

Applications of Generalized Distorted Distributions

Jorge Navarro¹,
Universidad de Murcia, Spain
E-mail: jorgenav@um.es

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Definition Distorted Distributions (DD)

- The distorted distributions were introduced in Yaari's dual theory of choice under risk (Econometrica 55 (1987):95–115).
- The *distorted distribution* (DD) associated to a distribution function (DF) F and to an increasing continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (1.1)$$

- If q is strictly increasing, then F and F_q have the same support.
- For the reliability functions (RF) $\bar{F} = 1 - F$, $\bar{F}_q = 1 - F_q$, we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (1.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*.

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Generalized Distorted Distributions (GDD)

- The *generalized distorted distribution* (GDD) associated to n DF F_1, \dots, F_n and to an increasing continuous *multivariate distortion function* $Q : [0, 1]^n \rightarrow [0, 1]$ such that $Q(0, \dots, 0) = 0$ and $Q(1, \dots, 1) = 1$, is

$$F_Q(t) = Q(F_1(t), \dots, F_n(t)). \quad (1.3)$$

- If Q is strictly increasing and F_1, \dots, F_n have the same support, then F_Q also has the same support.
- For the RF we have

$$\bar{F}_Q(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t)), \quad (1.4)$$

where $\bar{F} = 1 - F$, $\bar{F}_Q = 1 - F_Q$ and $\bar{Q}(u_1, \dots, u_n) = 1 - Q(1 - u_1, \dots, 1 - u_n)$ is the *multivariate dual distortion function*.

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Proportional hazard rate (PHR) model

- The PHR (Cox) model associated to a RF \bar{F} is

$$\bar{F}_\alpha(t) = (\bar{F}(t))^\alpha = \bar{q}(\bar{F}(t))$$

for $\alpha > 0$. \bar{F}_α a DD with $\bar{q}(u) = u^\alpha$ and $q(u) = 1 - (1 - u)^\alpha$.

- The hazard (failure) rate function is defined by $h(t) = f(t)/\bar{F}(t)$ where f is the PDF.
- Under the PHR model, $h_\alpha(t) = \alpha h(t)$.
- The proportional reversed hazard rate (PRHR) model is

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Order statistics (OS)

- X_1, \dots, X_n IID $\sim F$ random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any permutation σ

$$(X_1, \dots, X_n) \stackrel{ST}{=} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) is an arbitrary random vector with

$$F(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

$$\bar{F}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the DF.
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Distorted Distribution Representation-IID case

- In the IID case, we have

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.5)$$

(see David and Nagaraja 2003, p. 46) where

$$F_{j:j}(t) = \Pr(X_{j:j} \leq t) = \Pr(\max(X_1, \dots, X_j) \leq t) = F^j(t)$$

and

$$q_{i:n}(u) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} u^j$$

is a strictly increasing polynomial in $[0, 1]$.

- Both $F_{j:j}$ and $F_{i:n}$ are DD from F .

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Distorted Distribution Representation-IID case

- The upper OS $X_{j:j}$ (lifetime of the parallel system) satisfies the PRHR model with $\alpha = j$ since

$$F_{j:j}(t) = \Pr(X_{j:j} \leq t) = \Pr(\max(X_1, \dots, X_j) \leq t) = (F(t))^j.$$

- The lower OS $X_{1:j}$ (lifetime of the series system) satisfies the PHR model

$$\bar{F}_{1:j}(t) = \Pr(X_{1:j} \leq t) = \Pr(\min(X_1, \dots, X_j) > t) = (\bar{F}(t))^j.$$

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Distorted Distribution Representation- EXC case

- In the EXC case the left hand side of (1.5) holds with

$$F_{j:j}(t) = \Pr(\max(X_1, \dots, X_j) \leq t) = \mathbf{F}(\underbrace{t, \dots, t}_j, \underbrace{\infty, \dots, \infty}_{n-j}).$$

- The copula representation for \mathbf{F} is

$$\mathbf{F}(x_1, \dots, x_n) = C(F_1(x_1), \dots, F_n(x_n)), \quad (1.6)$$

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Coherent systems

- A **coherent system** is

$$\phi = \phi(x_1, \dots, x_n) : \{0, 1\}^n \rightarrow \{0, 1\},$$

where $x_i \in \{0, 1\}$ (it represents the state of the i th component) and where ϕ (which represents the state of the system) is increasing in x_1, \dots, x_n and strictly increasing in x_i for at least a point (x_1, \dots, x_n) , for all $i = 1, \dots, n$.

- If X_1, \dots, X_n are the component lifetimes, then there exists ψ such that the system lifetime $T = \psi(X_1, \dots, X_n)$.
- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
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- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
- $X_{1:n}$ is the series system lifetime and $X_{n:n}$ is the parallel system lifetime.

Coherent systems- IID and EXC case

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (1.7)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- IID case: p_i only depends on ϕ

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (1.8)$$

- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (1.7) holds for EXC r.v. when \mathbf{p} is given by (1.8).
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Generalized mixture representations

- Navarro, Ruiz and Sandoval (CSTM, 2007), EXC case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t). \quad (1.9)$$

- $\mathbf{a} = (a_1, \dots, a_n)$ is the minimal signature of T .
- a_i only depends on ϕ but can be negative and so (1.9) is called a generalized mixture.
- In the IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}^i(t) = \bar{q}_\phi(\bar{F}(t)), \quad (1.10)$$

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Coherent systems-GENERAL case

- A **path set** of T is a set $P \subseteq \{1, \dots, n\}$ such that if all the components in P work, then the system works.
- A **minimal path set** of T is a path set which does not contain other path sets.
- If P_1, \dots, P_r are the minimal path sets of T , then $T = \max_{j=1, \dots, r} X_{P_j}$, where $X_P = \min_{i \in P} X_i$ and

$$\begin{aligned} \bar{F}_T(t) &= \Pr \left(\max_{j=1, \dots, r} X_{P_j} > t \right) = \Pr \left(\bigcup_{j=1}^r \{X_{P_j} > t\} \right) \\ &= \sum_{i=1}^r \bar{F}_{P_i}(t) - \sum_{i \neq j} \bar{F}_{P_i \cup P_j}(t) + \dots \pm \bar{F}_{P_1 \cup \dots \cup P_r}(t) \end{aligned}$$

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- The copula representation for the RF of (X_1, \dots, X_n) is

$$\bar{F}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$ and K is the survival copula.

