

Order statistics and related concepts

Jorge Navarro¹,
Universidad de Murcia, Spain
E-mail: jorgenav@um.es



¹Supported by Ministerio de Ciencia y Tecnología under grant MTM2009-08311 and Fundación Séneca under grant 08627/PI/08.

- OS IID case

- X_1, \dots, X_n IID random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1, \dots, X_n) =_{ST} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) an arbitrary random vector with joint distribution

$$\mathbf{F}(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

and with joint reliability

$$\bar{\mathbf{F}}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the distribution function (DF).

- X_1, \dots, X_n IID random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1, \dots, X_n) \stackrel{ST}{=} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) an arbitrary random vector with joint distribution

$$F(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

and with joint reliability

$$\bar{F}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the distribution function (DF).

- X_1, \dots, X_n IID random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1, \dots, X_n) \stackrel{ST}{=} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) an arbitrary random vector with joint distribution

$$\mathbf{F}(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

and with joint reliability

$$\bar{\mathbf{F}}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the distribution function (DF).

- X_1, \dots, X_n IID random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1, \dots, X_n) \stackrel{ST}{=} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) an arbitrary random vector with joint distribution

$$\mathbf{F}(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

and with joint reliability

$$\bar{\mathbf{F}}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the distribution function (DF).

- X_1, \dots, X_n IID random variables.
- X_1, \dots, X_n exchangeable (EXC), i.e., for any σ

$$(X_1, \dots, X_n) \stackrel{ST}{=} (X_{\sigma(1)}, \dots, X_{\sigma(n)}).$$

- (X_1, \dots, X_n) an arbitrary random vector with joint distribution

$$\mathbf{F}(x_1, \dots, x_n) = \Pr(X_1 \leq x_1, \dots, X_n \leq x_n)$$

and with joint reliability

$$\bar{\mathbf{F}}(x_1, \dots, x_n) = \Pr(X_1 > x_1, \dots, X_n > x_n).$$

- Let $X_{1:n}, \dots, X_{n:n}$ be the associated OS.
- Let $F_{i:n}(t) = \Pr(X_{i:n} \leq t)$ be the distribution function (DF).

Generalized mixture representations

- In the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n \binom{n}{j} F^j(t) \bar{F}^{n-j}(t),$$

where $F(t) = \Pr(X_i \leq t) = 1 - \bar{F}(t)$.

- Also in the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.1)$$

where $F_{j:j}(t) = F^j(t)$ and $q_{i:n}(u)$ is an increasing polynomial.

- In the EXC case the left hand side of (1.1) holds with

$$F_{j:j}(t) = \mathbf{F}(\underbrace{t, \dots, t}_j, \underbrace{\infty, \dots, \infty}_{n-j}).$$

- Some coefficients in (1.1) are negative.

Generalized mixture representations

- In the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n \binom{n}{j} F^j(t) \bar{F}^{n-j}(t),$$

where $F(t) = \Pr(X_i \leq t) = 1 - \bar{F}(t)$.

- Also in the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.1)$$

where $F_{j:j}(t) = F^j(t)$ and $q_{i:n}(u)$ is an increasing polynomial.

- In the EXC case the left hand side of (1.1) holds with

$$F_{j:j}(t) = \mathbf{F}(\underbrace{t, \dots, t}_j, \underbrace{\infty, \dots, \infty}_{n-j}).$$

- Some coefficients in (1.1) are negative.

Generalized mixture representations

- In the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n \binom{n}{j} F^j(t) \bar{F}^{n-j}(t),$$

where $F(t) = \Pr(X_i \leq t) = 1 - \bar{F}(t)$.

- Also in the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.1)$$

where $F_{j:j}(t) = F^j(t)$ and $q_{i:n}(u)$ is an increasing polynomial.

- In the EXC case the left hand side of (1.1) holds with

$$F_{j:j}(t) = \mathbf{F}(\underbrace{t, \dots, t}_j, \underbrace{\infty, \dots, \infty}_{n-j}).$$

- Some coefficients in (1.1) are negative.

Generalized mixture representations

- In the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n \binom{n}{j} F^j(t) \bar{F}^{n-j}(t),$$

where $F(t) = \Pr(X_i \leq t) = 1 - \bar{F}(t)$.

- Also in the IID case:

$$F_{i:n}(t) = \sum_{j=i}^n (-1)^{j-i} \binom{n}{j} \binom{j-1}{i-1} F_{j:j}(t) = q_{i:n}(F(t)), \quad (1.1)$$

where $F_{j:j}(t) = F^j(t)$ and $q_{i:n}(u)$ is an increasing polynomial.

- In the EXC case the left hand side of (1.1) holds with

$$F_{j:j}(t) = \mathbf{F}(\underbrace{t, \dots, t}_j, \underbrace{\infty, \dots, \infty}_{n-j}).$$

- Some coefficients in (1.1) are negative.

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

Stochastic orderings

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

- $X \leq_{ST} Y \Leftrightarrow \bar{F}_X(t) \leq \bar{F}_Y(t)$ stochastic order.
- $X \leq_{HR} Y \Leftrightarrow h_X(t) \geq h_Y(t)$, hazard rate order.
- $X \leq_{HR} Y \Leftrightarrow (X - t|X > t) \leq_{ST} (Y - t|Y > t)$ for all t .
- $X \leq_{MRL} Y \Leftrightarrow E(X - t|X > t) \leq E(Y - t|Y > t)$, mean residual life order.
- $X \leq_{LR} Y \Leftrightarrow f_Y(t)/f_X(t)$ is nondecreasing, likelihood ratio order.
- $X \leq_{LR} Y \Leftrightarrow (X|s < X < t) \leq_{ST} (Y|s < Y < t)$ for $s < t$.

Stochastic orderings relationships

$$\begin{array}{ccccc} E(X_{s,t}) \leq E(Y_{s,t}) & \Rightarrow & E(X_t) \leq E(Y_t) & \Rightarrow & E(X) \leq E(Y) \\ \Updownarrow & & \Updownarrow & & \Updownarrow \\ X \leq_{DTM} Y & \Rightarrow & X \leq_{MRL} Y & \Rightarrow & X \leq_M Y \\ \Uparrow & & \Uparrow & & \Uparrow \\ X \leq_{LR} Y & \Rightarrow & X \leq_{HR} Y & \Rightarrow & X \leq_{ST} Y \\ \Updownarrow & & \Updownarrow & & \Updownarrow \\ X_{s,t} \leq_{ST} Y_{s,t} & \Rightarrow & X_t \leq_{ST} Y_t & \Rightarrow & \bar{F}_X \leq \bar{F}_Y \end{array}$$

where $Z_t = (Z - t | Z > t)$ and $Z_{s,t} = (Z | s < Z < t)$ (see Navarro, Belzunce and Ruiz, PEIS, 1997).

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

- X is Increasing (Decreasing) Hazard rate IHR (DHR) if h is increasing.
- X is IHR $\Leftrightarrow (X - s|X > s) \geq_{ST} (X - t|X > t)$ for all $s < t$.
- X is New Better (Worse) than Used NBU (NWU) if $\Leftrightarrow X \geq_{ST} (X - t|X > t)$ for all $t > 0$.
- X is Increasing (Decreasing) Likelihood Ratio ILR (DLR) if f is log-concave (log-convex).
- X is ILR $\Leftrightarrow (X - s|X > s) \geq_{LR} (X - t|X > t)$ for all $s < t$.
- $ILR \Rightarrow IHR \Rightarrow NBU$.

