_{i=0}^{m_1} \sum_{j=0}^{m_2} c(i, j) \bar{F}_{m_1-i+1:m_1}^A(t) \bar{F}_{m_2-j+1:m_2}^B(t),$$

where $X_{m_1-i+1:m_1}^A(t)$ is the $m_1 - i + 1$ order statistics between the components of type 1, $X_{m_2-j+1:m_2}^B(t)$ is the $m_2 - j + 1$ order statistics between the components of type 2 and

$$c(i, j) = \phi(i, j) - \phi(i, j - 1) - \phi(i - 1, j) + \phi(i - 1, j - 1)$$

(by convention $\phi(i, j) = 0$ if $i < 0$ or $j < 0$).

Residual lifetimes

- X_1, \dots, X_n component lifetimes with RF

$$\bar{F}_i(t) = \Pr(X_i > t).$$

- $T = \phi(X_1, \dots, X_n)$ system lifetime with RF

$$\bar{F}_T(t) = \Pr(T > t).$$

- We assume $\bar{F}_i(t) = \Pr(X_i > t) > 0$ and $\bar{F}_T(t) > 0$ for $t \geq 0$.
- Component residual lifetimes $X_{i,t} = (X_i - t | X_i > t)$ with RF:

$$\bar{F}_{i,t}(x) = \Pr(X_{i,t} > x) = \Pr(X_i - t > x | X_i > t) = \frac{\bar{F}_i(t+x)}{\bar{F}_i(t)}.$$

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- We have two main options to define the system residual lifetime at time $t > 0$:
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- Which one is the best system?
- Intuitively, it seems that T_t^* should be always better than T_t .
- It should be better to know that all the components are working at time t !
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see Pellerey and Petakos (IEEE Tr Rel, 2002) and Li and Lu (PEIS, 2003).

- Conditions on (X_1, \dots, X_n) to have (3.1) were given in Li, Pellerey and You (2013).
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$$\bar{F}_t(x) = \frac{\bar{F}_T(t+x)}{\bar{F}_T(t)} = \frac{\bar{Q}(\bar{F}_1(t+x), \dots, \bar{F}_n(t+x))}{\bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t))}.$$

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$$\bar{F}_t(x) = \frac{\bar{Q}(\bar{F}_1(t)\bar{F}_{1,t}(x), \dots, \bar{F}_n(t)\bar{F}_{n,t}(x))}{\bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t))},$$

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Parallel system with two components

- $T = \max(X_1, X_2)$.
- Minimal path sets $P_1 = \{1\}$ and $P_2 = \{2\}$.
- System reliability function:

$$\bar{F}_T(t) = \Pr(\max(X_1, X_2) > t) = \bar{F}_1(t) + \bar{F}_2(t) - \Pr(X_1 > t, X_2 > t).$$

- Then:

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Comparison results-System residual lifetimes

- The results for GDD can be applied to compare T_t and T_t^* .
For example:
 - $T_t \leq_{ST} T_t^*$ (\geq_{ST}) holds for all $\bar{F}_1, \dots, \bar{F}_n$ if and only if $\bar{Q}_t \leq \bar{Q}_t^*$ (\geq) in $(0, 1)^n$.
 - $T_t \leq_{HR} T_t^*$ (\geq_{HR}) for all $\bar{F}_1, \dots, \bar{F}_n$ if and only if \bar{Q}_t^*/\bar{Q}_t is decreasing (increasing) in $(0, 1)^n$.
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Example 1: Parallel system with two ID components

- $T = \max(X_1, X_2)$ where X_1 and X_2 have DF F .
- Then $\bar{F}_T(t) = \bar{q}(\bar{F}(t))$ where

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$$\bar{q}_t(u) = \bar{Q}_t(u, u) = \frac{\bar{q}(cu)}{\bar{q}(c)} = \frac{2cu - K(cu, cu)}{2c - K(c, c)},$$

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$$K(u, v) = \left(u^{-\theta} + v^{-\theta} - 1 \right)^{-1/\theta}, \quad \theta > 0,$$

then

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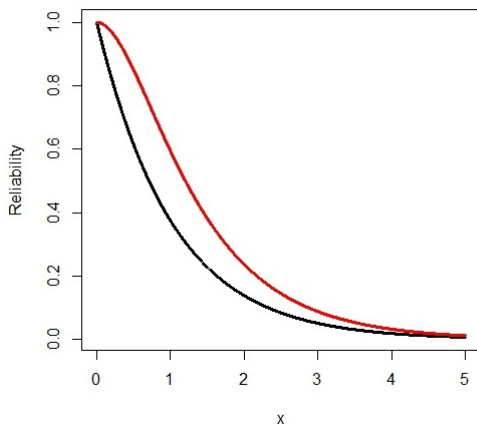


Figure: Reliability functions of T_t (black) and T_t^* (red) when $t = 1$, $\bar{F}(x) = e^{-x}$ and $\theta = 2$.