- Then

$$\bar{F}_P(t) = Q_{P,K}(\bar{F}_1(t), \dots, \bar{F}_n(t)),$$

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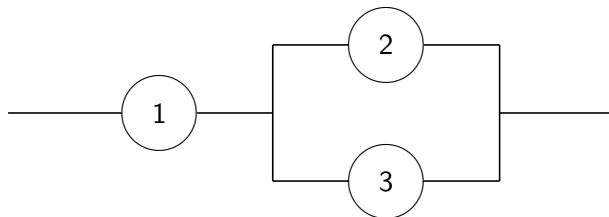
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- The same holds for OS (k-out-of-n systems).

Example

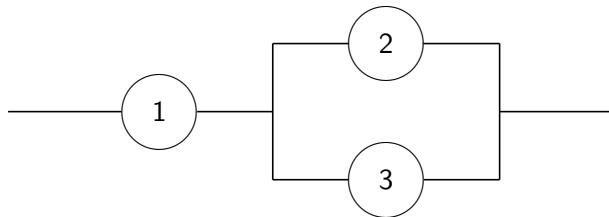


Example



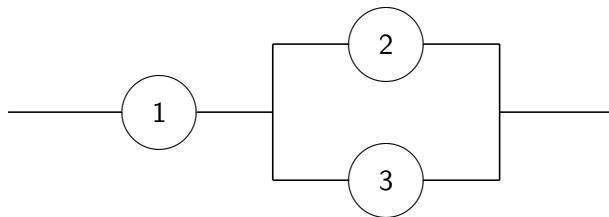
Coherent system lifetime $T = \min(X_1, \max(X_2, X_3))$.

Example



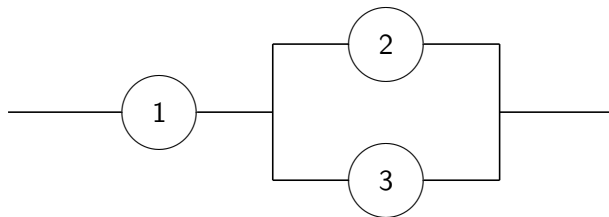
$3! = 6$ permutations.

Example



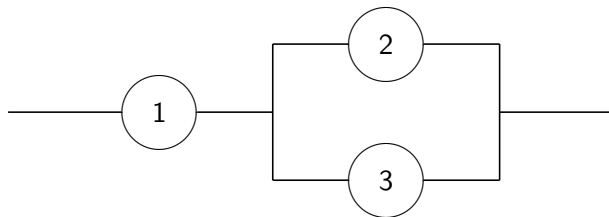
$$X_1 < X_2 < X_3 \Rightarrow T = X_1 = X_{1:3}$$

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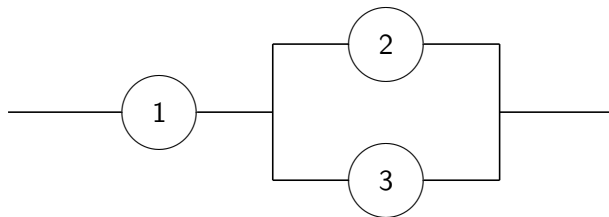
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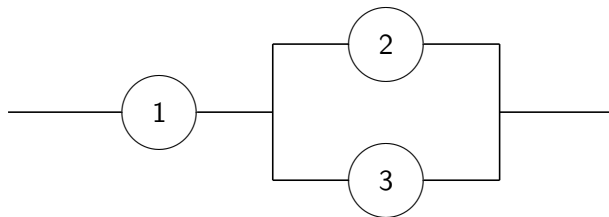
$$X_2 < X_1 < X_3 \Rightarrow T = X_1 = X_{2:3}$$

Example



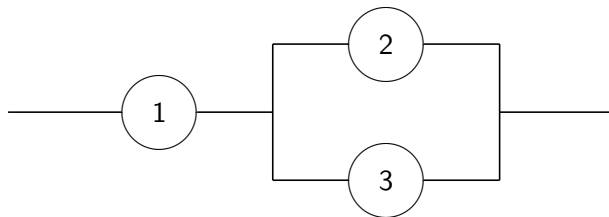
$$X_2 < X_3 < X_1 \Rightarrow T = X_3 = X_{2:3}$$

Example



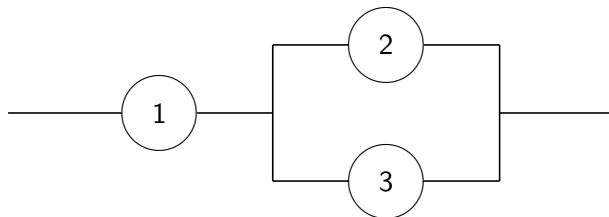
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Example



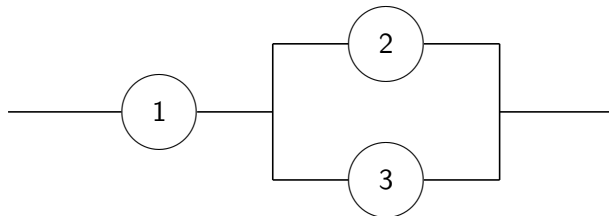
$$X_3 < X_2 < X_1 \Rightarrow T = X_2 = X_{2:3}$$

Example



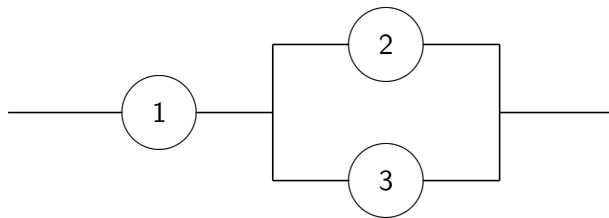
IID \bar{F} cont.: $\mathbf{p} = (2/6, 4/6, 0) = (1/3, 2/3, 0)$.