Ordering properties for OS

- In the IID case:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}.$$

- In the I case:

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n}.$$

- In the general case:

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}.$$

- In the IID case:

$$F \text{ IHR} \Rightarrow F_{i:n} \text{ IHR}$$

$$F \text{ NBU} \Rightarrow F_{i:n} \text{ NBU, and}$$

$$F \text{ ILR} \Rightarrow F_{i:n} \text{ ILR.}$$

Ordering properties for OS

- In the IID case:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}.$$

- In the I case:

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n}.$$

- In the general case:

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}.$$

- In the IID case:

$$F \text{ IHR} \Rightarrow F_{i:n} \text{ IHR}$$

$$F \text{ NBU} \Rightarrow F_{i:n} \text{ NBU, and}$$

$$F \text{ ILR} \Rightarrow F_{i:n} \text{ ILR.}$$

Ordering properties for OS

- In the IID case:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}.$$

- In the I case:

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n}.$$

- In the general case:

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}.$$

- In the IID case:

$$F \text{ IHR} \Rightarrow F_{i:n} \text{ IHR}$$

$$F \text{ NBU} \Rightarrow F_{i:n} \text{ NBU, and}$$

$$F \text{ ILR} \Rightarrow F_{i:n} \text{ ILR.}$$

Ordering properties for OS

- In the IID case:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}.$$

- In the I case:

$$X_{1:n} \leq_{HR} \cdots \leq_{HR} X_{n:n}.$$

- In the general case:

$$X_{1:n} \leq_{ST} \cdots \leq_{ST} X_{n:n}.$$

- In the IID case:

$$F \text{ IHR} \Rightarrow F_{i:n} \text{ IHR}$$

$$F \text{ NBU} \Rightarrow F_{i:n} \text{ NBU, and}$$

$$F \text{ ILR} \Rightarrow F_{i:n} \text{ ILR.}$$

Generalized Order statistics (GOS)

GOS

- OS IID case

Generalized Order statistics (GOS)

- For an arbitrary DF F , GOS $X_{1:n}^{GOS}, \dots, X_{n:n}^{GOS}$ based on F can be obtained (Kamps, 1995, B. G. Teubner Stuttgart, p.49) via the quantile transformation

$$X_{r:n}^{GOS} = F^{-1}(U_{r:n}^{GOS}), \quad r = 1, \dots, n,$$

where $(U_{1:n}^*, \dots, U_{n:n}^*)$ has the joint PDF

$$g^{GOS}(u_1, \dots, u_n) = k \left(\prod_{j=1}^{n-1} \gamma_j \right) \left(\prod_{i=1}^{n-1} (1 - u_i)^{m_i} \right) (1 - u_n)^{k-1}$$

for $0 \leq u_1 \leq \dots \leq u_n < 1$, $n \geq 2$, $k \geq 1$, $\gamma_1, \dots, \gamma_n > 0$ and $m_i = \gamma_i - \gamma_{i+1} - 1$.

Generalized Order statistics (GOS)

- If $\gamma_1, \dots, \gamma_n$ are pairwise different, then

$$F_{r:n}^{GOS}(t) = 1 - c_{r-1} \sum_{i=1}^r \frac{a_{i,r}}{\gamma_i} (1 - F(t))^{\gamma_i} = q_{r:n}^{GOS}(F(t)) \quad (1.2)$$

with the constants

$$c_{r-1} = \prod_{j=1}^r \gamma_j, \quad a_{i,r} = \prod_{\substack{j=1 \\ j \neq i}}^r \frac{1}{\gamma_j - \gamma_i}, \quad 1 \leq i \leq r \leq n$$

where the empty product \prod_{\emptyset} is defined to be 1.

Ordering properties for GOS

- For the GOS we have:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}$$

Cramer, Kamps and Raqab (2003, *Applicationses Mathematicae*) and Hu and Zhuang (2005, *Statist Probab Lett*).

- For the GOS we have:

$$F \text{ IHR} \Rightarrow F_{r:n}^{GOS} \text{ IHR}$$

(Kamps, 1995, B. G. Teubner Stuttgart, p. 172) and

$$F \text{ ILR} \Rightarrow F_{r:n}^{GOS} \text{ ILR}$$

under some conditions (see Cramer, 2004, *Statist Probab Lett* and Chen, Xie and Hu, 2009, *Statist Probab Lett* 79).

Ordering properties for GOS

- For the GOS we have:

$$X_{1:n} \leq_{LR} \cdots \leq_{LR} X_{n:n}$$

Cramer, Kamps and Raqab (2003, *Applicationses Mathematicae*) and Hu and Zhuang (2005, *Statist Probab Lett*).

- For the GOS we have:

$$F \text{ IHR} \Rightarrow F_{r:n}^{GOS} \text{ IHR}$$

(Kamps, 1995, B. G. Teubner Stuttgart, p. 172) and

$$F \text{ ILR} \Rightarrow F_{r:n}^{GOS} \text{ ILR}$$

under some conditions (see Cramer, 2004, *Statist Probab Lett* and Chen, Xie and Hu, 2009, *Statist Probab Lett* 79).

- The GOS include:
 - OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
 - kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
 - RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
 - SOS, Sequential Order Statistics under the Proportional Hazard Rate (PHR) model, i.e., with $\bar{F}_r = \bar{F}^{\alpha_r}$ for $r = 1, \dots, n$ ($\gamma_r = (n - r + 1)\alpha_r$ and $k = \alpha_n$).

- The GOS include:
- OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
- kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
- RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
- SOS, Sequential Order Statistics under the Proportional Hazard Rate (PHR) model, i.e., with $\bar{F}_r = \bar{F}^{\alpha_r}$ for $r = 1, \dots, n$ ($\gamma_r = (n - r + 1)\alpha_r$ and $k = \alpha_n$).

- The GOS include:
- OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
- kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
- RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
- SOS, Sequential Order Statistics under the Proportional Hazard Rate (PHR) model, i.e., with $\bar{F}_r = \bar{F}^{\alpha_r}$ for $r = 1, \dots, n$ ($\gamma_r = (n - r + 1)\alpha_r$ and $k = \alpha_n$).

- The GOS include:
- OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
- kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
- RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
- SOS, Sequential Order Statistics under the Proportional Hazard Rate (PHR) model, i.e., with $\bar{F}_r = \bar{F}^{\alpha_r}$ for $r = 1, \dots, n$ ($\gamma_r = (n - r + 1)\alpha_r$ and $k = \alpha_n$).

- The GOS include:
- OS, IID case ($m_1 = \dots = m_{n-1} = 0$ and $k = 1$).
- kRV, k-th record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1, 2, \dots$).
- RV, record values ($m_1 = \dots = m_{n-1} = -1$ and $k = 1$).
- SOS, Sequential Order Statistics under the Proportional Hazard Rate (PHR) model, i.e., with $\bar{F}_r = \bar{F}^{\alpha_r}$ for $r = 1, \dots, n$ ($\gamma_r = (n - r + 1)\alpha_r$ and $k = \alpha_n$).

Sequential Order statistics (SOS)



Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1)$ for $t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1})$ for $t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1)$ for $t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1})$ for $t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1)$ for $t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1})$ for $t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1) \text{ for } t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1}) \text{ for } t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1) \text{ for } t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1}) \text{ for } t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1)$ for $t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1})$ for $t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- $\bar{F}_1, \dots, \bar{F}_n$.
- $Y_1^{(1)}, \dots, Y_n^{(1)} \text{ IID } \sim \bar{F}_1$.
- $X_{1:n}^{SOS} = \min(Y_1^{(1)}, \dots, Y_n^{(1)}) = t_1$.
- $Y_1^{(2)}, \dots, Y_{n-1}^{(2)} \text{ IID } \sim \bar{F}_2(t)/\bar{F}_2(t_1) \text{ for } t \geq t_1$.
- $X_{2:n}^{SOS} = \min(Y_1^{(2)}, \dots, Y_{n-1}^{(2)}) = t_2$.
- ...
- $X_{n:n}^{SOS} = Y_1^{(n)} \sim \bar{F}_n(t)/\bar{F}_n(t_{n-1}) \text{ for } t \geq t_{n-1}$.