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- If K is the Gumbel-Barnett Archimedean copula

$$K(u, v) = uv \exp[-\theta(\ln u)(\ln v)], \quad \theta \in (0, 1], \quad (3.4)$$

then by plotting $\Psi(u)$, we see that it takes positive and negative values in the set $[0, 1]$ when $\theta = 1$.

- Therefore T_t and T_t^* are not ST ordered (for all F and t).
- These conditions lead to a Gumbel bivariate exponential with a negative correlation.
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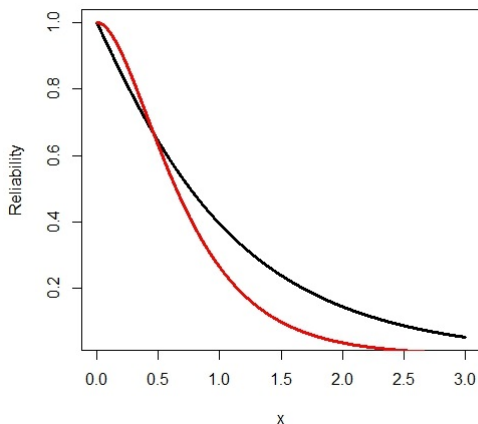


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- Now we can study if $T_t \leq_{MRL} T_t^*$ holds.
- By plotting the ratio $g(u) = \bar{q}_t(u)/\bar{q}_t^*(u)$ for $t = 1$ we see that it is first decreasing in $(0, u_0)$ and then increasing in $(u_0, 1]$ for a $u_0 \in (0, 1)$.

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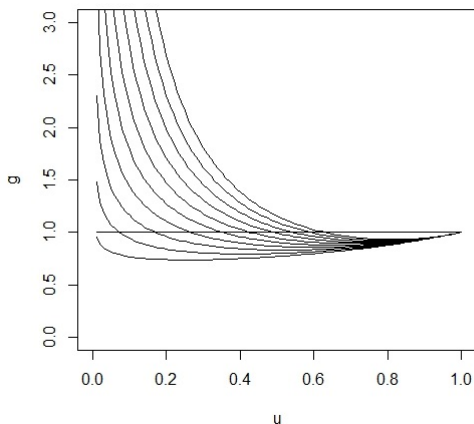


Figure: Ratio $g(u) = \bar{q}_t(u)/\bar{q}_t^*(u)$ for $t = 1$, $\bar{F}(x) = e^{-x}$ and $\theta = 0.1, 0.2, \dots, 1$ (from the bottom to the top).

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- Hence $T_t \geq_{MRL} T_t^*$ for all F such that $E(T_t) \geq E(T_t^*)$.
- For example, if $t = 1$, $\bar{F}(x) = e^{-x}$ and $\theta = 1$, then

$$E(T_t) = 1.05615 > E(T_t^*) = 0.77366.$$

- So $T_t \geq_{MRL} T_t^*$ for $t = 1$ and $\bar{F}(x) = e^{-x}$.

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- For example, if $t = 1$, $\bar{F}(x) = e^{-x}$ and $\theta = 1$, then

$$E(T_t) = 1.05615 > E(T_t^*) = 0.77366.$$

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Example 1: Gumbel-Barnett Archimedean copula

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Example 2: Parallel system with two INID components

- $T = \max(X_1, X_2)$, X_1, X_2 IND with DF F_1 and F_2 .
- Then

$$\begin{aligned}\bar{Q}(u_1, u_2) &= u_1 + u_2 - u_1 u_2 = \bar{Q}_t^*(u_1, u_2), \\ \bar{Q}_t(u_1, u_2) &= \frac{c_1 u_1 + c_2 u_2 - c_1 c_2 u_1 u_2}{c_1 + c_2 - c_1 c_2},\end{aligned}$$

where $c_1 = \bar{F}_1(t)$ and $c_2 = \bar{F}_2(t)$.

- $T_t \leq_{HR} T_t^*$ holds for all F_1, F_2 if and only if

$$\frac{\bar{Q}(u, v)}{\bar{Q}_t(u, v)} = \frac{(u + v - uv)(c_1 + c_2 - c_1 c_2)}{c_1 u + c_2 - c_1 c_2 uv}$$

is decreasing in u and v in the set $[0, 1]^2$.