Example



$$\text{IID } \bar{F} \text{ cont.: } \bar{F}_T(t) = \frac{1}{3}\bar{F}_{1:3}(t) + \frac{2}{3}\bar{F}_{2:3}(t).$$

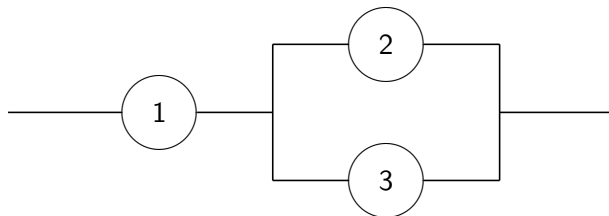
Example-general case



Coherent system lifetime $T = \max(\min(X_1, X_2), \min(X_1, X_3))$

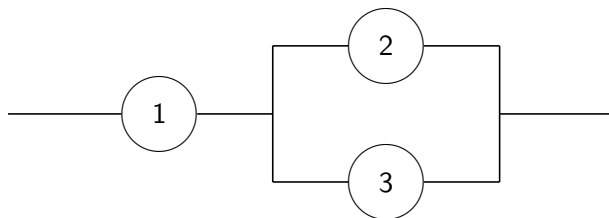
Minimal path sets $P_1 = \{1, 2\}$ and $P_1 = \{1, 3\}$.

Example-general case



$$\begin{aligned}\bar{F}_T(t) &= \Pr(\{X_{\{1,3\}} > t\} \cup \{X_{\{1,2\}} > t\}) \\ &= \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) - \bar{F}_{\{1,2,3\}}(t).\end{aligned}$$

Example-general case

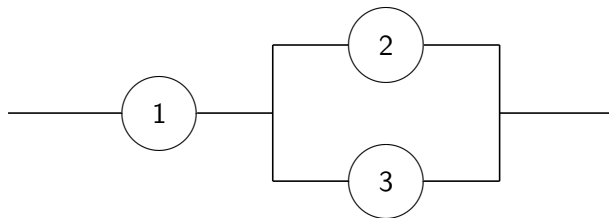


$$\bar{F}_{\{1,2\}}(t) = \bar{F}(t, t, 0) = K(\bar{F}_1(t), \bar{F}_2(t), 1), \dots$$

$$\bar{F}_T(t) = Q_{\phi, K}(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)) \text{ where}$$

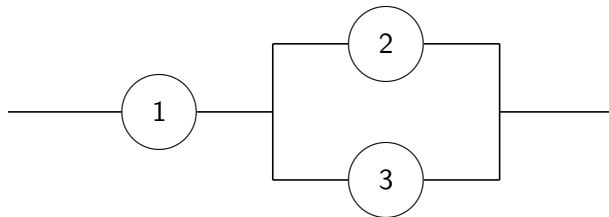
$$Q_{\phi, K}(u_1, u_2, u_3) = K(u_1, u_2, 1) + K(u_1, 1, u_3) - K(u_1, u_2, u_3).$$

Example-general case



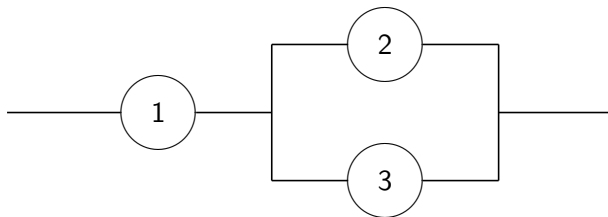
EXC: $\bar{F}_T(t) = 2\bar{F}_{1:2}(t) - \bar{F}_{1:3}(t) = q_{\phi, \kappa}(\bar{F}(t))$,
where $q_{\phi, \kappa}(u) = 2K(u, u, 1) - K(u, u, u)$.
Minimal signature $\mathbf{a} = (0, 2, -1)$.

Example-general case



IID: $\bar{F}_T(t) = 2\bar{F}^2(t) - \bar{F}^3(t) = q_\phi(\bar{F}(t))$,
where $q_\phi(u) = 2u^2 - u^3$.

Example-general case



The minimal signatures for $n \leq 5$ can be seen in:
Navarro and Rubio (2010, Comm Stat Simul Comp 39, 68–84).

Generalized Order Statistics (GOS)

- For an arbitrary DF F , GOS $X_{1:n}^{GOS}, \dots, X_{n:n}^{GOS}$ based on F can be obtained (Kamps, 1995, B. G. Teubner Stuttgart, p.49) via the quantile transformation

$$X_{r:n}^{GOS} = F^{-1}(U_{r:n}^{GOS}), \quad r = 1, \dots, n,$$

where $(U_{1:n}^*, \dots, U_{n:n}^*)$ has the joint PDF

$$g^{GOS}(u_1, \dots, u_n) = k \left(\prod_{j=1}^{n-1} \gamma_j \right) \left(\prod_{i=1}^{n-1} (1 - u_i)^{m_i} \right) (1 - u_n)^{k-1}$$

for $0 \leq u_1 \leq \dots \leq u_n < 1$, $n \geq 2$, $k \geq 1$, $\gamma_1, \dots, \gamma_n > 0$ and $m_i = \gamma_i - \gamma_{i+1} - 1$.

Generalized Order statistics (GOS)

- If $\gamma_1, \dots, \gamma_n$ are pairwise different, then

$$F_{r:n}^{GOS}(t) = 1 - c_{r-1} \sum_{i=1}^r \frac{a_{i,r}}{\gamma_i} (1 - F(t))^{\gamma_i} = q_{r:n}^{GOS}(F(t))$$

with the constants

$$c_{r-1} = \prod_{j=1}^r \gamma_j, \quad a_{i,r} = \prod_{\substack{j=1 \\ j \neq i}}^r \frac{1}{\gamma_j - \gamma_i}, \quad 1 \leq i \leq r \leq n$$

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Particular cases of GOS

- The GOS include:
 - OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
 - kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
 - RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
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Preservation results