Sequential Order statistics (SOS)

- OS (IID case) are SOS when $\bar{F}_1 = \dots = \bar{F}_n$.
- $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ are the order statistics from an exchangeable random vector

$$(X_1^{SOS}, \dots, X_n^{SOS}).$$

- If $\bar{F}_i = \bar{F}^{\alpha_i}$ for $i = 1, \dots, n$ (PHR model), the SOS are GOS.
- The SOS are not necessarily GOS.
- The GOS are not necessarily SOS.

Sequential Order statistics (SOS)

- OS (IID case) are SOS when $\bar{F}_1 = \dots = \bar{F}_n$.
- $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ are the order statistics from an exchangeable random vector

$$(X_1^{SOS}, \dots, X_n^{SOS}).$$

- If $\bar{F}_i = \bar{F}^{\alpha_i}$ for $i = 1, \dots, n$ (PHR model), the SOS are GOS.
- The SOS are not necessarily GOS.
- The GOS are not necessarily SOS.

Sequential Order statistics (SOS)

- OS (IID case) are SOS when $\bar{F}_1 = \dots = \bar{F}_n$.
- $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ are the order statistics from an exchangeable random vector

$$(X_1^{SOS}, \dots, X_n^{SOS}).$$

- If $\bar{F}_i = \bar{F}^{\alpha_i}$ for $i = 1, \dots, n$ (PHR model), the SOS are GOS.
 - The SOS are not necessarily GOS.
 - The GOS are not necessarily SOS.

Sequential Order statistics (SOS)

- OS (IID case) are SOS when $\bar{F}_1 = \dots = \bar{F}_n$.
- $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ are the order statistics from an exchangeable random vector

$$(X_1^{SOS}, \dots, X_n^{SOS}).$$

- If $\bar{F}_i = \bar{F}^{\alpha_i}$ for $i = 1, \dots, n$ (PHR model), the SOS are GOS.
- The SOS are not necessarily GOS.
- The GOS are not necessarily SOS.

Sequential Order statistics (SOS)

- OS (IID case) are SOS when $\bar{F}_1 = \dots = \bar{F}_n$.
- $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ are the order statistics from an exchangeable random vector

$$(X_1^{SOS}, \dots, X_n^{SOS}).$$

- If $\bar{F}_i = \bar{F}^{\alpha_i}$ for $i = 1, \dots, n$ (PHR model), the SOS are GOS.
- The SOS are not necessarily GOS.
- The GOS are not necessarily SOS.

Ordering properties for SOS

- The SOS are not necessarily HR ordered; see Navarro and Burkschat (2011, Naval Res Log).
- For the SOS:

$$\bar{F}_1, \dots, \bar{F}_n \text{ IHR} \not\Rightarrow F_{r:n}^{\text{SOS}} \text{ IHR}$$

and

$$\bar{F}_1, \dots, \bar{F}_n \text{ ILR} \not\Rightarrow F_{r:n}^{\text{GOS}} \text{ ILR};$$

see Navarro and Burkschat (2011, Naval Res Log).

Ordering properties for SOS

- The SOS are not necessarily HR ordered; see Navarro and Burkschat (2011, Naval Res Log).
- For the SOS:

$$\bar{F}_1, \dots, \bar{F}_n \text{ IHR} \not\Rightarrow F_{r:n}^{\text{SOS}} \text{ IHR}$$

and

$$\bar{F}_1, \dots, \bar{F}_n \text{ ILR} \not\Rightarrow F_{r:n}^{\text{GOS}} \text{ ILR};$$

see Navarro and Burkschat (2011, Naval Res Log).

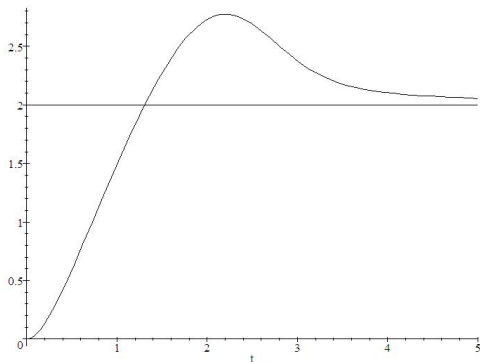


Figure: Hazard rate functions $h_{1:2}^{SOS}$ (constant line) and $h_{2:2}^{SOS}$ for the SOS obtained from $\bar{F}_1(t) = e^{-t}$ (exponential) and $\bar{F}_2(t) = e^{-t^2}$ (Weibull). The SOS are not HR ordered and $h_{2:2}^*$ is not monotone.

Ordering properties for SOS

- Conditions for the HR, MRL and LR ordering of SOS were given in Navarro and Burkschat (2011, Naval Res Log).
- For example:

Theorem

Let $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ be the SOS based on $\bar{F}_1, \dots, \bar{F}_n$ having hazard rate function h_1, \dots, h_n . If h_k/h_{k+1} is increasing for $k = 1, \dots, i$, then $X_{i:n}^{SOS} \leq_{HR} X_{i+1:n}^{SOS}$.

Ordering properties for SOS

- Conditions for the HR, MRL and LR ordering of SOS were given in Navarro and Burkschat (2011, Naval Res Log).
- For example:

Theorem

Let $X_{1:n}^{SOS}, \dots, X_{n:n}^{SOS}$ be the SOS based on $\bar{F}_1, \dots, \bar{F}_n$ having hazard rate function h_1, \dots, h_n . If h_k/h_{k+1} is increasing for $k = 1, \dots, i$, then $X_{i:n}^{SOS} \leq_{HR} X_{i+1:n}^{SOS}$.

- Conditions for the preservation of IHR, IHRA, NBU and ILR classes under the formation of SOS were given in Navarro and Burkschat (2011, Probab Eng Inf Sci, to appear).

Theorem

Let f_i be log-concave for $i = 1, 2, \dots, r$ and $h_{j+1} - h_j$ be decreasing for $j = 1, 2, \dots, r - 1$. Then $X_{r:n}^{SOS}$ is ILR.

-
- For more results, please go to PS9.

- Conditions for the preservation of IHR, IHRA, NBU and ILR classes under the formation of SOS were given in Navarro and Burkschat (2011, Probab Eng Inf Sci, to appear).

Theorem

Let f_i be log-concave for $i = 1, 2, \dots, r$ and $h_{j+1} - h_j$ be decreasing for $j = 1, 2, \dots, r - 1$. Then $X_{r:n}^{SOS}$ is ILR.

- For more results, please go to PS9.

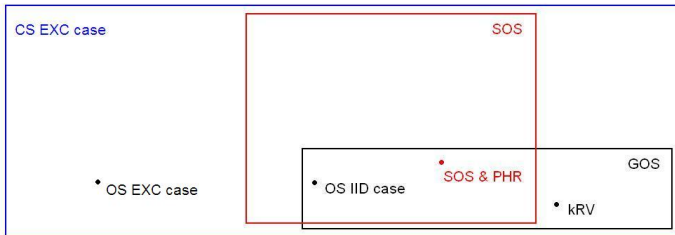
- Conditions for the preservation of IHR, IHRA, NBU and ILR classes under the formation of SOS were given in Navarro and Burkschat (2011, Probab Eng Inf Sci, to appear).

Theorem

Let f_i be log-concave for $i = 1, 2, \dots, r$ and $h_{j+1} - h_j$ be decreasing for $j = 1, 2, \dots, r - 1$. Then $X_{r:n}^{SOS}$ is ILR.

- For more results, please go to PS9.