- As this property is not true, they are not HR ordered.
- Therefore Theorem 3 in Li and Lu (PEIS, 2003) is not correct.

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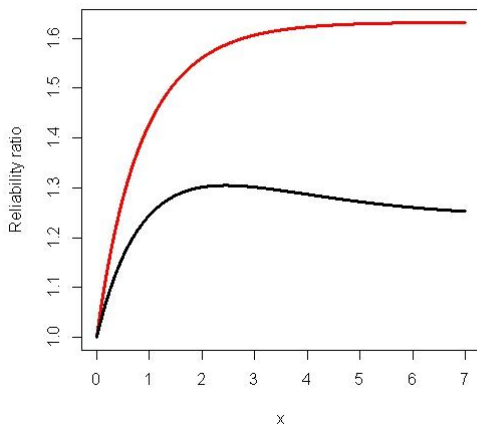


Figure: Ratio \bar{F}_t^*/\bar{F}_t for $t = 1$, $\bar{F}_1(x) = e^{-x}$ and $\bar{F}_2(x) = e^{-x/2}$ (black) or $\bar{F}_2(x) = e^{-x}$ (red).

Example 2: Parallel system with two INID components

- If X_1, X_2 are IID with DF F , then $T_t \leq_{HR} T_t^*$ holds for all F since

$$\frac{q(u)}{q_t(u)} = \frac{2-u}{2-u\bar{F}(t)} (2-\bar{F}(t))$$

is decreasing in u in the set $[0, 1]$.

- Even more, $T_t \leq_{LR} T_t^*$ holds since

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Example 3: Coherent system with DID components

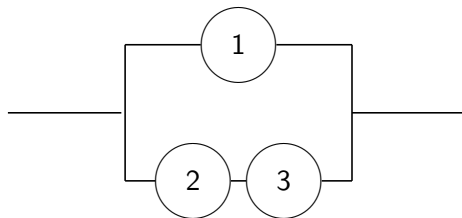


Figure: System in Example 3.

Example 3: Coherent system with DID components

- $T = \max(X_1, \min(X_2, X_3))$, X_1, X_2, X_3 DID with DF F .
- Then $P_1 = \{1\}$, $P_2 = \{2, 3\}$ and

$$q(u) = u + K(1, u, u) - K(u, u, u).$$

- Therefore $q_t(u) = q(cu)/q(c)$ and

$$q_t^*(u) = \frac{K(cu, c, c) + K(c, cu, cu) - K(cu, cu, cu)}{K(c, c, c)},$$

where $c = \bar{F}(t)$.

- We assume a Farlie-Gumbel-Morgenstern (FGM) copula

$$K(u, v, w) = uvw(1 + \theta(1 - u)(1 - v)(1 - w)), \quad \theta \in [-1, 1].$$

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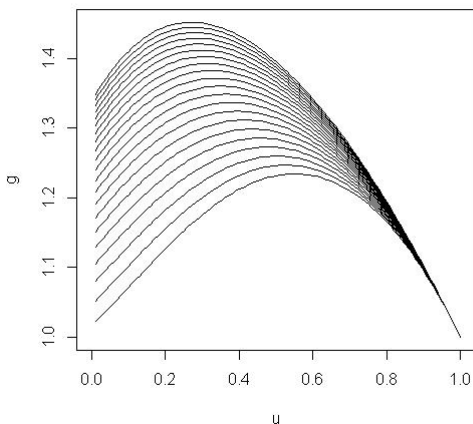


Figure: Ratio $g(u) = \bar{q}_t^*(u)/\bar{q}_t(u)$ for $t = 1$, $\bar{F}(x) = e^{-x}$ and $\theta = -1, -0.9, \dots, 1$ (from the bottom to the top).

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Open questions

- Representations and comparisons for

$$T_{t_1, \dots, t_r, t}^{(i_1, \dots, i_r)} = (T - t | H_{t_1, \dots, t_r, t}^{(i_1, \dots, i_r)}).$$

where $0 < r < n$, $0 < t_1 < \dots < t_r < t$, $\Pr(H_{t_1, \dots, t_r, t}^{(i_1, \dots, i_r)}) > 0$ and the event $H_{t_1, \dots, t_r, t}^{(i_1, \dots, i_r)}$ implies $T > t$. Some were obtained in the case of absolutely continuous distributions in Navarro and Durante (2015, submitted).

- Results for discrete distributions? Some results were obtained for k-out-of-n system in Dembinska (2015, Discrete Order Statistics for Non-Identically Distributed Variates with Applications to Reliability, MMR2015).
- Other reasonable cases $(T - t | H_t)$ where H_t implies $T > t$.

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References

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