- If q_1 and q_2 are two DF,

$$q_1(F) \leq_{ord} q_2(F) \text{ for all } F?$$

- If q is a DF,

$$F \leq_{ord} G \Rightarrow q(F) \leq_{ord} q(G)?$$

- If Q_1 and Q_2 are two MDF,

$$Q_1(F_1, \dots, F_n) \leq_{ord} Q_2(F_1, \dots, F_n)?$$

- If Q is a MDF,

$$F_i \leq_{ord} G_i, i = 1, \dots, n, \Rightarrow Q(F_1, \dots, F_n) \leq_{ord} Q(G_1, \dots, G_n)?$$

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Main stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$, stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t | X > t) \leq_{ST} (Y - t | Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t | X > t) \leq E(Y - t | Y > t)$ for all t .
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{RHR} Y \Leftrightarrow (t - X | X < t) \geq_{ST} (t - Y | Y < t)$ for all t .
- Then

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- If T_i has the DD $q_i(F(t))$, $i = 1, 2$, then:
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 - $T_1 \leq_{LR} T_2$ (\geq_{LR}) for all F if and only if $q_2(q_1^{-1}(u))$ is concave (convex) in $(0, 1)$.
 - $T_1 \leq_{LR} T_2$ for all F if and only if $q'_1(u)/q'_2(u)$ decreases.
 - **NEW** $T_1 \leq_{MRL} T_2$ for all F if $E(T_1) \leq E(T_2)$ and \bar{q}_2/\bar{q}_1 is bathtub in $(0, 1)$.

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where $\alpha(u) = uq'(1-u)/(1-q(1-u)) = u\bar{q}'(u)/\bar{q}(u)$.

- If $\beta_q(u)$ is decreasing and nonnegative in $(0, 1)$, then

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and $D_i \Phi(u_1, \dots, u_n) = \frac{\partial}{\partial u_i} \Phi(u_1, \dots, u_n)$.

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- $G_1 \leq_{ST} G_2$ for all F_1, \dots, F_n if and only if $Q_1/Q_2 \geq 1$ in $(0, 1)^n$.
- $G_1 \leq_{HR} G_2$ for all F_1, \dots, F_n if and only if $\overline{Q}_2/\overline{Q}_1$ is decreasing in $(0, 1)^n$.
- $G_1 \leq_{HR} G_2$ for all F_1, \dots, F_n if $\alpha_i^{\overline{Q}_1} \geq \alpha_i^{\overline{Q}_2}$ in $(0, 1)^n$ for $i = 1, \dots, n$, where

$$\alpha_i^{\Phi}(u_1, \dots, u_n) = \frac{u_i D_i \Phi(u_1, \dots, u_n)}{\Phi(u_1, \dots, u_n)} \quad (2.1)$$

and $D_i \Phi(u_1, \dots, u_n) = \frac{\partial}{\partial u_i} \Phi(u_1, \dots, u_n)$.

- $G_1 \leq_{RHR} G_2$ for all F_1, \dots, F_n if and only if Q_2/Q_1 is increasing in $(0, 1)^n$.

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- If $F_Q = Q(F_1, \dots, F_n)$ and $G_Q = Q(G_1, \dots, G_n)$, then:
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 - If $F_i \leq_{HR} G_i$ for $i = 1, \dots, n$, then $F_Q \leq_{HR} G_Q$ for all MDF Q such that $\bar{\alpha}_i^{\bar{Q}}$ is decreasing in $(0, 1)^n$ for $i = 1, \dots, n$.
 - If $F_i \leq_{HR} G_i$ for $i = 1, \dots, n$, then $F_Q \leq_{HR} G_Q$ for all MDF Q such that

$$\frac{\bar{Q}(u_1 v_1, \dots, u_n v_n)}{\bar{Q}(u_1, \dots, u_n)}. \quad (2.2)$$

is decreasing in u_1, \dots, u_n when $0 < u_i < 1$ and $0 < u_i v_i < 1$.

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- If $F_i \leq_{RHR} G_i$ for $i = 1, \dots, n$, then $F_Q \leq_{RHR} G_Q$ for all MDF Q such that α_i^Q is decreasing in $(0, 1)^n$ for $i = 1, \dots, n$.
- If $F_i \leq_{LR} G_i$ and F_i is IHR (DHR) for $i = 1, \dots, n$, then $F_Q \leq_{LR} G_Q$ for all MDF Q such that

$$\gamma_{\bar{Q}} = \frac{w_1 z_1 u_1 D_1 \bar{Q}(u_1 v_1, \dots, u_n v_n) + \dots + w_n z_n u_n D_n \bar{Q}(u_1 v_1, \dots, u_n v_n)}{z_1 u_1 D_1 \bar{Q}(u_1, \dots, u_n) + \dots + z_n u_n D_n \bar{Q}(u_1, \dots, u_n)}$$

is decreasing in u_1, \dots, u_n , increasing in $v_1, \dots, v_n, w_1, \dots, w_n$
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- If $F_1 \leq_{LR} G_1$ and $F_1 \leq_{LR} F_i$ (\geq_{LR}) for $i = 2, \dots, n$, then $F_Q \leq_{LR} G_Q$ for all MDF Q such that

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Preservation results of aging classes

- Let \mathcal{C} be an aging class.
- If q is a distorted function,

$$F \in \mathcal{C} \Rightarrow q(F) \in \mathcal{C}?$$

- If Q is a multivariate distorted function,

$$F_i \in \mathcal{C}, i = 1, \dots, n, \Rightarrow Q(F_1, \dots, F_n) \in \mathcal{C}?$$

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Stochastic aging classes

- X is Increasing (Decreasing) Hazard Rate IHR (DHR) if h is increasing (decreasing).
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $X \geq_{ST} (X - t|X > t)$ (\leq_{ST}) for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
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Preservation of Stochastic aging classes DD

- Let $F_q = q(F)$ and $\alpha(u) = u\bar{q}'(u)/\bar{q}(u)$. Then:
- The IHR class is preserved (i.e. F_q is IHR for all F IHR) if and only if α is decreasing in $(0, 1)$.
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- The IHR and DHR classes are preserved if and only if the PHR holds (α is constant).
- The NBU (NWU) class is preserved if and only if

$$\bar{q}(uv) \leq \bar{q}(u)\bar{q}(v) \quad (\geq), \quad 0 \leq u, v \leq 1. \quad (2.4)$$

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- The NBU (NWU) class is preserved if the IHR (DHR) class is preserved.