Coherent systems (CS)



- Coherent systems $\phi = \phi(x_1, \dots, x_n) \in \{0, 1\}$ where $x_i \in \{0, 1\}$, the structure function ϕ is nondecreasing and strictly increasing in x_i for at least one point (x_1, \dots, x_n) , for $i = 1, \dots, n$.
- If X_1, \dots, X_n are the component lifetimes, then there exist ϕ such that the system lifetime $T = \phi(X_1, \dots, X_n)$.
- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
- $T = X_{i:n}$ for $i = 1, \dots, n$.

- Coherent systems $\phi = \phi(x_1, \dots, x_n) \in \{0, 1\}$ where $x_i \in \{0, 1\}$, the structure function ϕ is nondecreasing and strictly increasing in x_i for at least one point (x_1, \dots, x_n) , for $i = 1, \dots, n$.
- If X_1, \dots, X_n are the component lifetimes, then there exist ϕ such that the system lifetime $T = \phi(X_1, \dots, X_n)$.
- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
- $T = X_{i:n}$ for $i = 1, \dots, n$.

- Coherent systems $\phi = \phi(x_1, \dots, x_n) \in \{0, 1\}$ where $x_i \in \{0, 1\}$, the structure function ϕ is nondecreasing and strictly increasing in x_i for at least one point (x_1, \dots, x_n) , for $i = 1, \dots, n$.
- If X_1, \dots, X_n are the component lifetimes, then there exist ϕ such that the system lifetime $T = \phi(X_1, \dots, X_n)$.
- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
- $T = X_{i:n}$ for $i = 1, \dots, n$.

- Coherent systems $\phi = \phi(x_1, \dots, x_n) \in \{0, 1\}$ where $x_i \in \{0, 1\}$, the structure function ϕ is nondecreasing and strictly increasing in x_i for at least one point (x_1, \dots, x_n) , for $i = 1, \dots, n$.
- If X_1, \dots, X_n are the component lifetimes, then there exist ϕ such that the system lifetime $T = \phi(X_1, \dots, X_n)$.
- $X_{1:n}, \dots, X_{n:n}$ are the lifetimes of k -out-of- n systems.
- $T = X_{i:n}$ for $i = 1, \dots, n$.

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \bar{F} and

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (2.2)$$

- Navarro and Rychlik (JMVA, 2007), (2.1) holds for EXC absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (2.1) holds for EXC r.v. when \mathbf{p} is given by (2.2).

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \bar{F} and

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (2.2)$$

- Navarro and Rychlik (JMVA, 2007), (2.1) holds for EXC absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (2.1) holds for EXC r.v. when \mathbf{p} is given by (2.2).

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \bar{F} and

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (2.2)$$

- Navarro and Rychlik (JMVA, 2007), (2.1) holds for EXC absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (2.1) holds for EXC r.v. when \mathbf{p} is given by (2.2).

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \bar{F} and

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (2.2)$$

- Navarro and Rychlik (JMVA, 2007), (2.1) holds for EXC absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (2.1) holds for EXC r.v. when \mathbf{p} is given by (2.2).

- Samaniego (IEEE TR, 1985), IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n p_i \bar{F}_{i:n}(t), \quad (2.1)$$

where $p_i = \Pr(T = X_{i:n})$.

- $\mathbf{p} = (p_1, \dots, p_n)$ is the signature of the system.
- p_i does not depend on \bar{F} and

$$p_i = \frac{|\{\sigma : \phi(x_1, \dots, x_n) = x_{i:n}, \text{ when } x_{\sigma(1)} < \dots < x_{\sigma(n)}\}|}{n!} \quad (2.2)$$

- Navarro and Rychlik (JMVA, 2007), (2.1) holds for EXC absolutely continuous joint distribution.
- Navarro, Samaniego, Balakrishnan and Bhattacharya (NRL, 2008), (2.1) holds for EXC r.v. when \mathbf{p} is given by (2.2).

- A **mixed system** of order n is a stochastic mixture of coherent systems of order n (Boland and Samaniego, 2004).
- From (2.1), in the EXC case, all the mixed systems of order n can be written as mixtures of $X_{1:n}, \dots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0, 1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\bar{F}_T(t) = \sum_{i=1}^n c_i \bar{F}_{i:n}(t).$$

- A **mixed system** of order n is a stochastic mixture of coherent systems of order n (Boland and Samaniego, 2004).
- From (2.1), in the EXC case, all the mixed systems of order n can be written as mixtures of $X_{1:n}, \dots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0, 1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\bar{F}_T(t) = \sum_{i=1}^n c_i \bar{F}_{i:n}(t).$$

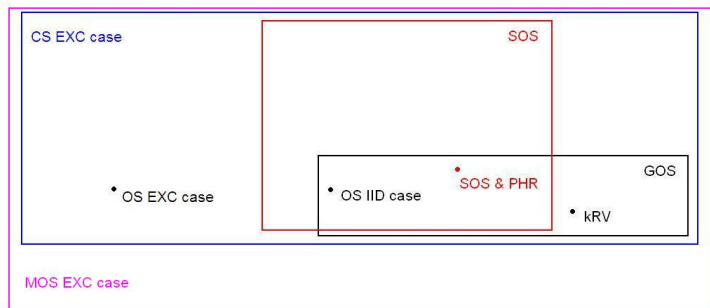
- A **mixed system** of order n is a stochastic mixture of coherent systems of order n (Boland and Samaniego, 2004).
- From (2.1), in the EXC case, all the mixed systems of order n can be written as mixtures of $X_{1:n}, \dots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0, 1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\bar{F}_T(t) = \sum_{i=1}^n c_i \bar{F}_{i:n}(t).$$

- A **mixed system** of order n is a stochastic mixture of coherent systems of order n (Boland and Samaniego, 2004).
- From (2.1), in the EXC case, all the mixed systems of order n can be written as mixtures of $X_{1:n}, \dots, X_{n:n}$.
- The vector with the coefficients in that representation is called the signature of the mixed system.
- Conversely, any probability vector in the simplex $\{\mathbf{c} \in [0, 1]^n : \sum_{i=1}^n c_i = 1\}$ determines a mixed system with reliability

$$\bar{F}_T(t) = \sum_{i=1}^n c_i \bar{F}_{i:n}(t).$$

Mixtures of Order Statistics (MOS), EXC case



Generalized mixture representations

- Navarro, Ruiz and Sandoval (CSTM, 2007), if T has EXC components, then

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t). \quad (2.3)$$

- $\mathbf{a} = (a_1, \dots, a_n)$ is the minimal signature of T .
- a_i only depends on ϕ but can be negative and so (2.3) is a generalized mixture.
- In the IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}^i(t) = q_\phi(\bar{F}(t)), \quad (2.4)$$

where $q_\phi(x) = \sum_{i=1}^n a_i x^i$ is the domination or reliability polynomial.

Generalized mixture representations

- Navarro, Ruiz and Sandoval (CSTM, 2007), if T has EXC components, then

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t). \quad (2.3)$$

- $\mathbf{a} = (a_1, \dots, a_n)$ is the minimal signature of T .
- a_i only depends on ϕ but can be negative and so (2.3) is a generalized mixture.
- In the IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}^i(t) = q_\phi(\bar{F}(t)), \quad (2.4)$$

where $q_\phi(x) = \sum_{i=1}^n a_i x^i$ is the domination or reliability polynomial.

Generalized mixture representations

- Navarro, Ruiz and Sandoval (CSTM, 2007), if T has EXC components, then

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t). \quad (2.3)$$

- $\mathbf{a} = (a_1, \dots, a_n)$ is the minimal signature of T .
- a_i only depends on ϕ but can be negative and so (2.3) is a generalized mixture.
- In the IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}^i(t) = q_\phi(\bar{F}(t)), \quad (2.4)$$

where $q_\phi(x) = \sum_{i=1}^n a_i x^i$ is the domination or reliability polynomial.

Generalized mixture representations

- Navarro, Ruiz and Sandoval (CSTM, 2007), if T has EXC components, then

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t). \quad (2.3)$$

- $\mathbf{a} = (a_1, \dots, a_n)$ is the minimal signature of T .
- a_i only depends on ϕ but can be negative and so (2.3) is a generalized mixture.
- In the IID case:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}^i(t) = q_\phi(\bar{F}(t)), \quad (2.4)$$

where $q_\phi(x) = \sum_{i=1}^n a_i x^i$ is the domination or reliability polynomial.

Generalized mixture representations

- A **path set** of T is a set such that if all the components in P work, then the system works.
- A **minimal path set** of T is a path set which does not contain other path sets.
- If P_1, \dots, P_r are the minimal path sets of T , then $T = \max_{j=1, \dots, r} X_{P_j}$, where $X_P = \min_{i \in P} X_i$.

$$\begin{aligned}\bar{F}_T(t) &= \Pr \left(\max_{j=1, \dots, r} X_{P_j} > t \right) \\ &= \Pr \left(\bigcup_{j=1, \dots, r} \{X_{P_j} > t\} \right) \\ &= \sum_{i=1}^r \bar{F}_{P_i}(t) - \sum_{i \neq j} \bar{F}_{P_i \cup P_j}(t) + \dots \pm \bar{F}_{P_1 \cup \dots \cup P_r}(t).\end{aligned}$$

where $\bar{F}_P(t) = \Pr(X_P > t)$.

Generalized mixture representations

- A **path set** of T is a set such that if all the components in P work, then the system works.
- A **minimal path set** of T is a path set which does not contain other path sets.
- If P_1, \dots, P_r are the minimal path sets of T , then $T = \max_{j=1, \dots, r} X_{P_j}$, where $X_P = \min_{i \in P} X_i$.

$$\begin{aligned}\bar{F}_T(t) &= \Pr \left(\max_{j=1, \dots, r} X_{P_j} > t \right) \\ &= \Pr \left(\bigcup_{j=1, \dots, r} \{X_{P_j} > t\} \right) \\ &= \sum_{i=1}^r \bar{F}_{P_i}(t) - \sum_{i \neq j} \bar{F}_{P_i \cup P_j}(t) + \dots \pm \bar{F}_{P_1 \cup \dots \cup P_r}(t).\end{aligned}$$

where $\bar{F}_P(t) = \Pr(X_P > t)$.

Generalized mixture representations

- A **path set** of T is a set such that if all the components in P work, then the system works.
- A **minimal path set** of T is a path set which does not contain other path sets.
- If P_1, \dots, P_r are the minimal path sets of T , then $T = \max_{j=1, \dots, r} X_{P_j}$, where $X_P = \min_{i \in P} X_i$.

$$\begin{aligned}\bar{F}_T(t) &= \Pr \left(\max_{j=1, \dots, r} X_{P_j} > t \right) \\ &= \Pr \left(\cup_{j=1, \dots, r} \{X_{P_j} > t\} \right) \\ &= \sum_{i=1}^r \bar{F}_{P_i}(t) - \sum_{i \neq j} \bar{F}_{P_i \cup P_j}(t) + \dots \pm \bar{F}_{P_1 \cup \dots \cup P_r}(t).\end{aligned}$$

where $\bar{F}_P(t) = \Pr(X_P > t)$.

Generalized mixture representations

- If K is the survival copula of (X_1, \dots, X_n) , then

$$\bar{F}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$, $i = 1, \dots, n$.

- Then

$$\bar{F}_P(t) = K(\mathbf{z}_P)$$

where $\mathbf{z}_P = (z_1, \dots, z_n)$, $z_i = \bar{F}_i(t)$ for $i \in P$ and $z_i = 1$ for $i \notin P$.

- Therefore

$$\bar{F}_T(t) = Q_{\phi, K}(\bar{F}_1(t), \dots, \bar{F}_n(t)).$$

- In the ID case

$$\bar{F}_T(t) = q_{\phi, K}(\bar{F}(t)). \quad (2.5)$$

Generalized mixture representations

- If K is the survival copula of (X_1, \dots, X_n) , then

$$\bar{F}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$, $i = 1, \dots, n$.

- Then

$$\bar{F}_P(t) = K(\mathbf{z}_P)$$

where $\mathbf{z}_P = (z_1, \dots, z_n)$, $z_i = \bar{F}_i(t)$ for $i \in P$ and $z_i = 1$ for $i \notin P$.

- Therefore

$$\bar{F}_T(t) = Q_{\phi, K}(\bar{F}_1(t), \dots, \bar{F}_n(t)).$$

- In the ID case

$$\bar{F}_T(t) = q_{\phi, K}(\bar{F}(t)). \quad (2.5)$$

Generalized mixture representations

- If K is the survival copula of (X_1, \dots, X_n) , then

$$\bar{F}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$, $i = 1, \dots, n$.

- Then

$$\bar{F}_P(t) = K(\mathbf{z}_P)$$

where $\mathbf{z}_P = (z_1, \dots, z_n)$, $z_i = \bar{F}_i(t)$ for $i \in P$ and $z_i = 1$ for $i \notin P$.

- Therefore

$$\bar{F}_T(t) = Q_{\phi, K}(\bar{F}_1(t), \dots, \bar{F}_n(t)).$$

- In the ID case

$$\bar{F}_T(t) = q_{\phi, K}(\bar{F}(t)). \quad (2.5)$$

Generalized mixture representations

- If K is the survival copula of (X_1, \dots, X_n) , then

$$\bar{F}(x_1, \dots, x_n) = K(\bar{F}_1(x_1), \dots, \bar{F}_n(x_n)),$$

where $\bar{F}_i(t) = \Pr(X_i > t)$, $i = 1, \dots, n$.

- Then

$$\bar{F}_P(t) = K(\mathbf{z}_P)$$

where $\mathbf{z}_P = (z_1, \dots, z_n)$, $z_i = \bar{F}_i(t)$ for $i \in P$ and $z_i = 1$ for $i \notin P$.

- Therefore

$$\bar{F}_T(t) = Q_{\phi, K}(\bar{F}_1(t), \dots, \bar{F}_n(t)).$$

- In the ID case

$$\bar{F}_T(t) = q_{\phi, K}(\bar{F}(t)). \quad (2.5)$$

Theorem (Navarro et al., NRL 2008)

If $T_1 = \phi_1(X_1, \dots, X_n)$ and $T_2 = \phi_2(X_1, \dots, X_n)$ have signatures $\mathbf{p} = (p_1, \dots, p_n)$ and $\mathbf{q} = (q_1, \dots, q_n)$, (X_1, \dots, X_n) is EXC, then:

(i) If $\mathbf{p} \leq_{ST} \mathbf{q}$, then $T_1 \leq_{ST} T_2$.

(ii) If $\mathbf{p} \leq_{HR} \mathbf{q}$ and $X_{1:n} \leq_{HR} \dots \leq_{HR} X_{n:n}$ holds, then $T_1 \leq_{HR} T_2$.

(iii) If $\mathbf{p} \leq_{HR} \mathbf{q}$ and $X_{1:n} \leq_{MRL} \dots \leq_{MRL} X_{n:n}$ holds, then $T_1 \leq_{MRL} T_2$.

(iv) If $\mathbf{p} \leq_{LR} \mathbf{q}$ and $X_{1:n} \leq_{LR} \dots \leq_{LR} X_{n:n}$ holds, then $T_1 \leq_{LR} T_2$.

Aging classes results for coherent systems

- If X_1, \dots, X_n are IID

$$X_1 \text{ NBU} \Rightarrow T \text{ NBU},$$

but

$$X_1 \text{ IHR} \not\Rightarrow T \text{ IHR}$$

and

$$X_1 \text{ ILR} \not\Rightarrow T \text{ ILR}.$$

Distorted Distributions (DD)

- The distorted distributions are a way to model distortion risk measures developed from research on premium principles, see Wang (1996, ASTIN Bull).
- The *distorted distribution* associated to F and to an increasing right continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (3.1)$$

- Some authors assume that q is continuous and strictly increasing. Then F and F_q have the same support.
- For the reliability functions we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (3.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*; see Hürlimann (2004, N Am Actuarial J).