Preservation of Stochastic aging classes

- In the IID case:
 - The IHR class and the HR order are preserved for $X_{i:n}$ since $\alpha_{i:n}(u)$ is decreasing (Esary and Proschan 1963, Tech.).
 - The DHR class is not necessarily preserved for $X_{i:n}$! It is only preserved for $X_{1:n}$ since $\alpha_{1:n}(u)$ is constant.
 - The IHR and DHR classes are not necessarily preserved under the formation of coherent systems! It depends on the system structure.
 - In the ID case the IHR class is not necessarily preserved for $X_{i:n}$! It depends on the copula (dependence).

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- The IHR and DHR classes are not necessarily preserved under the formation of coherent systems! It depends on the system structure.
- In the ID case the IHR class is not necessarily preserved for $X_{i:n}$! It depends on the copula (dependence).

Preservation of Stochastic aging classes DD

- Let $F_q = q(F)$ and let

$$\beta(u) = u\bar{q}''(u)/\bar{q}'(u),$$

and

$$\bar{\beta}(u) = (1 - u)\bar{q}''(u)/\bar{q}'(u).$$

Then:

- If F is ILR and there exists $a \in [0, 1]$ such that β is non-negative and decreasing in $(0, a)$ and $\bar{\beta}$ is non-positive and decreasing in $(a, 1)$, then F_q is ILR.
- If F is DLR with support (l, ∞) ($l \geq 0$), β is non-negative and increasing in $(0, 1)$, then F_q is DLR.

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- The NBU (NWU) class is preserved if

$$\bar{Q}(u_1 v_1, \dots, u_n v_n) \leq \bar{Q}(u_1, \dots, u_n) \bar{Q}(v_1, \dots, v_n) \quad (\geq)$$

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Preservation of Stochastic aging classes GDD

- If X_1, \dots, X_n are independent, then:
- The NBU class is preserved under the formation of coherent systems (Esary, Marshall and Proschan, 1970, SIAM J Appl Math).
- The IHR class is not preserved under the formation of coherent systems (order statistics) in the independent case.

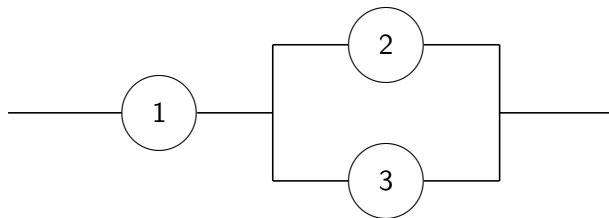
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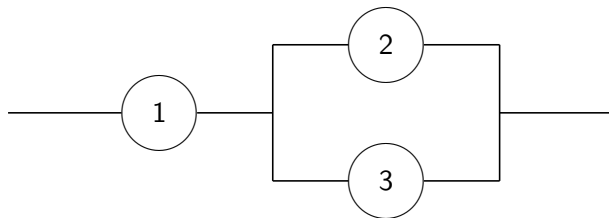
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Example-system IID case



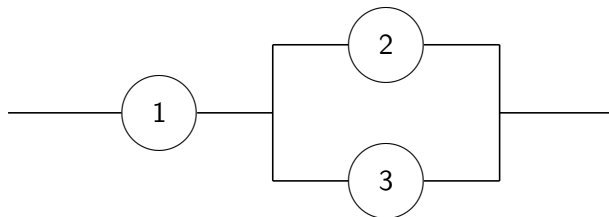
- Coherent system lifetime $T = \min(X_1, \max(X_2, X_3))$.
- In the IID case: $q(u) = u + u^2 - u^3$ and $\bar{q}(u) = 2u^2 - 3u^3$.
- Then $\alpha(u) = \frac{4-3u}{2-u}$ is strictly decreasing.
- The HR order is preserved.
- The IHR class is preserved and the DHR is not always preserved.

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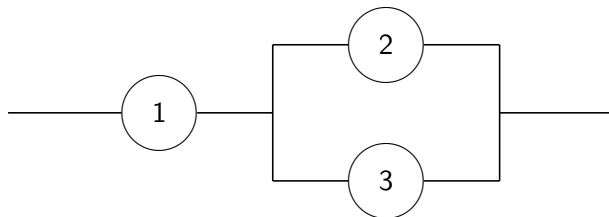
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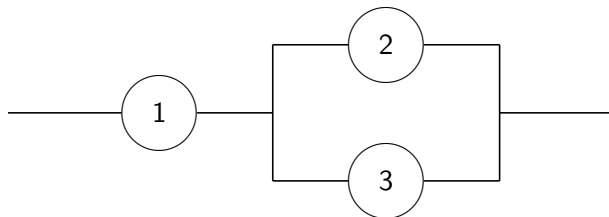
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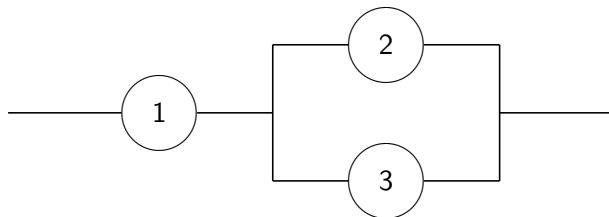
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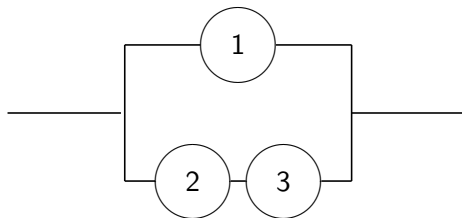
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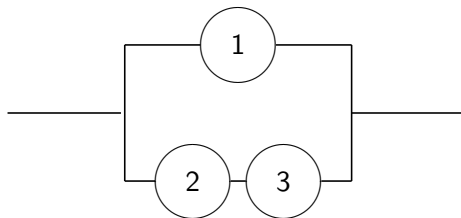
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Example- paradoxical system IID case