- \bar{q} is also increasing in $(0, 1)$ from $\bar{q}(0) = 0$ to $\bar{q}(1) = 1$.

Distorted Distributions (DD)

- The distorted distributions are a way to model distortion risk measures developed from research on premium principles, see Wang (1996, ASTIN Bull).
- The *distorted distribution* associated to F and to an increasing right continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (3.1)$$

- Some authors assume that q is continuous and strictly increasing. Then F and F_q have the same support.
- For the reliability functions we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (3.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*; see Hürlimann (2004, N Am Actuarial J).

- \bar{q} is also increasing in $(0, 1)$ from $\bar{q}(0) = 0$ to $\bar{q}(1) = 1$.

Distorted Distributions (DD)

- The distorted distributions are a way to model distortion risk measures developed from research on premium principles, see Wang (1996, ASTIN Bull).
- The *distorted distribution* associated to F and to an increasing right continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (3.1)$$

- Some authors assume that q is continuous and strictly increasing. Then F and F_q have the same support.
- For the reliability functions we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (3.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*; see Hürlimann (2004, N Am Actuarial J).

- \bar{q} is also increasing in $(0, 1)$ from $\bar{q}(0) = 0$ to $\bar{q}(1) = 1$.

Distorted Distributions (DD)

- The distorted distributions are a way to model distortion risk measures developed from research on premium principles, see Wang (1996, ASTIN Bull).
- The *distorted distribution* associated to F and to an increasing right continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (3.1)$$

- Some authors assume that q is continuous and strictly increasing. Then F and F_q have the same support.
- For the reliability functions we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (3.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*; see Hürlimann (2004, N Am Actuarial J).

- \bar{q} is also increasing in $(0, 1)$ from $\bar{q}(0) = 0$ to $\bar{q}(1) = 1$.

Distorted Distributions (DD)

- The distorted distributions are a way to model distortion risk measures developed from research on premium principles, see Wang (1996, ASTIN Bull).
- The *distorted distribution* associated to F and to an increasing right continuous *distortion function* $q : [0, 1] \rightarrow [0, 1]$ such that $q(0) = 0$ and $q(1) = 1$, is

$$F_q(t) = q(F(t)). \quad (3.1)$$

- Some authors assume that q is continuous and strictly increasing. Then F and F_q have the same support.
- For the reliability functions we have

$$\bar{F}_q(t) = \bar{q}(\bar{F}(t)), \quad (3.2)$$

where $\bar{q}(u) = 1 - q(1 - u)$ is the *dual distortion function*; see Hürlimann (2004, N Am Actuarial J).

- \bar{q} is also increasing in $(0, 1)$ from $\bar{q}(0) = 0$ to $\bar{q}(1) = 1$.

Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

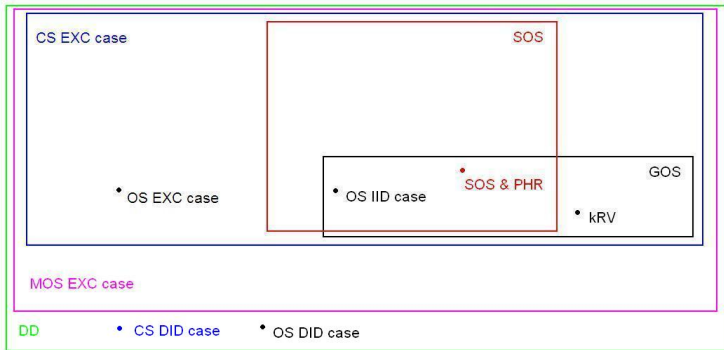
Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

Particular cases of Distorted Distributions (DD)

- The OS in the IID case are DD (1.1).
- The GOS (Records, k-Records, etc.) are DD (1.2).
- The SOS in the PHR case are DD.
- The CS (OS) in the ID case (includes the EXC case) are DD (2.5).
- The SOS in the general case are DD but q and F are quite complicate.
- PHR and RPHR are DD.

Distorted Distributions (DD)



Ordering results for distorted distributions

- Conditions to get ordering results for DD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (to appear in ASMBI, DOI: 10.1002/asmb.1917).
- For example:

Theorem

Let $F_1 = q_1(F)$ and let $F_2 = q_2(F)$. Then we have the following properties:

- (i) $F_1 \leq_{ST} F_2$ (\geq_{ST}) for all F if and only if $q_1(u)/q_2(u) \geq 1$ (\leq) in $(0, 1)$.*
- (ii) $F_1 \leq_{HR} F_2$ (\geq_{HR}) for all F if and only if $\bar{q}_1(u)/\bar{q}_2(u)$ increases (decreases) in $(0, 1)$.*
- (iii) $F_1 \leq_{LR} F_2$ (\geq_{LR}) for all F if and only if $\bar{q}_2(\bar{q}_1^{-1}(u))$ is concave (convex) in $(0, 1)$.*

Ordering results for distorted distributions

- Conditions to get ordering results for DD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (to appear in ASMBI, DOI: 10.1002/asmb.1917).
- For example:

Theorem

Let $F_1 = q_1(F)$ and let $F_2 = q_2(F)$. Then we have the following properties:

- (i) $F_1 \leq_{ST} F_2$ (\geq_{ST}) for all F if and only if $q_1(u)/q_2(u) \geq 1$ (\leq) in $(0, 1)$.*
- (ii) $F_1 \leq_{HR} F_2$ (\geq_{HR}) for all F if and only if $\bar{q}_1(u)/\bar{q}_2(u)$ increases (decreases) in $(0, 1)$.*
- (iii) $F_1 \leq_{LR} F_2$ (\geq_{LR}) for all F if and only if $\bar{q}_2(\bar{q}_1^{-1}(u))$ is concave (convex) in $(0, 1)$.*

Ordering results for distorted distributions

- Conditions to get preservation of aging classes for DD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (submitted).
- For example:

Theorem

Let $F_q = q(F)$ and let $\alpha_q(u) = \frac{uq'(1-u)}{1-q(1-u)}$. Then:

- (i) If α_q is decreasing in $(0, 1)$ and F is IHR, then F_q is IHR.
- (ii) If α_q is increasing in $(0, 1)$ and F is DHR, then F_q is DHR.
- (iii) If α_q is increasing in $(0, 1)$ and F_q is IHR, then F is IHR.
- (iv) If α_q is decreasing in $(0, 1)$ and F_q is DFR, then F is DFR.

Ordering results for distorted distributions

- Conditions to get preservation of aging classes for DD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (submitted).
- For example:

Theorem

Let $F_q = q(F)$ and let $\alpha_q(u) = \frac{uq'(1-u)}{1-q(1-u)}$. Then:

- (i) If α_q is decreasing in $(0, 1)$ and F is IHR, then F_q is IHR.
- (ii) If α_q is increasing in $(0, 1)$ and F is DHR, then F_q is DHR.
- (iii) If α_q is increasing in $(0, 1)$ and F_q is IHR, then F is IHR.
- (iv) If α_q is decreasing in $(0, 1)$ and F_q is DFR, then F is DFR.

Inference results for distorted distributions

- Inference results for distorted distributions (i.e. to estimate characteristics of F from a *distorted* sample from F_q) were obtained in:
 - Balakrishnan, Ng and Navarro (2011, IEEE Trans. Reliab. 60, 426-440).
 - Balakrishnan, Ng and Navarro (2011, J. Nonparametric Stat. 23, 741-752).
 - Ng, Navarro and Balakrishnan (2012, Metrika 75, 367-388).

Inference results for distorted distributions

- Inference results for distorted distributions (i.e. to estimate characteristics of F from a *distorted* sample from F_q) were obtained in:
- Balakrishnan, Ng and Navarro (2011, IEEE Trans. Reliab. 60, 426-440).
- Balakrishnan, Ng and Navarro (2011, J. Nonparametric Stat. 23, 741-752).
- Ng, Navarro and Balakrishnan (2012, Metrika 75, 367-388).

Inference results for distorted distributions

- Inference results for distorted distributions (i.e. to estimate characteristics of F from a *distorted* sample from F_q) were obtained in:
- Balakrishnan, Ng and Navarro (2011, IEEE Trans. Reliab. 60, 426-440).
- Balakrishnan, Ng and Navarro (2011, J. Nonparametric Stat. 23, 741-752).
- Ng, Navarro and Balakrishnan (2012, Metrika 75, 367-388).

Inference results for distorted distributions

- Inference results for distorted distributions (i.e. to estimate characteristics of F from a *distorted* sample from F_q) were obtained in:
- Balakrishnan, Ng and Navarro (2011, IEEE Trans. Reliab. 60, 426-440).
- Balakrishnan, Ng and Navarro (2011, J. Nonparametric Stat. 23, 741-752).
- Ng, Navarro and Balakrishnan (2012, Metrika 75, 367-388).

Definition Generalized Distorted Distributions (GDD)

- The *generalized distorted distribution* associated to F_1, \dots, F_n and to an increasing right continuous *generalized distortion function* $Q : [0, 1]^n \rightarrow [0, 1]$ such that $Q(0, \dots, 0) = 0$ and $Q(1, \dots, 1) = 1$, is

$$F_Q(t) = Q(F_1(t), \dots, F_n(t)), \quad (3.3)$$

see Navarro, del Aguila, Sordo and Suarez-Llorens (submitted).

- For the reliability functions we have

$$\bar{F}_Q(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t)), \quad (3.4)$$

where $\bar{Q}(u_1, \dots, u_n) = 1 - Q(1 - u_1, \dots, 1 - u_n)$ is the *dual generalized distortion function*.

- \bar{Q} is also increasing in $(0, 1)^n$ from $\bar{Q}(0, \dots, 0) = 0$ to $\bar{Q}(1, \dots, 1) = 1$.

Definition Generalized Distorted Distributions (GDD)

- The *generalized distorted distribution* associated to F_1, \dots, F_n and to an increasing right continuous *generalized distortion function* $Q : [0, 1]^n \rightarrow [0, 1]$ such that $Q(0, \dots, 0) = 0$ and $Q(1, \dots, 1) = 1$, is

$$F_Q(t) = Q(F_1(t), \dots, F_n(t)), \quad (3.3)$$

see Navarro, del Aguila, Sordo and Suarez-Llorens (submitted).

- For the reliability functions we have

$$\bar{F}_Q(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t)), \quad (3.4)$$

where $\bar{Q}(u_1, \dots, u_n) = 1 - Q(1 - u_1, \dots, 1 - u_n)$ is the *dual generalized distortion function*.

- \bar{Q} is also increasing in $(0, 1)^n$ from $\bar{Q}(0, \dots, 0) = 0$ to $\bar{Q}(1, \dots, 1) = 1$.

Definition Generalized Distorted Distributions (GDD)

- The *generalized distorted distribution* associated to F_1, \dots, F_n and to an increasing right continuous *generalized distortion function* $Q : [0, 1]^n \rightarrow [0, 1]$ such that $Q(0, \dots, 0) = 0$ and $Q(1, \dots, 1) = 1$, is

$$F_Q(t) = Q(F_1(t), \dots, F_n(t)), \quad (3.3)$$

see Navarro, del Aguila, Sordo and Suarez-Llorens (submitted).

- For the reliability functions we have

$$\bar{F}_Q(t) = \bar{Q}(\bar{F}_1(t), \dots, \bar{F}_n(t)), \quad (3.4)$$

where $\bar{Q}(u_1, \dots, u_n) = 1 - Q(1 - u_1, \dots, 1 - u_n)$ is the *dual generalized distortion function*.

- \bar{Q} is also increasing in $(0, 1)^n$ from $\bar{Q}(0, \dots, 0) = 0$ to $\bar{Q}(1, \dots, 1) = 1$.

Particular case of Generalized Distorted Distributions

- The OS in the general case (includes the INID case) are GDD.
- The CS in the general case (includes the INID case) are GDD.
- Ordering and aging classes properties for GDD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (submitted), see also Marshall, Olkin and Arnold (2011, Springer).

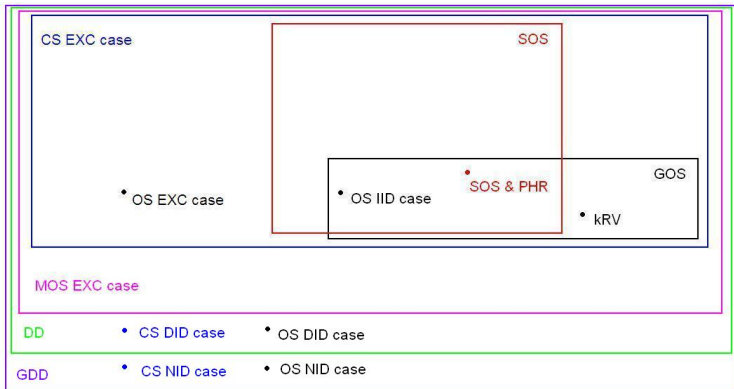
Particular case of Generalized Distorted Distributions

- The OS in the general case (includes the INID case) are GDD.
- The CS in the general case (includes the INID case) are GDD.
- Ordering and aging classes properties for GDD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (submitted), see also Marshall, Olkin and Arnold (2011, Springer).

Particular case of Generalized Distorted Distributions

- The OS in the general case (includes the INID case) are GDD.
- The CS in the general case (includes the INID case) are GDD.
- Ordering and aging classes properties for GDD were given in Navarro, del Aguila, Sordo and Suarez-Llorens (submitted), see also Marshall, Olkin and Arnold (2011, Springer).

Distorted Distributions (DD)



Example

- $X_{2,3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\bar{F}_T(t) = K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2,3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2,3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- $X_{2:3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) \\ &\quad - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2:3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2:3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- $X_{2,3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\bar{F}_T(t) = K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2,3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2,3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- $X_{2:3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) \\ &\quad - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2:3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2:3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- $X_{2:3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) \\ &\quad - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2:3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2:3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- $X_{2:3}$ has the path sets $P_1 = \{1, 2\}$, $P_2 = \{1, 3\}$, and $P_3 = \{2, 3\}$.
- Then

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- Therefore, in the ID case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}(t), \bar{F}(t), 1) + K(\bar{F}(t), 1, \bar{F}(t)) + K(1, \bar{F}(t), \bar{F}(t)) \\ &\quad - 2K(\bar{F}(t), \bar{F}(t), \bar{F}(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = q(\bar{F}(t))$ where $q(u) = K(u, u, 1) + K(u, 1, u) + K(u, u, 1) - 2K(u, u, u)$.
- In the EXC case $q(u) = q_{2:3}^{EXC}(u) = 3K(u, u, 1) - 2K(u, u, u)$.
- In the IID case $q(u) = q_{2:3}^{IID}(u) = 3u^2 - 2u^3$.