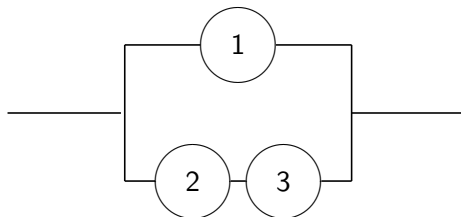
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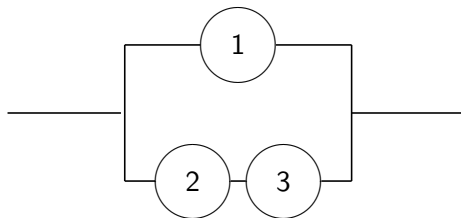
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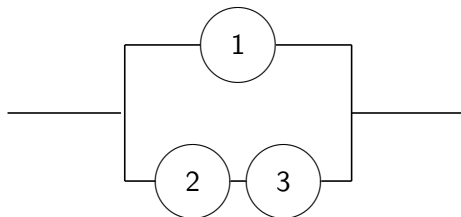
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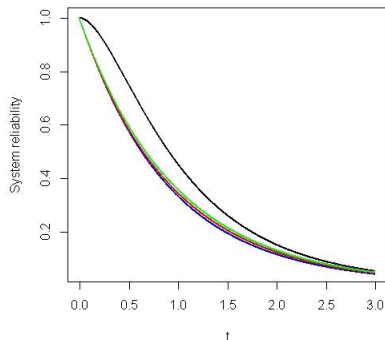
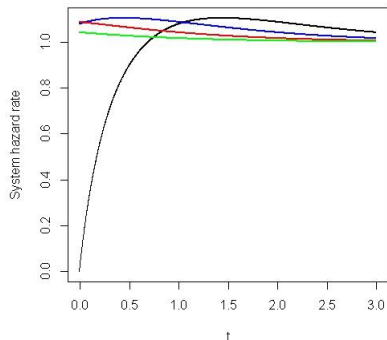


Figure: HR (left) and RF (left) of the residual lifetimes $(T - t | T > t)$ of the system $T = \max(X_1, \min(X_2, X_3))$ when X_i are $\text{IID} \sim \text{Exp}(\mu = 1)$ with $t = 0, 1, 2, 3$ (black, blue, red, green).

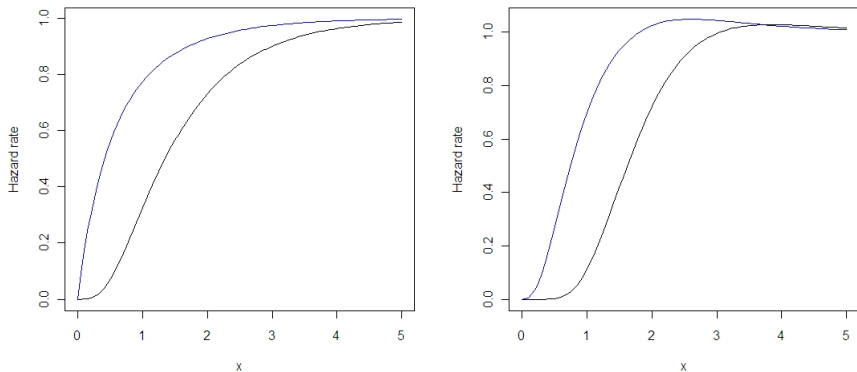


Figure: HR X_1 (left) and $T = \max(X_1, \min(X_2, X_3))$ (right) when X_i are IID with $\bar{F}(t) = 1 - (1 - e^{-t})^a$ for $t > 0$ and $a = 2, 5$ (blue, black).

Example-DID case

- Series system $X_{1:n} = \min(X_1, \dots, X_n)$ with ID components having a Clayton-Oakes survival copula

$$K(u_1, \dots, u_n) = \left(\sum_{i=1}^n u_i^{1-\theta} - (n-1) \right)^{1/(1-\theta)}, \quad \theta > 1.$$

- Then

$$\bar{q}(u) = K(u, \dots, u) = (nu^{1-\theta} - n + 1)^{1/(1-\theta)}.$$

- As $\alpha(u) = \frac{n}{n - (n-1)u^{\theta-1}}$ is a strictly increasing function for all $\theta > 1$, the DHR class is preserved for all n .
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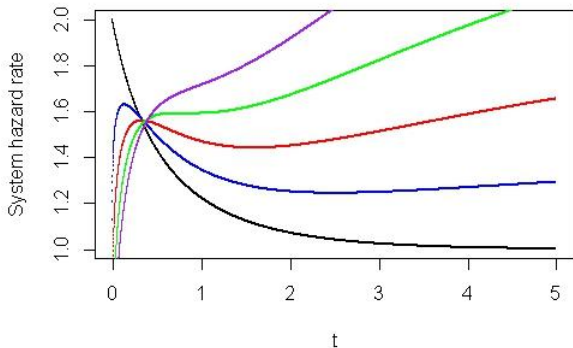


Figure: HR of $T = \min(X_1, X_2)$ when (X_1, X_2) has a C-O survival copula with $\theta = 2$ and $\bar{F}_i(t) = \exp(-t^a)$, $t > 0$, $i = 1, 2$ with $a = 1$ (black, Exponential), $a = 1.1, 1.2, 1.3, 1.4$ (blue, red, green, purple, IHR Weibull).

Example-Parallel system IND case

- Parallel system $X_{2:2} = \max(X_1, X_2)$ with IND components.
- Then $\bar{Q}_{2:2}(u_1, u_2) = u_1 + u_2 - u_1 u_2$.
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is decreasing, then $X_{1:2} \leq_{HR} X_{2:2}$.

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is decreasing, then $X_{1:2} \leq_{HR} X_{2:2}$.

- X_1 and $X_{2:2}$ are not always HR-ordered since

$$\frac{\bar{Q}_{2:2}(u_1, u_2)}{u_1} = 1 + \frac{u_2}{u_1} - u_2$$

is decreasing in u_1 but increasing in u_2 .

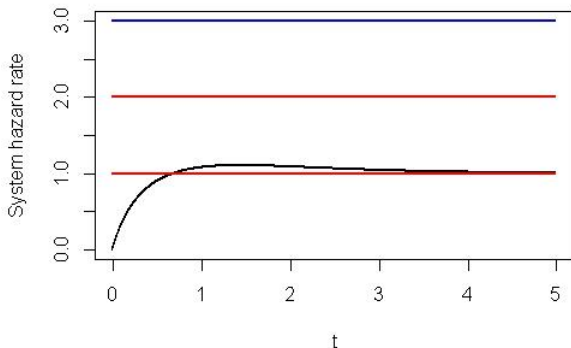


Figure: HR of X_i (red), $X_{1:2}$ (blue) and $X_{2:2}$ (black) when $X_i \sim \text{Exp}(\mu = 1/i)$, $i = 1, 2$. X_i are IHR and DHR but $X_{2:2}$ is neither IHR nor DHR.

Example-Series system IND case

- $X_{1:n} = \min(X_1, \dots, X_n)$ having DF F_1, F_2, \dots, F_n .
- $Y_{1:n} = \min(Y_1, \dots, Y_n)$ having DF G_1, F_2, \dots, F_n ,
- $F_1 \leq_{LR} G_1$
- If F_1 is DHR and F_i is IHR for $i = 2, \dots, n$, then $X_{1:n} \leq_{LR} Y_{1:n}$.
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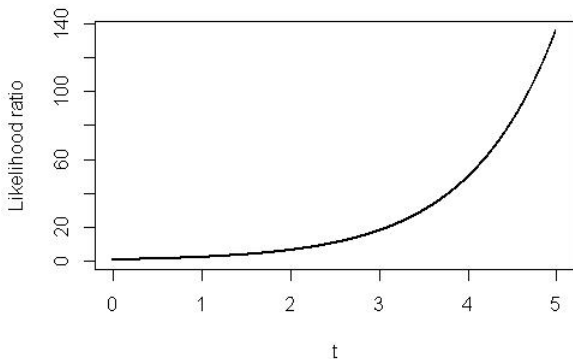


Figure: LR $g_{1:2}/f_{1:2}$ for $X_{1:2} = \min(X_1, X_2)$ and $Y_{1:2} = \min(Y_1, Y_2)$ when $X_1 \sim \text{Exp}(\mu = 1/2)$, $Y_1 \sim \text{Exp}(\mu = 1)$ and $\Pr(X_2 > t) = \Pr(Y_2 > t) = \exp(-t^2)$ (IHR Weibull).

Parrondo's paradox series systems-IID case

- Parrondo's paradox shows (Game Theory) how, in some games, a random strategy might be better than any deterministic strategy.
- The same paradox holds for coherent systems.
- Let us assume that we have two kind of units with reliability functions $\bar{F}_1 \geq \bar{F}_2$ (in a similar number) to build series systems with two independent units.
- Let $T = \min(X_1, X_2)$ be the system obtained when $\bar{F}_i(t) = \Pr(X_i > t)$, $i = 1, 2$.
- Let S be the system obtained when the units are chosen randomly.
- Then $T \leq_{ST} S$ since

$$\bar{F}_T(t) = \bar{F}_1(t)\bar{F}_2(t) \leq (0.5\bar{F}_1(t) + 0.5\bar{F}_1(t))^2 = \bar{F}_S(t).$$

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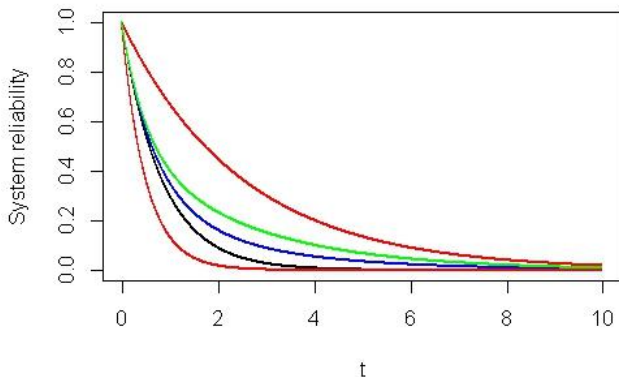


Figure: Reliability functions of systems T (black) and S (blue) when the units have exponential distributions with means 5 and 1.

Parrondo's paradox in other systems

- The same happen with series systems of size n with independent components.
- The orderings are reversed for parallel systems.
- In both cases, we compare the GDD $Q(F_1, \dots, F_n)$ and $Q(G, \dots, G)$, where $G = (F_1 + \dots + F_n)/n$.
- A function $g : \mathbb{R}^n \rightarrow \mathbb{R}$ is weakly Schur-concave (convex) if

$$g(u_1, u_2, \dots, u_n) \leq g(\bar{u}, \bar{u}, \dots, \bar{u}) \quad (\geq)$$

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Parrondo's paradox

Theorem (Navarro and Spizzichino, ASMBI 2010)

If (X_1, X_2, \dots, X_n) and (Y_1, Y_2, \dots, Y_n) have the same copula, $\bar{F}_i(t) = \Pr(X_i > t)$ and $\bar{G}(t) = (\bar{F}_1(t) + \dots + \bar{F}_n(t))/n = \Pr(Y_i > t)$ for $i = 1, \dots, n$, and $\bar{Q}_{\phi, K}$ is weakly Schur-concave (convex), then

$$T = \phi(X_1, \dots, X_n) \leq_{ST} S = \phi(Y_1, \dots, Y_n) \quad (\geq_{ST}).$$

Parrondo's paradox in other systems

- This theorem can be applied to GDD.
- For $X_{1:n}$ with independent components $\bar{Q}_{1:n}(u_1, \dots, u_n) = u_1 \dots u_n$ which is Schur-concave and so Parrondo's paradox holds.
- For $X_{1:n}$ with dependent components $\bar{Q}_{1:n,K}(u_1, \dots, u_n) = K(u_1, \dots, u_n)$.
- Many copulas are Schur-concave (e.g. Archimedean copulas) and so Parrondo's paradox holds in many series systems.
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Randomized GDD

- If \bar{Q} is a GDF, we consider the GDD with RF

$$\bar{F}_k(t) = \bar{Q}(\underbrace{\bar{F}_X(t), \dots, \bar{F}_X(t)}_{k\text{-times}}, \underbrace{\bar{F}_Y(t), \dots, \bar{F}_Y(t)}_{(n-k)\text{-times}}), k = 0, \dots, n \quad (3.1)$$