Example

- As

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- In the general case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}_1(t), \bar{F}_2(t), 1) + K(\bar{F}_1(t), 1, \bar{F}_3(t)) \\ &\quad + K(1, \bar{F}_2(t), \bar{F}_3(t)) - 2K(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = Q(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t))$ where

$$\begin{aligned}Q(u_1, u_2, u_3) &= K(u_1, u_2, 1) + K(u_1, 1, u_3) + K(u_1, u_2, 1) \\ &\quad - 2K(u_1, u_2, u_3).\end{aligned}$$

- In the I case:

$$Q(u_1, u_2, u_3) = u_1 u_2 + u_1 u_3 + u_1 u_2 - 2u_1 u_2 u_3.$$

Example

- As

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- In the general case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}_1(t), \bar{F}_2(t), 1) + K(\bar{F}_1(t), 1, \bar{F}_3(t)) \\ &\quad + K(1, \bar{F}_2(t), \bar{F}_3(t)) - 2K(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = Q(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t))$ where

$$\begin{aligned}Q(u_1, u_2, u_3) &= K(u_1, u_2, 1) + K(u_1, 1, u_3) + K(u_1, u_2, 1) \\ &\quad - 2K(u_1, u_2, u_3).\end{aligned}$$

- In the I case:

$$Q(u_1, u_2, u_3) = u_1 u_2 + u_1 u_3 + u_1 u_2 - 2u_1 u_2 u_3.$$

Example

- As

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- In the general case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}_1(t), \bar{F}_2(t), 1) + K(\bar{F}_1(t), 1, \bar{F}_3(t)) \\ &\quad + K(1, \bar{F}_2(t), \bar{F}_3(t)) - 2K(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = Q(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t))$ where

$$\begin{aligned}Q(u_1, u_2, u_3) &= K(u_1, u_2, 1) + K(u_1, 1, u_3) + K(u_1, u_2, 1) \\ &\quad - 2K(u_1, u_2, u_3).\end{aligned}$$

- In the I case:

$$Q(u_1, u_2, u_3) = u_1 u_2 + u_1 u_3 + u_1 u_2 - 2u_1 u_2 u_3.$$

Example

- As

$$\bar{F}_T(t) = \bar{F}_{\{1,2\}}(t) + \bar{F}_{\{1,3\}}(t) + \bar{F}_{\{2,3\}}(t) - 2\bar{F}_{\{1,2,3\}}(t).$$

- In the general case, we have

$$\begin{aligned}\bar{F}_T(t) &= K(\bar{F}_1(t), \bar{F}_2(t), 1) + K(\bar{F}_1(t), 1, \bar{F}_3(t)) \\ &\quad + K(1, \bar{F}_2(t), \bar{F}_3(t)) - 2K(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t)).\end{aligned}$$

- That is $\bar{F}_T(t) = Q(\bar{F}_1(t), \bar{F}_2(t), \bar{F}_3(t))$ where

$$\begin{aligned}Q(u_1, u_2, u_3) &= K(u_1, u_2, 1) + K(u_1, 1, u_3) + K(u_1, u_2, 1) \\ &\quad - 2K(u_1, u_2, u_3).\end{aligned}$$

- In the I case:

$$Q(u_1, u_2, u_3) = u_1 u_2 + u_1 u_3 + u_1 u_2 - 2u_1 u_2 u_3.$$

Connectivity problems in Networks

- A **graph** (or network) is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are 2-element subsets of V .
- A **directed graph** is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are elements of $V \times V$.
- Let us assume that in a graph (directed graph) the nodes cannot fail but the edges can fail. Let X_1, \dots, X_n be the edges lifetimes.
- Suppose that we want to study a given connectivity problem (e.g. the connection of all the nodes). Let T_N be the lifetime of the network for this connectivity problem. Then

$$T_N = \phi(X_1, \dots, X_n)$$

for a coherent system ϕ .

Connectivity problems in Networks

- A **graph** (or network) is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are 2-element subsets of V .
- A **directed graph** is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are elements of $V \times V$.
- Let us assume that in a graph (directed graph) the nodes cannot fail but the edges can fail. Let X_1, \dots, X_n be the edges lifetimes.
- Suppose that we want to study a given connectivity problem (e.g. the connection of all the nodes). Let T_N be the lifetime of the network for this connectivity problem. Then

$$T_N = \phi(X_1, \dots, X_n)$$

for a coherent system ϕ .

Connectivity problems in Networks

- A **graph** (or network) is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are 2-element subsets of V .
- A **directed graph** is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are elements of $V \times V$.
- Let us assume that in a graph (directed graph) the nodes cannot fail but the edges can fail. Let X_1, \dots, X_n be the edges lifetimes.
- Suppose that we want to study a given connectivity problem (e.g. the connection of all the nodes). Let T_N be the lifetime of the network for this connectivity problem. Then

$$T_N = \phi(X_1, \dots, X_n)$$

for a coherent system ϕ .

Connectivity problems in Networks

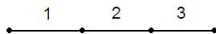
- A **graph** (or network) is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are 2-element subsets of V .
- A **directed graph** is an ordered pair $G = (V, E)$ comprising a set V of nodes together with a set E of edges, which are elements of $V \times V$.
- Let us assume that in a graph (directed graph) the nodes cannot fail but the edges can fail. Let X_1, \dots, X_n be the edges lifetimes.
- Suppose that we want to study a given connectivity problem (e.g. the connection of all the nodes). Let T_N be the lifetime of the network for this connectivity problem. Then

$$T_N = \phi(X_1, \dots, X_n)$$

for a coherent system ϕ .

All nodes connection problem in a network

Network



Coherent system

Path sets:

?

All nodes connection problem in a network

Network



Coherent system

Path sets:

$\{1,2,3\}$

?

All nodes connection problem in a network

Network



Coherent system

Path sets:

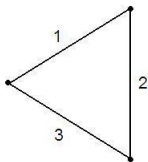
$\{1,2,3\}$

Series system

$X_{1,3}$

All nodes connection problem in a network

Network



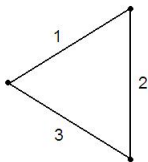
Coherent system

Path sets:

?

All nodes connection problem in a network

Network



Coherent system

Path sets:

{1,2}

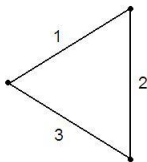
{1,3}

{2,3}

?

All nodes connection problem in a network

Network



Path sets:

{1,2}

{1,3}

{2,3}

Coherent system

2-out-of-3

$X_{2,3}$

All nodes connection problem in a network

Network

?

Coherent system

Path sets:

{1}

{2}

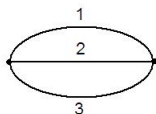
{3}

Parallel system

$X_{3:3}$

All nodes connection problem in a network

Network



Coherent system

Path sets:

{1}

{2}

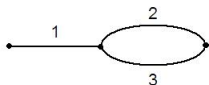
{3}

Parallel system

$X_{3:3}$

All nodes connection problem in a network

Network



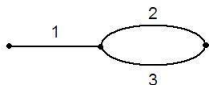
Coherent system

Path sets:

?

All nodes connection problem in a network

Network



Coherent system

Path sets:

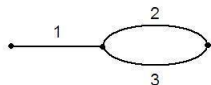
{1,2}

{1,3}

?

All nodes connection problem in a network

Network



Path sets:

{1,2}

{1,3}

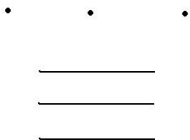
Coherent system

$$\min(X_1, \max(X_2, X_3))$$

All nodes connection problem in a network

What is the best way to connect three nodes with three edges?

Network

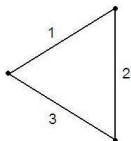


Coherent system

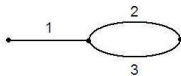
All nodes connection problem in a network

What is the best way to connect three nodes with three edges?

Network



Coherent system



2-out-of-3

$$X_{2,3} \geq \min(X_1, \max(X_2, X_3))$$

- For the complete references, please visit my personal web page:

<https://webs.um.es/jorgenav/>

- Thank you for your attention!!

- For the complete references, please visit my personal web page:

<https://webs.um.es/jorgenav/>

- Thank you for your attention!!