- Here, e.g., we can assume $X \geq_{ST} Y$.
- The randomized GDD is obtained when the number k of “good components” is chosen randomly according to a discrete random variable K with support included in $\{0, \dots, n\}$.
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Proposition (Navarro, Pellerey and Di Crecenzo, 2014)

If k is chosen randomly according to K_1 or K_2 and

$$\varphi(k) = \overline{Q}(\underbrace{u, \dots, u}_{k\text{-times}}, \underbrace{v, \dots, v}_{(n-k)\text{-times}})$$

is convex (concave) in $\{0, 1, \dots, m\}$ for all $u, v \in (0, 1)$, then:

- (i) $K_1 \leq_{CX} K_2$ implies $T_{K_1} \leq_{ST} T_{K_2}$ (\geq_{ST}).
- (ii) $X \geq_{ST} Y$ and $K_1 \leq_{ICX} K_2$ (\leq_{ICV}) imply $T_{K_1} \leq_{ST} T_{K_2}$.

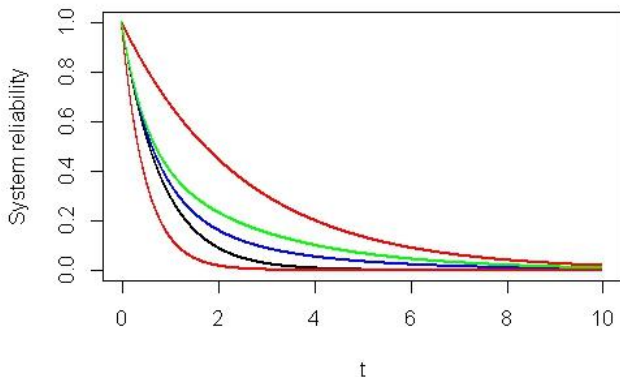


Figure: Reliability functions of systems T (black) and S (blue) when the units have exponential distributions with means 1 and 5.

Parrondo paradox example

- $T = \min(X_1, X_2)$ with $\bar{Q}(u, v) = uv$.
- It is obtained with K_1 such that $\Pr(K_1 = 1) = 1$.
- S is obtained with K_2 such that $\Pr(K_2 = 1) = 1/2$ and $\Pr(K_2 = 0) = \Pr(K_2 = 2) = 1/4$.
- Another reasonable option is obtained with K_3 such that $\Pr(K_3 = i) = 1/3$ for $i = 0, 1, 2$.
- Another option K_4 such that $\Pr(K_4 = 0) = \Pr(K_4 = 2) = 1/2$.
- Note that $E(K_i) = 1$ for $i = 1, 2, 3, 4$.
- As $\varphi(k) = u^k v^{1-k}$ is convex and $K_1 \leq_{CX} K_2 \leq_{CX} K_3 \leq_{CX} K_4$, then

$$\bar{F}_{K_1} \leq_{ST} \bar{F}_{K_2} \leq_{ST} \bar{F}_{K_3} \leq_{ST} \bar{F}_{K_4}.$$

- Actually, K_4 is the best option (the most convex) whenever $E(K) = 1$.

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- S is obtained with K_2 such that $\Pr(K_2 = 1) = 1/2$ and $\Pr(K_2 = 0) = \Pr(K_2 = 2) = 1/4$.
- Another reasonable option is obtained with K_3 such that $\Pr(K_3 = i) = 1/3$ for $i = 0, 1, 2$.
- Another option K_4 such that $\Pr(K_4 = 0) = \Pr(K_4 = 2) = 1/2$.
- Note that $E(K_i) = 1$ for $i = 1, 2, 3, 4$.
- As $\varphi(k) = u^k v^{1-k}$ is convex and $K_1 \leq_{CX} K_2 \leq_{CX} K_3 \leq_{CX} K_4$, then

$$\bar{F}_{K_1} \leq_{ST} \bar{F}_{K_2} \leq_{ST} \bar{F}_{K_3} \leq_{ST} \bar{F}_{K_4}.$$

- Actually, K_4 is the best option (the most convex) whenever $E(K) = 1$.

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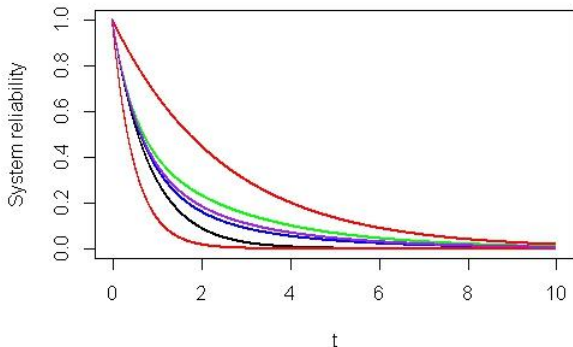


Figure: Reliability functions of systems $T = T_{K_1}$ (black), $S = T_{K_2}$ (blue), T_{K_3} (purple) and T_{K_4} (green) when the units have exponential distributions with means 5 and 1.

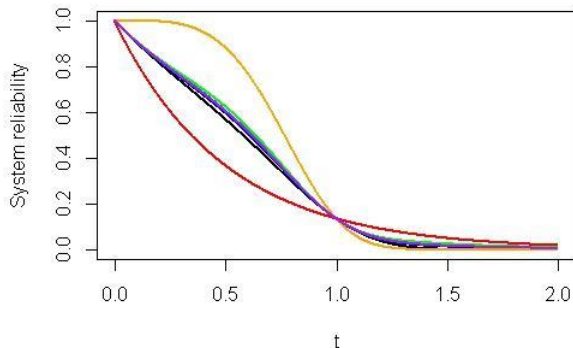


Figure: Reliability functions of systems $T = T_{K_1}$ (black), $S = T_{K_2}$ (blue), T_{K_3} (purple) and T_{K_4} (green) when the units have reliability $\bar{F}(t) = \exp(-t)$ (exponential, red) or $\bar{F}(t) = \exp(-t^4)$ (Weibull, orange).

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References

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